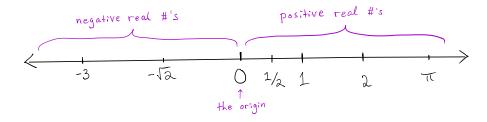
R = the set of all real numbers. $e.g.: 1 \in \mathbb{R}, 2 \in \mathbb{R}, -3 \in \mathbb{R}, \pi \in \mathbb{R}, \frac{1}{2} \in \mathbb{R}, -52 \in \mathbb{R}$

We often think of R as a <u>1-dimensional space</u> (the real line):



If
$$x \in \mathbb{R}$$
, then $t \times \in \mathbb{R}$ for all real numbers t .
(\mathbb{R} is closed under scalar multiplication)

Loosely speaking, a set with properties
$$(1)+(2)$$
 is called a real vector space or a vector space over R .

$$\frac{\mathbb{R}^{2}: 2 - \text{Dimensional Space}}{\text{We can represent elements}}$$

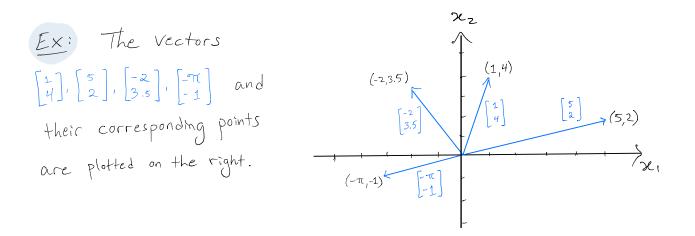
$$\frac{\mathbb{R}^{2}: 2 - \text{Dimensional Space}}{\mathbb{R}^{2}}$$

$$\frac{\mathbb{R}^{2}: 2 - \text{Dimensional Space}}{\mathbb{R}^{2}}$$

$$\frac{\mathbb{R}^{2}: P(P_{1}, P_{2})}{\mathbb{R}^{2}}$$

$$\frac{\mathbb{R}^{2}: P(P_{1}, P_{2})}{$$

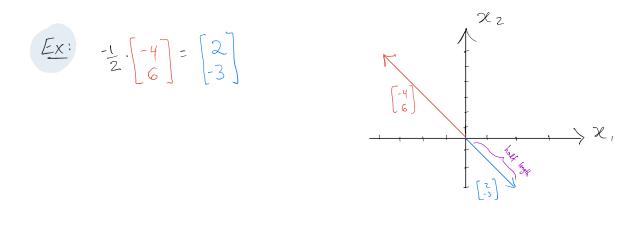
The zero-vector is $\vec{O} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$.



We'll often switch between thinking of elements in \mathbb{R}^2 as points $P(p_1, p_2)$ and vectors $\vec{p} = \begin{bmatrix} p_1 \\ p_2 \end{bmatrix}$

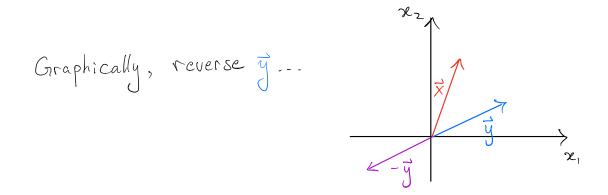
Q: Can we add and scale/stretch in
$$\mathbb{R}^2$$
? \underbrace{YES}_{z} ?
Addition: If $\vec{x} = \begin{bmatrix} x_1 \\ x_2 \end{bmatrix}$ and $\vec{y} = \begin{bmatrix} y_1 \\ y_2 \end{bmatrix}$, then
 $\vec{x} + \vec{y} = \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} + \begin{bmatrix} y_1 \\ y_2 \end{bmatrix} = \begin{bmatrix} x_1 + y_1 \\ x_2 + y_2 \end{bmatrix}$

