

§ 6.2 - Diagonalization

In §6.1, we motivated the study of eigenvectors by looking at the matrix

$$A = \begin{bmatrix} 2 & 0 \\ 0 & 5 \end{bmatrix}.$$

This diagonal matrix was very easy to work with:

$$A^2 = \begin{bmatrix} 2^2 & 0 \\ 0 & 5^2 \end{bmatrix}, \quad A^3 = \begin{bmatrix} 2^3 & 0 \\ 0 & 5^3 \end{bmatrix}, \quad \dots, \quad A^{100} = \begin{bmatrix} 2^{100} & 0 \\ 0 & 5^{100} \end{bmatrix}$$

Most other matrices aren't so nice... BUT we can

sometimes convert these bad matrices into nice

diagonal ones through a process called diagonalization!

Let's see how this process works through the following example:

Ex: Let $A = \begin{bmatrix} 2 & 1 \\ 1 & 2 \end{bmatrix}$.

1. Find the eigenvalues of A and a basis for each eigenspace.

$P_A(\lambda) = (\lambda-1)(\lambda-3)$, so eigenvalues are 1, 3.

For $\lambda=1$, a basis is $\left\{ \begin{bmatrix} 1 \\ -1 \end{bmatrix} \right\}$

For $\lambda=3$, a basis is $\left\{ \begin{bmatrix} 1 \\ 1 \end{bmatrix} \right\}$

2. Put the eigenvalues in a diagonal matrix D . (order doesn't matter, but repeated eigenvalues should be grouped together)

In our example, take $D = \begin{bmatrix} 1 & 0 \\ 0 & 3 \end{bmatrix}$.

3. Using the same order as in 2., put the basis vectors for each eigenspace as

columns of a matrix P .

In our example, $P = \begin{bmatrix} 1 & 1 \\ -1 & 1 \end{bmatrix}$

↑ The basis for the $\lambda=1$ eigenspace comes first because 1 came first in D !

4. Find P^{-1} . We get $P^{-1}AP = D$ (diagonal!)

$$\left[\begin{array}{cc|cc} 1 & 1 & 1 & 0 \\ -1 & 1 & 0 & 1 \end{array} \right] \xrightarrow{R_2+R_1} \left[\begin{array}{cc|cc} 1 & 1 & 1 & 0 \\ 0 & 2 & 1 & 1 \end{array} \right] \xrightarrow{R_2 \cdot \frac{1}{2}} \left[\begin{array}{cc|cc} 1 & 1 & 1 & 0 \\ 0 & 1 & \frac{1}{2} & \frac{1}{2} \end{array} \right] \xrightarrow{R_1 - R_2} \sim$$

$$\left[\begin{array}{cc|cc} 1 & 0 & \frac{1}{2} & -\frac{1}{2} \\ 0 & 1 & \frac{1}{2} & \frac{1}{2} \end{array} \right] \quad \therefore \underline{P^{-1} = \frac{1}{2} \begin{bmatrix} 1 & -1 \\ 1 & 1 \end{bmatrix}}.$$

We get

$$\underline{\frac{1}{2} \begin{bmatrix} 1 & -1 \\ 1 & 1 \end{bmatrix} \begin{bmatrix} 2 & 1 \\ 1 & 2 \end{bmatrix} \begin{bmatrix} 1 & 1 \\ -1 & 1 \end{bmatrix} = \begin{bmatrix} 1 & 0 \\ 0 & 3 \end{bmatrix}}$$

$P^{-1} \quad A \quad P \quad = \quad D.$

Ex: Let's try to diagonalize

$$A = \begin{bmatrix} 2 & 2 & 0 \\ -1 & -1 & 0 \\ 1 & 2 & 1 \end{bmatrix}$$

1. $P_A(\lambda) = \det(A - \lambda I)$

$$= \det \left(\begin{bmatrix} 2-\lambda & 2 & 0 \\ -1 & -1-\lambda & 0 \\ 1 & 2 & 1-\lambda \end{bmatrix} \right)$$

$$= (1-\lambda) \begin{vmatrix} 2-\lambda & 2 \\ -1 & -1-\lambda \end{vmatrix}$$

$$= (1-\lambda) \left((2-\lambda)(-1-\lambda) + 2 \right)$$

$$= (1-\lambda) \left(-2 - 2\lambda + \lambda + \lambda^2 + 2 \right)$$

$$= (1-\lambda)(\lambda^2 - \lambda) = -\lambda(1-\lambda)^2$$

The eigenvalues are $0, 1, 1$.

