§ 1.6 - Subspaces of 
$$\mathbb{R}^n$$
 (\$1.2 in fext)  
Webe been studying the geometry of vectors in  $\mathbb{R}^n$  ( $n=1,2,3,...$ )  
Everything we've done in  $\mathbb{R}^n$  works because  
(i) We can add vectors in  $\mathbb{R}^n$  according to certain  
nice rules:  
For all  $\vec{w}, \vec{x}, \vec{y} \in \mathbb{R}^n$  (closed under addition)  
(2)  $\vec{x} + \vec{y} = \vec{y} + \vec{x}$  (addition is commutative)  
(3)  $(\vec{x} + \vec{y}) + \vec{w} = \vec{x} + (\vec{y} + \vec{w})$  (addition is associative)  
(4) There exists a vector  $\vec{v} \in \mathbb{R}^n$  such that  $\vec{x} + (-\vec{x}) = \vec{0}$   
(additive inverses)  
(5) For each  $\vec{x} \in \mathbb{R}^n$  there exists a vector  $-\vec{x} \in \mathbb{R}^n$  such that  $\vec{x} + (-\vec{x}) = \vec{0}$   
(additive inverses)  
(5) No can Multiply vectors in  $\mathbb{R}^n$  by real scalars according  
to certain nice, rules:  
For all  $\vec{w}, \vec{x}, \vec{y} \in \mathbb{R}^n$  and  $s, t \in \mathbb{R}$  we have  
(6)  $t\vec{x} \in \mathbb{R}^n$  (closed under scalar multiplication)  
(7)  $s(t\vec{x}) = (st) \cdot \vec{x}$  (a distributive law)  
(10)  $1\vec{x} = \vec{x}$  (scalar multiplicative)  
Since  $\mathbb{R}^n$  is closed under addition (1),  
closed under scalar multiplication (6),  
and these operations obey the other rules above,  
we call  $\mathbb{R}^n$  a vector space.

There are <u>LOTS</u> of other vector spaces out there... In this course we'll only be interested in vector spaces  $S \xrightarrow{within R^n}$  (i.e., sets S contained in R<sup>n</sup> that are · closed under addition, and · closed under scalar multiplication.) Definition A non-empty subset S of R<sup>n</sup> is called a subspace of R<sup>n</sup> if for all vectors  $\overline{x}, \overline{y} \in S$  and  $t \in R$ , (1)  $\overline{x} + \overline{y} \in S$  (S is closed under addition), and

(z)  $t \vec{x} \in S$  (S is closed under scalar multiplication)



Thankfully, no! Any subspace of  $\mathbb{R}^n$  will automatically inherits properties (2)-(5) and (7)-(10) from  $\mathbb{R}^n$ , so we don't need to check them!

Remarks: (i) In (2) of the definition of "subspace"  
above, we can set 
$$t=0$$
 to see that  
every subspace must contain  $\vec{O}$   
This is useful for showing that certain subsets of  
 $\mathbb{R}^n$  are NOT subspaces.  
For example, if  $S = \left\{ \begin{bmatrix} \mathbf{x}_1 \\ \mathbf{x}_2 \end{bmatrix} : \mathbf{x}_1 + \mathbf{x}_2 - 3\mathbf{x}_3 = 5 \right\}$ , then  $S$   
is NOT a subspace of  $\mathbb{R}^3$ .  
Why?  $\vec{O} \notin S!$ 

In fact, if S is any line or plane in R<sup>h</sup> that doesn't pass through the origin, then S is NOT a subspace!

(ii) The smallest subspace of 
$$\mathbb{R}^n$$
 is  $\{\vec{0}\}$ .  
This is sometimes called the trivial subspace.

Ex: Show that 
$$S = \left\{ \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} : x_1 + 2x_2 + 3x_3 = 0 \right\}$$
 is a subspace of  $\mathbb{R}^3$ .

(i) 
$$\underline{S}$$
 is non-empty  
We'll check that  $\overline{O} \in \underline{S}$ . If  $x_1 = 0$ ,  $x_2 = 0$ , and  $x_3 = 0$ ,  
then  $x_1 + 2x_2 + 3x_3 = 0 + 2(0) + 3(0) = 0$ . So  $\overline{O} \in \underline{S}$ .  
 $\therefore$   $\underline{S}$  is non-empty.