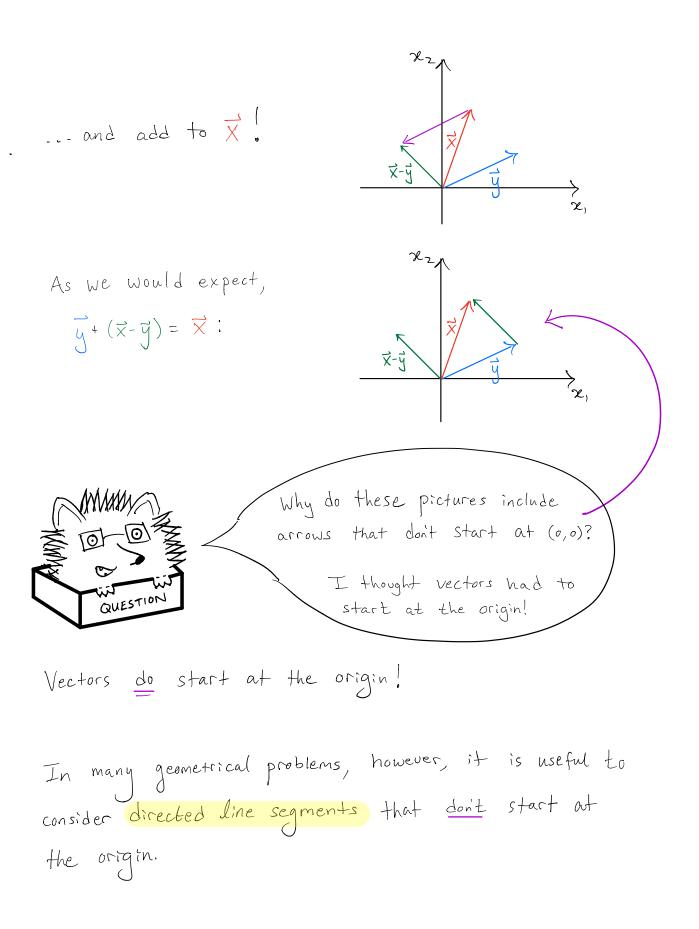
Scalar Multiplication: If
$$\vec{X} = \begin{bmatrix} x \\ x_1 \end{bmatrix}$$
 and $t \in R$, then
 $\begin{bmatrix} t \vec{X} = t \\ x_2 \end{bmatrix} = \begin{bmatrix} t x_1 \\ t x_2 \end{bmatrix}$
These operations can be viewed geometrically!
To add, connect vectors tip to tail.
 $\vec{E}x: \begin{bmatrix} x \\ y \end{bmatrix} + \begin{bmatrix} 2 \\ 1 \end{bmatrix} = \begin{bmatrix} 3 \\ 4 \end{bmatrix}$
 $\vec{T} = \begin{bmatrix} 3 \\ 4 \end{bmatrix}$
 $\vec{T} = \begin{bmatrix} 3 \\ 1 \end{bmatrix} = \begin{bmatrix} 3 \\ 4 \end{bmatrix}$
 $\vec{T} = \begin{bmatrix} 3 \\ 1 \end{bmatrix} = \begin{bmatrix} 3 \\ 4 \end{bmatrix}$
 $\vec{T} = \begin{bmatrix} 3 \\ 1 \end{bmatrix} = \begin{bmatrix} 6 \\ 3 \end{bmatrix}$
 $\vec{T} = \begin{bmatrix} 7 \\ 7 \end{bmatrix}$
 $\vec{T} =$