Now to find the eigenvectors!

$$\underline{\lambda=0}: A - 0I = \begin{bmatrix} 2 & 2 & 0 \\ -1 & -1 & 0 \\ 1 & 2 & 1 \end{bmatrix} \xrightarrow{R_1: \frac{1}{2}} \begin{bmatrix} 1 & 1 & 0 \\ -1 & -1 & 0 \\ 1 & 2 & 1 \end{bmatrix} \sim \begin{matrix} \sim \\ R_2+R_1 \\ R_3-R_1 \end{matrix}$$

$$\begin{bmatrix} 1 & 1 & 0 \\ 0 & 0 & 0 \\ 0 & 1 & 1 \end{bmatrix} \xrightarrow{R_2 \uparrow R_3} \begin{bmatrix} 1 & 1 & 0 \\ 0 & 1 & 1 \\ 0 & 0 & 0 \end{bmatrix} \xrightarrow{R_1 - R_2} \begin{bmatrix} 1 & 0 & -1 \\ 0 & 1 & 1 \\ 0 & 0 & 0 \end{bmatrix} \text{ (RREF)}$$

We get $x_3 = t$, $x_2 = -t$, $x_1 = t$

The solution is $\vec{x} = t \begin{bmatrix} 1 \\ -1 \\ 1 \end{bmatrix}$, $t \in \mathbb{R}$, so a

basis is $\left\{ \begin{bmatrix} 1 \\ -1 \\ 1 \end{bmatrix} \right\}$

$$\underline{\lambda=1}: A - 1I = \begin{bmatrix} 1 & 2 & 0 \\ -1 & -2 & 0 \\ 1 & 2 & 0 \end{bmatrix} \sim \begin{bmatrix} 1 & 2 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} \xrightarrow{R_2+R_1, R_3-R_1} \text{ (RREF)}$$

We get $x_3 = t$, $x_2 = s$, $x_1 = -2s$

The solution is $\vec{x} = s \begin{bmatrix} -2 \\ 1 \\ 0 \end{bmatrix} + t \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}$, $s, t \in \mathbb{R}$.

So a basis is $\left\{ \begin{bmatrix} -2 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix} \right\}$.

2. We'll take $D = \begin{bmatrix} 0 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$

3. We'll take $P = \begin{bmatrix} 1 & -2 & 0 \\ -1 & 1 & 0 \\ 1 & 0 & 1 \end{bmatrix}$

4. We now find P^{-1} :

$$\left[\begin{array}{ccc|ccc} 1 & -2 & 0 & 1 & 0 & 0 \\ -1 & 1 & 0 & 0 & 1 & 0 \\ 1 & 0 & 1 & 0 & 0 & 1 \end{array} \right] \begin{array}{l} \sim \\ R_2+R_1 \\ R_3-R_1 \end{array} \sim \left[\begin{array}{ccc|ccc} 1 & -2 & 0 & 1 & 0 & 0 \\ 0 & -1 & 0 & 1 & 1 & 0 \\ 0 & 2 & 1 & -1 & 0 & 1 \end{array} \right] \begin{array}{l} \sim \\ R_2(-1) \end{array}$$

$$\left[\begin{array}{ccc|ccc} 1 & -2 & 0 & 1 & 0 & 0 \\ 0 & 1 & 0 & -1 & -1 & 0 \\ 0 & 0 & 1 & 1 & 2 & 1 \end{array} \right] \begin{array}{l} R_1+2R_2 \\ \sim \end{array} \left[\begin{array}{ccc|ccc} 1 & 0 & 0 & -1 & -2 & 0 \\ 0 & 1 & 0 & -1 & -1 & 0 \\ 0 & 0 & 1 & 1 & 2 & 1 \end{array} \right]$$

So $P^{-1} = \begin{bmatrix} -1 & -2 & 0 \\ -1 & -1 & 0 \\ 1 & 2 & 1 \end{bmatrix}$. We get $P^{-1}AP = D$,

i.e., $\begin{bmatrix} -1 & -2 & 0 \\ -1 & -1 & 0 \\ 1 & 2 & 0 \end{bmatrix} \begin{bmatrix} 2 & 2 & 0 \\ -1 & -1 & 0 \\ 1 & 2 & 1 \end{bmatrix} \begin{bmatrix} 1 & -2 & 0 \\ -1 & 1 & 0 \\ 1 & 0 & 1 \end{bmatrix} = \begin{bmatrix} 0 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$

Ex: Let's try to diagonalize $A = \begin{bmatrix} 3 & 1 \\ 0 & 3 \end{bmatrix}$.

