

Constraint Satisfaction Problems

A Survey

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(with corrections)

CSP = specifications of subpowers of a finite algebra

Fix a finite algebra \mathbf{A} .

Definition

A **constraint network over \mathbf{A}** is a pair (n, φ) where

- ▶ $n \geq 1$
- ▶ φ is a quantifier-free formula of the form $\bigwedge_{i \in I} R_i(\mathbf{x}_i)$,

where for each $i \in I$,

- ▶ \mathbf{x}_i is a d -tuple of variables from $\{x_1, \dots, x_n\}$ (for some d)
- ▶ R_i is a **subuniverse** of \mathbf{A}^d .

The relation **defined by** (n, φ) is

$$\text{Rel}_{\mathbf{A}}(n, \varphi) = \{\mathbf{a} \in A^n : \varphi(\mathbf{a})\}.$$

Example

$$\begin{aligned}\text{Let } \mathbf{A} &= (\{0, 1\}; x+y+z) \\ R_0 &= \{(0, 0, 0), (0, 1, 1), (1, 0, 1), (1, 1, 0)\} \\ R_1 &= \{(0, 0, 1), (0, 1, 0), (1, 0, 0), (1, 1, 1)\}.\end{aligned}$$

$R_0, R_1 \leq \mathbf{A}^3$. Thus the following is a constraint network over \mathbf{A} :

$$(6, \underbrace{R_0(x_1, x_2, x_3) \wedge R_1(x_1, x_4, x_5) \wedge R_0(x_2, x_4, x_6) \wedge R_1(x_3, x_5, x_6)}_{\varphi}).$$

We can view φ as asserting (over \mathbb{Z}_2)

$$\begin{array}{rcl}x_1 + x_2 + x_3 & = & 0 \\x_1 & + x_4 + x_5 & = 1 \\x_2 & + x_4 & + x_6 = 0 \\& + x_3 & + x_5 + x_6 = 1.\end{array}$$

$\text{Rel}_{\mathbf{A}}(6, \varphi)$ is the solution-set to this linear system.

Variant notations

A **constraint network over \mathbf{A}** is a pair (n, φ) , $\varphi = \bigwedge_i R_i(\mathbf{x}_i) \dots$

...	may be written as ...
n	$\{\mathbf{x}_1, \dots, \mathbf{x}_n\}$ ($= V$, the set of variables)
φ	$\{(\mathbf{x}_i, R_i) : i \in I\}$ ($= \mathcal{C}$) <ul style="list-style-type: none">• (\mathbf{x}_i, R_i) is called a constraint• \mathbf{x}_i is its scope• R_i is its constraint relation
(n, φ)	(V, \mathcal{C}) or (V, A, \mathcal{C})
$\text{Rel}_{\mathbf{A}}(n, \varphi)$	$\text{Sol}(V, \mathcal{C})$

Decision Problems

Definition

(n, φ) is **k -ary** if each scope has length $\leq k$.

Definition

$\text{CSP}(\mathbf{A}, k)$

Input: A k -ary constraint network (n, φ) over \mathbf{A} .

Question: Is $\text{Rel}_{\mathbf{A}}(n, \varphi) \neq \emptyset$?

Dichotomy Conjecture (Feder & Vardi)

For all \mathbf{A} and k , $\text{CSP}(\mathbf{A}, k)$ is in P or is NP-hard.

Algebraic Dichotomy Conjecture (Bulatov, Krokhin & Jeavons)

If \mathbf{A} has a Taylor operation, then $\text{CSP}(\mathbf{A}, k)$ is in P for every k .

\mathbf{A} is tractable

Taylor operations

Definition

An operation $t : A^n \rightarrow A$ is a **Taylor operation** if

1. t is idempotent ($t(x, x, \dots, x) \approx x$);
2. For each $i = 1, \dots, n$, t satisfies an identity of the form $t(\mathbf{x}) \approx t(\mathbf{y})$ with $x_i \neq y_i$.

Theorem (Taylor; Barto & Kozik; Hobby & McKenzie)

For a finite algebra \mathbf{A} , the following are equivalent:

1. \mathbf{A} has a Taylor (term) operation.
2. \mathbf{A} satisfies some idempotent Maltsev condition not satisfied by SETS.
3. \mathbf{A} has an idempotent **cyclic** term $t(x_1, \dots, x_n)$, i.e.,

$$t(x_1, x_2, \dots, x_n) \approx t(x_2, \dots, x_n, x_1).$$

4. $V(\mathbf{A})$ omits type 1.