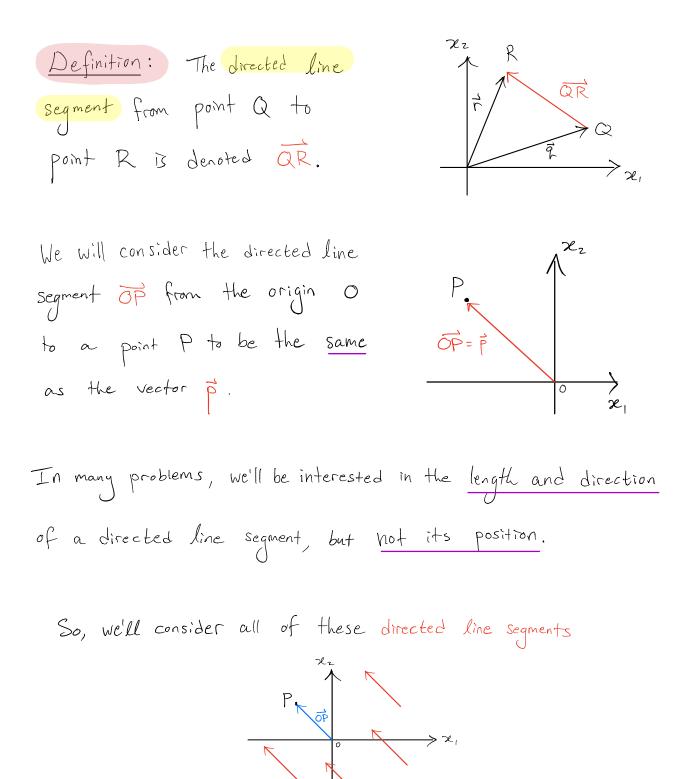


This also gives us a way to <u>subtract</u>! If $\vec{X} = \begin{bmatrix} x_1 \\ x_2 \end{bmatrix}$ and $\vec{y} = \begin{bmatrix} y_1 \\ y_2 \end{bmatrix}$, then $\vec{X} - \vec{y} = \vec{X} + (-1)\vec{y} = \begin{bmatrix} x_1 - y_1 \\ x_2 - y_2 \end{bmatrix}$

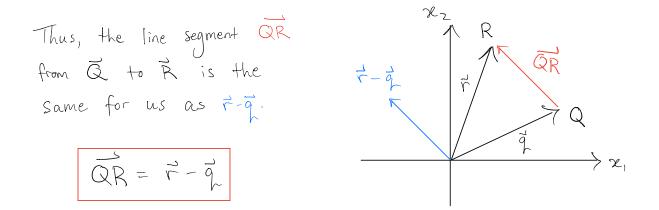
$$E_{X}: \begin{bmatrix} 1 \\ 3 \end{bmatrix} - \begin{bmatrix} 6 \\ 3 \end{bmatrix} = \begin{bmatrix} -5 \\ 0 \end{bmatrix}$$





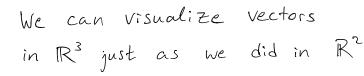


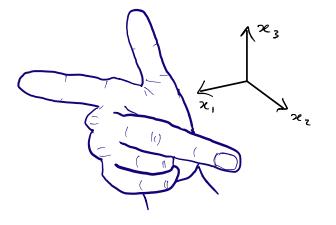
to be the same as $\overrightarrow{OP} = \overrightarrow{P}$.

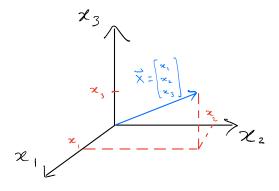


Vectors in Rh

Everything above can also be done in higher dimensions: $R^{3} = \left\{ \begin{bmatrix} \varkappa_{1} \\ \varkappa_{2} \\ \varkappa_{3} \end{bmatrix} : \varkappa_{1}, \varkappa_{2}, \varkappa_{3} \in R \right\}$







Here, the three axes are oriented according to the right hand rule.

More generally, if n is any positive integer,

$$R^{n} = \left\{ \begin{bmatrix} x_{1} \\ x_{2} \\ \vdots \\ x_{n} \end{bmatrix} : x_{1}, x_{2}, \dots, x_{n} \in R \right\}$$

Definition: If
$$\vec{X} = \begin{bmatrix} \varkappa_1 \\ \varkappa_2 \\ \vdots \\ \varkappa_n \end{bmatrix}$$
, $\vec{y} = \begin{bmatrix} y_1 \\ y_2 \\ \vdots \\ y_n \end{bmatrix}$ are vectors in \mathbb{R}^n

and LER, then

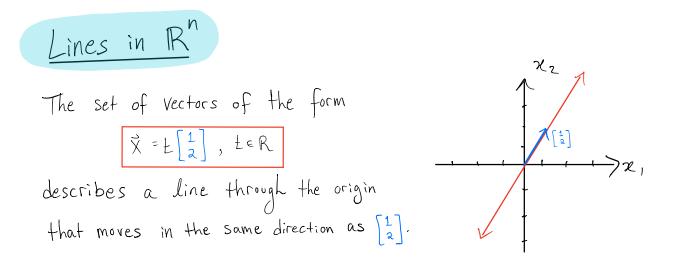
$$\vec{X} + \vec{y} = \begin{bmatrix} x_i + y_i \\ x_2 + y_2 \\ \vdots \\ y_{n} + y_n \end{bmatrix}$$
 (Addition)
$$\vec{t} \cdot \vec{x} = \begin{bmatrix} t \cdot x_i \\ t \cdot x_2 \\ \vdots \\ t \cdot x_n \end{bmatrix}$$
 (Scalar Multiplication)