1. $P_A(\lambda) = \det(A - \lambda I) = \begin{vmatrix} 3 - \lambda & 1 \\ 0 & 3 - \lambda \end{vmatrix} = (3 - \lambda)^2$

The eigenvalues are $\lambda = 3, 3$.

Let's find the eigenvectors!

$$A - 3I = \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix} \text{ (RREF)} \quad \begin{array}{l} x_1 = t \\ x_2 = 0 \end{array}$$

The solution is $\vec{x} = t \begin{bmatrix} 1 \\ 0 \end{bmatrix}$, $t \in \mathbb{R}$, so a

basis is $\left\{ \begin{bmatrix} 1 \\ 0 \end{bmatrix} \right\}$.

2. We have $D = \begin{bmatrix} 3 & 0 \\ 0 & 3 \end{bmatrix}$

3. We have $P = \begin{bmatrix} 1 \\ 0 \end{bmatrix}$

... WAT?

How are we supposed to invert this??

We simply didn't get enough eigenvectors from $\lambda = 3$ to make a 2×2 matrix P !

So... we can't diagonalize A ! :(

Let's investigate this phenomenon further.

Definition: Let A be an $n \times n$ matrix with eigenvalue λ .

(1) The **algebraic multiplicity** of λ is the number of times it occurs as a root in the characteristic polynomial of A .

(i.e., the # of times λ is an eigenvalue of A)

(2) The **geometric multiplicity** of λ is the number of basis vectors we can find in its

corresponding eigenspace.

Ex: With $A = \begin{bmatrix} 2 & 2 & 0 \\ -1 & -1 & 0 \\ 1 & 2 & 1 \end{bmatrix}$ we have eigenvalues $0, 1, 1$.

So $\lambda = 0$ has algebraic multiplicity 1

$\lambda = 1$ has algebraic multiplicity 2

A basis for the $\lambda = 0$ eigenspace was $\left\{ \begin{bmatrix} 1 \\ -1 \\ 1 \end{bmatrix} \right\}$

$\Rightarrow \lambda = 0$ has geometric multiplicity 1

A basis for the $\lambda = 1$ eigenspace was $\left\{ \begin{bmatrix} -2 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix} \right\}$

$\Rightarrow \lambda = 1$ has geometric multiplicity 2

Ex: From the last example, the eigenvalues of

$A = \begin{bmatrix} 3 & 1 \\ 0 & 3 \end{bmatrix}$ are 3, 3, so $\lambda = 3$ has algebraic multiplicity 2. Since $\left\{ \begin{bmatrix} 1 \\ 0 \end{bmatrix} \right\}$ is a basis for its eigenspace, $\lambda = 3$ has geometric multiplicity 1.

Note: With $A = \begin{bmatrix} 2 & 2 & 0 \\ -1 & -1 & 0 \\ 1 & 2 & 1 \end{bmatrix}$, each eigenvalue had its alg. mult. equal to its geo. mult. This matrix was diagonalizable (we could write $P^{-1}AP = D$)

With $A = \begin{bmatrix} 3 & 1 \\ 0 & 3 \end{bmatrix}$, however, the alg. mult. of $\lambda = 3$ was not equal to its geo. mult. This matrix was not diagonalizable (we can't write $P^{-1}AP = D$)

Theorem: Let A be an $n \times n$ matrix. Then A is diagonalizable (we can write $P^{-1}AP = D$) if and only if for each eigenvalue λ

$$\text{alg. mult of } \lambda = \text{geo. mult of } \lambda.$$

Application: Matrix Powers



This diagonalization stuff is pretty cool!
But what can we do with it??

One important application is taking high powers of matrices!

Suppose A is a diagonalizable $n \times n$ matrix, so we can write $P^{-1}AP = D$ (D diagonal)

Suppose we want to know A^{1000} .

$$\begin{aligned} \text{We have } P^{-1}AP = D &\Rightarrow \cancel{P(P^{-1}AP)P^{-1}} = PDP^{-1} \\ &\Rightarrow A = PDP^{-1}. \end{aligned}$$

$$\begin{aligned} \text{Then } A^{1000} &= (PDP^{-1})^{1000} \\ &= \underbrace{PDP^{-1}}_{=I} \underbrace{(PDP^{-1})}_{=I} \cancel{(PDP^{-1})} \cdots \cancel{(PDP^{-1})} \\ &= PD^{1000}P^{-1} \end{aligned}$$

In general: $A^k = PD^kP^{-1}$ for $k=1, 2, 3, \dots$

Ex: Consider the matrix $A = \begin{bmatrix} 17 & -15 \\ 20 & -18 \end{bmatrix}$

from §6.1. Compute A^{100} .