(ii) 
$$S$$
 is closed under addition  
Suppose that  $\vec{x} = \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix}$ ,  $\vec{y} = \begin{bmatrix} y_1 \\ y_3 \end{bmatrix} \in S$ , So  
 $\vec{x}_1 + 2x_2 + 3x_3 = 0$  and  $y_1 + 2y_2 + 3y_3 = 0$ .  
We need to check that  $\vec{x} + \vec{y} = \begin{bmatrix} x_1 + y_1 \\ x_2 + y_3 \end{bmatrix}$  belongs to  $S$ .  
We have  
 $(x_1 + y_1) + 2(x_2 + y_2) + 3(x_3 + y_3) = (x_1 + 2x_2 + 3x_3) + (y_1 + 2y_2 + 3y_3)$   
 $= 0$   
 $= 0 + 0$   
 $= 0$ 

$$\therefore$$
  $\vec{X} + \vec{y} \in \vec{S}$ , so  $\vec{S}$  is closed under addition

(iii) 
$$S$$
 is closed under scalar multiplication.  
Suppose that  $\vec{X} = \begin{bmatrix} x_1 \\ z_2 \\ z_3 \end{bmatrix}$  belongs to  $S$ , so  $X_1 + 2x_2 + 3x_3 = 0$ .  
For  $E \in \mathbb{R}$ , we must show that  $E\vec{X} = \begin{bmatrix} tx_1 \\ tx_2 \\ tx_3 \end{bmatrix} \in S$ .

$$(tx_1) + 2(tx_2) + 3(tx_3) = tx_1 + t(2x_2) + t(3x_3)$$
  
=  $t(x_1 + 2x_2 + 3x_3)$   
=  $t(0)$   
=  $0$ 

: EXES, so S is closed under scalar multiplication.

By (i), (ii), (iii), S is a subspace of 
$$\mathbb{R}^3$$
.

Exi Show that 
$$\Upsilon = \left\{ \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} : 2x_1 = 3x_2 \right\}$$
 is a subspace of  $\mathbb{R}^2$ .

(i) 
$$\underline{T}$$
 is non-empty  
Let's check that  $\overline{O} \in T$ . If  $x_1 = 0$  and  $x_2 = 0$ , then  
 $2x_1 = 0$  and  $3x_2 = 0$ , so  $2x_1 = 3x_2$ .

(ii) 
$$T$$
 is closed under addition.  
Suppose that  $\vec{x} = \begin{bmatrix} x_1 \\ x_2 \end{bmatrix}$  and  $\vec{y} = \begin{bmatrix} y_1 \\ y_2 \end{bmatrix}$  belong to ,  
so  $2x_1 = 3x_2$  and  $2y_1 = 3y_2$ .  
We must show that  $\vec{x} + \vec{y} = \begin{bmatrix} x_1 + y_1 \\ x_2 + y_2 \end{bmatrix} \in T$  as well.  
We have  
 $2(x_1 + y_1) = 2x_1 + 2y_1 = 3x_2 + 3y_2 = 3(x_2 + y_2)$ .  
 $\therefore \vec{x} + \vec{y} \in T$ , so  $T$  is closed under addition.

(iii) T is closed under scalar Multiplication.  
Suppose that 
$$\vec{X} = \begin{bmatrix} x_1 \\ x_2 \end{bmatrix}$$
 belongs to T, So  $2x_1 = 3x_2$ .  
For teR, we must show that  $\pm \vec{x} = \begin{bmatrix} \pm x_1 \\ \pm x_2 \end{bmatrix} \in T$ .  
We have

$$2(tx_1) = t(Zx_1) = t(3x_2) = 3(tx_2).$$



Solution

Show that 
$$S = \{ \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} : x_1 x_2 = 0 \}$$
 is not a subspace of  $\mathbb{R}^2$ .

The fastest way to do this would be to show that S  
doesn't contain 
$$\vec{O}$$
. Unfortunately,  $\vec{O} \in S$ ...  
Can we show that S is not closed under addition?  
If  $\vec{X} = \begin{bmatrix} 1 \\ 0 \end{bmatrix}$  and  $\vec{y} = \begin{bmatrix} 0 \\ 1 \end{bmatrix}$ , then  $\vec{X}, \vec{y} \in S$ , but  
 $\frac{\vec{X} + \vec{y} = \begin{bmatrix} 1 \\ 1 \end{bmatrix} \notin S$ .  
Why? Because  $(1)(1) \notin O$ .  
So S is not closed under addition, hence S is Not  
a subspace of  $\mathbb{R}^2$  !

Exercise: For each set below, decide whether or not it is a subspace of R<sup>3</sup>. Justify your answer.  $S_{1} = \begin{cases} \begin{pmatrix} x_{1} \\ x_{2} \\ x_{3} \end{cases} : 3x_{2} - 5x_{3} = 0 \end{cases}$  $S_{z} = \left\{ \begin{bmatrix} x_{1} \\ x_{2} \\ x_{3} \end{bmatrix} : x_{1} \ge 0 \right\}$  $S_{4} = \left\{ \begin{bmatrix} x_{1} \\ x_{2} \\ x_{3} \end{bmatrix} : \mathcal{X}_{1} + \mathcal{Y}_{2} = 1 \right\}$  $S_5 = \left\{ \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix}; \quad x_1 + 3x_2 = 0, \quad x_2 = x_3 \right\}$ 

Ex: If 
$$\mathbb{B} = \{\vec{v}_1, \vec{v}_2, ..., \vec{v}_k\}$$
 is a set of vectors in  $\mathbb{R}^n$ , let  $S$   
be the set of linear combinations of vectors from  $\mathbb{B}$ :  
 $S = \{t_1\vec{v}_1 + t_2\vec{v}_2 + ... + t_k\vec{v}_k \mid t_1, t_2, ..., t_k \in \mathbb{R}\}$   
Then  $S$  is a subspace of  $\mathbb{R}^n$ .

• 
$$\underline{S}$$
 is non-empty  
By taking  $t_1 = t_2 = \cdots = t_k = 0$ , we have that  
 $\overline{O} = 0 \overline{v_1} + 0 \overline{v_2} + \cdots + 0 \overline{v_k} \in S$ .

• S is closed under addition  
Let 
$$\vec{x}$$
 and  $\vec{y}$  belong to S'.  
By definition, there are  $t_1, t_2, ..., t_k \in \mathbb{R}$  and  $S_1, S_2, ..., S_k \in \mathbb{R}$   
such that  $\vec{x} = t_1 \vec{v_1} + t_2 \vec{v_2} + ... + t_k \vec{v_k}$   
 $\vec{y} = S_1 \vec{v_1} + S_2 \vec{v_2} + ... + S_k \vec{v_k}$ 

But then

$$\vec{X} + \vec{y} = \left( \underbrace{t_1 \vec{v}_1}_{l} + \underbrace{t_2 \vec{v}_2}_{l} + \cdots + \underbrace{t_k \vec{v}_k}_{l} \right) + \left( \underbrace{s_1 \vec{v}_1}_{l} + \underbrace{s_2 \vec{v}_2}_{l} + \cdots + \underbrace{s_k \vec{v}_k}_{l} \right)$$
$$= \left( \underbrace{t_1 + s_1}_{l} \right) \vec{v}_1 + \left( \underbrace{t_2 + s_2}_{l} \right) \vec{v}_2 + \cdots + \left( \underbrace{t_k + s_k}_{l} \right) \vec{v}_k$$

Since each 
$$(t_i + s_i) \in \mathbb{R}$$
, we have that  $\vec{x} + \vec{y} \in S$   
... S is closed under addition

•  $\underline{S}$  is closed under scalar multiplication If  $\vec{x} \in S$ , then there are  $S_1, S_2, ..., S_K \in \mathbb{R}$  such that  $\vec{x} = S_1 \vec{v_1} + S_2 \vec{v_2} + \dots + S_k \vec{v_k}$ Then for any  $t \in \mathbb{R}$ , we have  $t \vec{x} = t \left( S_1 \vec{v_1} + S_2 \vec{v_2} + \dots + S_k \vec{v_k} \right)$  $= (t S_1) \vec{v_1} + (t S_2) \vec{v_2} + \dots + (t S_k) \vec{v_k}$ 

Since each  $ts_i \in \mathbb{R}$ , we have  $t\overline{x} \in S$ .  $\therefore$  S is closed under scalar multiplication.

Thus, S is indeed a subspace of Rn!

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