In
$$\mathbb{R}^{4}$$
, $2\begin{bmatrix}3\\0\\1/2\\4\end{bmatrix} + \begin{bmatrix}1\\1\\6\\-2\end{bmatrix} = \begin{bmatrix}6\\0\\1\\8\end{bmatrix} + \begin{bmatrix}1\\1\\6\\-2\end{bmatrix} = \begin{bmatrix}7\\-\\1\\-2\end{bmatrix} =$

For all $\vec{w}, \vec{x}, \vec{y} \in \mathbb{R}^n$ and $s, t \in \mathbb{R}$ we have

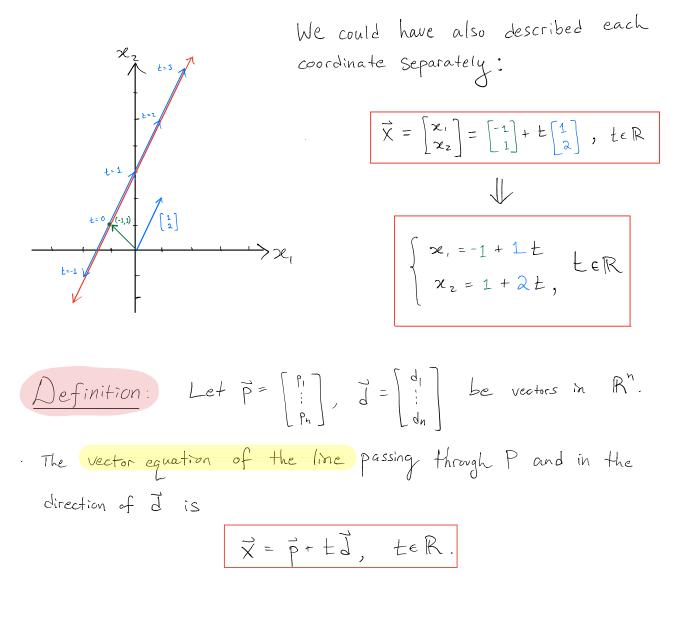
- (1) $\vec{x} + \vec{y} \in \mathbb{R}^n$ (closed under addition)
- (2) $\vec{x} + \vec{y} = \vec{y} + \vec{x}$ (addition is commutative)
- (3) $(\vec{x} + \vec{y}) + \vec{w} = \vec{x} + (\vec{y} + \vec{w})$ (addition is associative)
- (4) There exists a vector $\vec{0} \in \mathbb{R}^n$ such that $\vec{z} + \vec{0} = \vec{z}$ for all $\vec{z} \in \mathbb{R}^n$ (zero vector)
- (5) For each $\vec{x} \in \mathbb{R}^n$ there exists a vector $-\vec{x} \in \mathbb{R}^n$ such that $\vec{x} + (-\vec{x}) = \vec{0}$ (additive inverses)
- (6) $t\vec{x} \in \mathbb{R}^n$ (closed under scalar multiplication)
- (7) $s(t\vec{x}) = (st)\vec{x}$ (scalar multiplication is associative)
- (8) $(s+t)\vec{x} = s\vec{x} + t\vec{x}$ (a distributive law)
- (9) $t(\vec{x} + \vec{y}) = t\vec{x} + t\vec{y}$ (another distributive law)
- (10) $1\vec{x} = \vec{x}$ (scalar multiplicative identity)

Properties of addition, scalar multiplication



What about the set of vectors of the form
$$\vec{X} = \begin{bmatrix} -1 \\ 1 \end{bmatrix} + t \begin{bmatrix} 1 \\ 2 \end{bmatrix}, t \in \mathbb{R}$$
?

This new line passes through (-1, 1), but still moves in the Same direction as $\begin{bmatrix} 1 \\ a \end{bmatrix}$. (i.e., it is parallel to $\begin{bmatrix} 1 \\ 2 \end{bmatrix}$.)