Solution: By above, we should first diagonalize A .

$$\begin{aligned}
 1. \quad P_A(\lambda) &= \begin{vmatrix} 17-\lambda & -15 \\ 20 & -18-\lambda \end{vmatrix} \\
 &= (17-\lambda)(-18-\lambda) + 300 \\
 &= \lambda^2 + \lambda - 306 + 300 \\
 &= \lambda^2 + \lambda - 6 \\
 &= (\lambda-2)(\lambda+3) \quad \Rightarrow \text{Eigenvalues are } 2, -3.
 \end{aligned}$$

For $\lambda = 2$: $A - 2I = \begin{bmatrix} 15 & -15 \\ 20 & -20 \end{bmatrix} \sim \begin{bmatrix} 1 & -1 \\ 0 & 0 \end{bmatrix}$ (RREF)

$$\begin{aligned}
 x_2 &= t \\
 x_1 &= t
 \end{aligned}
 \Rightarrow \text{Solution is } \vec{x} = t \begin{bmatrix} 1 \\ 1 \end{bmatrix}, t \in \mathbb{R}$$

A basis is $\left\{ \begin{bmatrix} 1 \\ 1 \end{bmatrix} \right\}$

For $\lambda = 3$: $A - (-3)I = \begin{bmatrix} 20 & -15 \\ 20 & -15 \end{bmatrix} \sim \begin{bmatrix} 1 & -3/4 \\ 0 & 0 \end{bmatrix}$ (RREF)

$$\begin{aligned}
 x_2 &= t \\
 x_1 &= 3/4 t
 \end{aligned}
 \Rightarrow \text{The solution is } \vec{x} = t \begin{bmatrix} 3/4 \\ 1 \end{bmatrix}, t \in \mathbb{R}$$

A basis is $\left\{ \begin{bmatrix} 3/4 \\ 1 \end{bmatrix} \right\}$

2. We take $D = \begin{bmatrix} 2 & 0 \\ 0 & -3 \end{bmatrix}$

3. We take $P = \begin{bmatrix} 1 & 3/4 \\ 1 & 1 \end{bmatrix}$

4. Let's compute P^{-1} :

$$\left[\begin{array}{cc|cc} 1 & 3/4 & 1 & 0 \\ 1 & 1 & 0 & 1 \end{array} \right] \xrightarrow{R_2 - R_1} \left[\begin{array}{cc|cc} 1 & 3/4 & 1 & 0 \\ 0 & 1/4 & -1 & 1 \end{array} \right] \xrightarrow{R_2 \cdot 4}$$

$$\left[\begin{array}{cc|cc} 1 & 3/4 & 1 & 0 \\ 0 & 1 & -4 & 4 \end{array} \right] \xrightarrow{R_1 - 3/4 R_2} \left[\begin{array}{cc|cc} 1 & 0 & 4 & -3 \\ 0 & 1 & -4 & 4 \end{array} \right]$$

So $P^{-1} = \begin{bmatrix} 4 & -3 \\ -4 & 4 \end{bmatrix}$ and we get $P^{-1}AP = D$.

Since $A^{100} = P D^{100} P^{-1}$, we have

$$A^{100} = \begin{bmatrix} 1 & 3/4 \\ 1 & 1 \end{bmatrix} \begin{bmatrix} 2 & 0 \\ 0 & -3 \end{bmatrix}^{100} \begin{bmatrix} 4 & -3 \\ -4 & 4 \end{bmatrix}$$

$$= \begin{bmatrix} 1 & 3/4 \\ 1 & 1 \end{bmatrix} \begin{bmatrix} 2^{100} & 0 \\ 0 & (-3)^{100} \end{bmatrix} \begin{bmatrix} 4 & -3 \\ -4 & 4 \end{bmatrix}$$

$$= \begin{bmatrix} 2^{100} & 3/4 \cdot 3^{100} \\ 2^{100} & 3^{100} \end{bmatrix} \begin{bmatrix} 4 & -3 \\ -4 & 4 \end{bmatrix}$$

$$= \begin{bmatrix} 4 \cdot 2^{100} - 3^{101} & -3 \cdot 2^{100} + 3^{101} \\ 4 \cdot 2^{100} - 4 \cdot 3^{100} & -3 \cdot 2^{100} + 4 \cdot 3^{100} \end{bmatrix}$$