Progress

Algebraic Dichotomy Conjecture

If \mathbf{A} has a Taylor operation, then $\underbrace{\text{CSP}(\mathbf{A}, k)}_{\mathbf{A} \text{ is tractable}}$ is in P for every k .

Theorem

\mathbf{A} is known to be tractable if:

1. $V(\mathbf{A})$ is CM. (Dalmau '05 + IMM VW '07, using Barto '16?)
2. $V(\mathbf{A})$ is $\text{SD}(\wedge)$. (Barto & Kozik '09; Bulatov '09)
3. \mathbf{A} is Taylor + **conservative**, i.e. $\text{Su}(\mathbf{A}) = \mathcal{P}(A)$. (Bulatov '03)
4. \mathbf{A} is Taylor and $|A| = 2$ or 3 . (Schaefer '78, Bulatov '02)

Definition

Let \mathbf{A} be a finite algebra, \mathcal{A} a set of finite algebras.

1. $\text{CSP}(\mathbf{A}) = \bigcup_k \text{CSP}(\mathbf{A}, k)$. “Global”
2. $\text{CSP}(\mathcal{A}, k) = \bigcup_{\mathbf{A} \in \mathcal{A}} \text{CSP}(\mathbf{A}, k)$. “Uniform”

Can't ask these problems to be in P. (Set of inputs is problematic.)

Definition

Say $\text{CSP}(\mathbf{A})$ [$\text{CSP}(\mathcal{A}, k)$] is “in” P if there is a poly-time algorithm which correctly decides all inputs to $\text{CSP}(\mathbf{A})$ [$\text{CSP}(\mathcal{A}, k)$].

Global Tractability Problem

If \mathbf{A} is tractable, does it follow that $\underbrace{\text{CSP}(\mathbf{A})}_{\mathbf{A} \text{ is globally tractable}}$ is “in” P?

Uniform Tractability Question

(For a given Taylor class \mathcal{A}): Is $\underbrace{\text{CSP}(\mathcal{A}, k)}_{\mathcal{A} \text{ is uniformly tractable}}$ “in” P for all k ?

Theorem

\mathbf{A} is known to be globally tractable if:

1. \mathbf{A} has a **cube term**. (Dalmau '05 + IMM VW '07)
2. $V(\mathbf{A})$ is $SD(\wedge)$. (Bulatov '09; Barto '14)
3. \mathbf{A} is Taylor + conservative. (Bulatov '03)
4. \mathbf{A} is Taylor and $|A| = 2$ or 3 . (Schaefer '78, Bulatov '02)

Theorem (Bulatov '09; Barto '14)

The class \mathcal{SD}_{\wedge} of all finite algebras generating an $SD(\wedge)$ variety is uniformly globally tractable.

Open problems

1. If $V(\mathbf{A})$ is congruence modular, is \mathbf{A} globally tractable?
2. Is the class \mathcal{M} of finite Maltsev algebras uniformly tractable?
3. If \mathbf{A} has a difference term, is \mathbf{A} tractable?
4. Suppose \mathbf{A} is idempotent and has a congruence θ such that
 - ▶ $\mathbf{A}/\theta \in \mathcal{SD}_{\wedge}$, and
 - ▶ Each θ -block is in \mathcal{M} .(“ $\mathcal{SD}(\wedge)$ over Maltsev.”) Is \mathbf{A} tractable?

Standard reductions

$\text{CSP}(\mathbf{A}, k)$ reduces to:

1. $\text{CSP}(\mathbf{A} \parallel_U, k)$, where U is a minimal range of a unary idempotent term, and $\mathbf{A} \parallel_U$ is the induced term-minimal algebra defined on U .
2. $\text{CSP}((\mathbf{A} \parallel_U)^{\text{id}}, k)$ where $(\mathbf{B})^{\text{id}}$ is the idempotent reduct of \mathbf{B} .

(This is the “reduction to the idempotent case.”)

3. $\text{CSP}(\mathbf{A}^{\lceil k/2 \rceil}, 2)$
4. $\text{multi-CSP}(H(\mathbf{A})_{si}, kd)$, where \mathbf{A} is a subdirect product of d subdirectly irreducible homomorphic images.
5. $\text{CSP}(\mathbf{A}^+, k)$ where $\mathbf{A}^+ = (A; \text{Pol}(\text{Su}(\mathbf{A}^k)))$.

Conditioning the input – local consistency

Let (n, φ) be a 2-ary constraint network over \mathbf{A} .

At essentially no cost, one can assume that (n, φ) is “determined” by a “(2,3)-minimal” constraint network.

Definition

A 2-ary constraint network (n, φ) is a **(2,3)-system**¹ provided for all $i, j \in \{1, 2, \dots, n\}$:

1. φ has exactly one constraint $R_{i,j}(x_i, x_j)$ with scope (x_i, x_j) .
2. $R_{j,i} = (R_{i,j})^{-1}$.
3. For all k , $R_{i,j} \subseteq R_{i,k} \circ R_{k,j}$.

The “associated potatoes” are $A_i := \text{proj}_1(R_{i,j})$, $i = 1, \dots, n$.

Fact

There is a poly-time algorithm which, given a 2-ary constraint network over \mathbf{A} , outputs an equivalent (2,3)-system over \mathbf{A} .

¹There is no standard terminology.

Conditioning the input – absorption

Definition

Suppose \mathbf{A} is a finite idempotent algebra and $\mathbf{B} \leq \mathbf{A}$.

1. \mathbf{B} is an **absorbing subalgebra** if there exists a term operation $t(x_1, \dots, x_m)$ of \mathbf{A} such that

$$t(B, \dots, B, A, B, \dots, B) \subseteq B$$

for all possible positions of A .

2. \mathbf{A} is **absorption-free** if it has no proper absorbing subalgebra.

Given a (2,3)-system (n, φ) over an idempotent \mathbf{A} , Barto & Kozik show how to “shrink” the associated potatoes to absorption-free algebras, though losing (2,3)-systemhood and equivalency.

In some situations this has proven to be useful.

Miklós magic

Lemma (Maróti '09)

Suppose \mathbf{A} is idempotent and has a term operation $t(x, y)$ such that:

1. $\mathbf{A} \models t(x, t(x, y)) \approx t(x, y)$.
2. $t(a, x)$ is non-surjective, for all $a \in A$.
3. There exists a proper subalgebra $\mathbf{C} < \mathbf{A}$ such that if $t(x, a)$ is surjective then $a \in C$.

Then $\text{CSP}(\mathbf{A}, k)$ can be reduced to $\text{multi-CSP}(\mathcal{B} \setminus \{\mathbf{A}\}, \ell)$, where

- ▶ \mathcal{B} is the closure of $\{\mathbf{A}\}$ under H , S , and “idempotent unary polynomial retracts.”
- ▶ $\ell = \max(k, |A|)$.

This may seem random, but it is useful (and the proof is beautiful).

Moving forward

Suppose (n, φ) is a k -ary constraint network over \mathbf{A} , and $R = \text{Rel}_{\mathbf{A}}(n, \varphi) \leq \mathbf{A}^n$.

Definition

A **compact k -frame** for R is a subset $F \subseteq R$ such that

1. $\text{proj}_J(F) = \text{proj}_J(R)$ for all $J \subseteq \{1 \dots, n\}$ with $|J| \leq k$.
2. $|F| \leq |A|^k \cdot \binom{n}{k}$.

Every relation definable by a k -ary constraint network over \mathbf{A} has a compact k -frame, and is determined by any one of its k -frames.

Speculation: Is it possible to mimic the few subpowers algorithm without having few subpowers?

To carry this out, we would need a notion of “compact k -representation” extending compact k -frames with more data.

The following problem seems central:

Functional Dependency Problem

Suppose

- ▶ \mathbf{A} is finite, idempotent, Taylor.
- ▶ F is a compact k -frame for a relation $R \leq \mathbf{A}^n$ defined by some k -ary constraint network over \mathbf{A} .
- ▶ $X \subseteq \{1, \dots, n\}$ and $\ell \in \{1, \dots, n\} \setminus X$.

What additional data would enable us to efficiently decide whether $\text{proj}_{X \cup \{\ell\}}(R)$ is the graph of a function $f : \text{proj}_X(R) \rightarrow \text{proj}_\ell(R)$?

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