The parametric equation of this line is

$$\begin{cases}
X_1 = P_1 + t d_1 \\
X_2 = P_2 + t d_2 \\
\vdots & \vdots , \\
X_n = P_n + t d_n
\end{cases}$$
The parametric equation of this line is

. Two lines

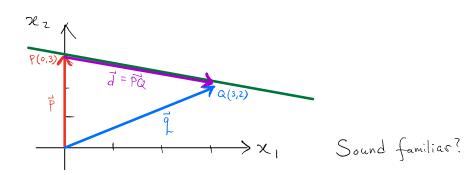
$$\begin{cases} \vec{X} = \vec{p} + t\vec{d}, \quad t \in \mathbb{R} \\ \vec{y} = \vec{q} + t\vec{e}, \quad t \in \mathbb{R} \end{cases}$$

are parallel if J is a (non-zero) scalar multiple of E.

EX: Find the vector equation of the line
(a) through
$$P(1,0)$$
 and in the direction of $\begin{bmatrix} 4\\3 \end{bmatrix}$;
(b) through $P(2,1)$ and parallel to the line $\vec{X} = \begin{bmatrix} 1\\1 \end{bmatrix} + t \begin{bmatrix} -6\\2 \end{bmatrix}$, teR;
(c) through $P(0,3)$ and $Q(3,2)$.

Solution:
(a)
$$\vec{p} = \begin{bmatrix} 1 \\ 0 \end{bmatrix}$$
 and $\vec{d} = \begin{bmatrix} 4 \\ 3 \end{bmatrix}$, so $\vec{X} = \begin{bmatrix} 1 \\ 0 \end{bmatrix} + t \begin{bmatrix} 4 \\ 3 \end{bmatrix}$, $t \in \mathbb{R}$.
(b) Here, $\vec{p} = \begin{bmatrix} 2 \\ 1 \end{bmatrix}$. Since our line is parallel to
 $\vec{X} = \begin{bmatrix} 1 \\ 1 \end{bmatrix} + t \begin{bmatrix} -6 \\ 2 \end{bmatrix}$, $t \in \mathbb{R}$
 $\vec{d} = any$ non-zero multiple of $\begin{bmatrix} -6 \\ 2 \end{bmatrix}$. Let's pick $\vec{d} = \begin{bmatrix} -6 \\ 2 \end{bmatrix}$
Our line is $\vec{X} = \begin{bmatrix} 2 \\ 1 \end{bmatrix} + t \begin{bmatrix} -6 \\ 2 \end{bmatrix}$, $t \in \mathbb{R}$.

(c) What's the direction vector? It's the line segment from P(0,3) to Q(3,2):



It's exactly $\vec{d} = \vec{PQ} = \vec{q} - \vec{P} = \begin{bmatrix} 3\\2 \end{bmatrix} - \begin{bmatrix} 0\\3 \end{bmatrix} = \begin{bmatrix} 3\\-1 \end{bmatrix}$ (note: $\vec{d} = \vec{QP}$ also works!)

We can use either P or Q as a point on the line. One equation: $\vec{X} = \begin{bmatrix} 0 \\ 3 \end{bmatrix} + t \begin{bmatrix} 3 \\ -1 \end{bmatrix}$, $t \in \mathbb{R}$.

Ex: Determine vector and parametric equations for the line through
$$P(4,0,1)$$
 and $Q(1,1,0)$ in \mathbb{R}^3 .

Solution: Let's start with the vector equation:
Direction vector
$$\vec{d}$$
 moves from $P(4,0,1)$ to $Q(1,1,0)$, So

$$\vec{d} = \vec{PQ} = \vec{q} - \vec{P} = \begin{bmatrix} 1\\1\\0 \end{bmatrix} - \begin{bmatrix} 4\\0\\1 \end{bmatrix} = \begin{bmatrix} -3\\1\\-1 \end{bmatrix}$$

We may use either P or Q as a point on the line.

One equation:
$$\vec{X} = \begin{bmatrix} 4 \\ 0 \\ 1 \end{bmatrix} + t \begin{bmatrix} -3 \\ 1 \\ -1 \end{bmatrix}$$
, $t \in \mathbb{R}$

Write
$$\tilde{X} = \begin{bmatrix} \chi_1 \\ \chi_2 \\ \chi_3 \end{bmatrix}$$
 to get the parametric equation: