All work and no play makes Jack enumerate maps

Michael La Croix PhD

University of Waterloo

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Outline

- Combinatorial Enumeration

- - Orientable Maps
 - Non-Orientable Maps
 - Hypermaps
 - Generating Series
- What does Jack have to do with it?
 - The invariants resolve a special case



- I'm a mathematician.
- I study combinatorial enumeration.
- I think a lot of problems are best understood via pictures.

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Enumeration

Systematic counting.

Example

How many ways are there to arrange 7 black and 3 white marbles in a row?



Generating Series (or Partition Functions)

A **generating series** is an algebraic tool for recording a sequences of numbers. Using such tools, counting problems become algebra problems.

Example

If $a_{n,k}$ is the number of ways to arrange n black and k white marbles, then

$$\sum_{n,k \ge 0} a_{n,k} x^n y^k = \sum_{n,k \ge 0} \binom{n+k}{k} x^n y^k = \frac{1}{1-x-y}$$

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- The behaviour of a sequence of numbers can describe physical properties.
 - This is the idea behind **Statistical mechanics**, a branch of physics that qualitatively models phase transitions.

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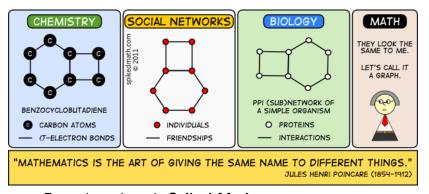
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- - Orientable Maps
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What is mathematics?

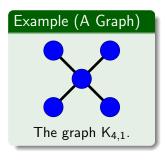
Mathematics is a way of abstractly studying relationships between objects.

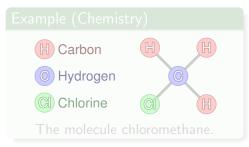


From the webcomic **Spiked Math** at spikedmath.com

Extra Information

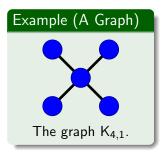
By studying the abstraction, we can more easily recognize what extra information is essential to the structure of a problem.

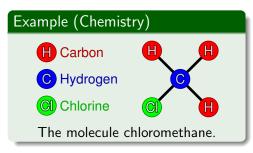




Extra Information

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Labelled Vertices

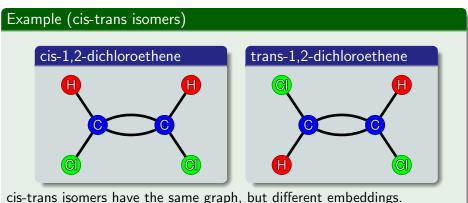
With labelled graphs, we can distinguish between some kinds of isomers.

Example (Isomers of dichloroethene) 1,1-dichloroethene 1,2-dichloroethene

The 1,1 and 1,2 isomers of $C_2H_2Cl_2$ are represented by different graphs.

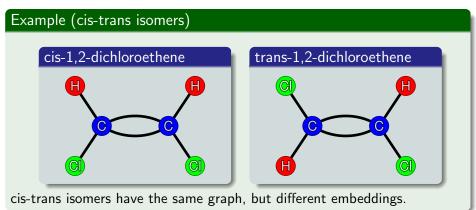
Embeddings

For other isomers, we actually need to draw the graphs.



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Conclusion: Sometimes the way a graph is drawn is as important as the graph itself.







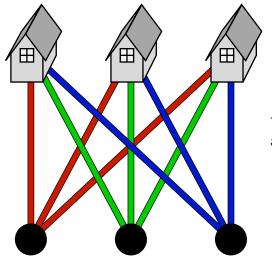
A classical challenge is how to place conduits so that three utilities can be connected to three houses.

This should be done so that no conduits cross.

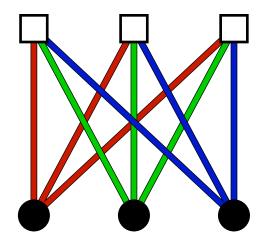




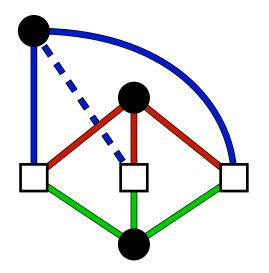




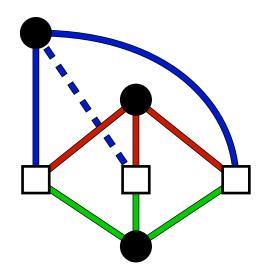
Together, the houses, utilities, and conduits define a graph.



We want to embed the graph.



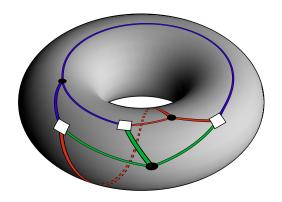
After a lot of effort, we conclude that the problem cannot be solved as it appears to be stated.



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This is actually a classic result (Kuratowski's Theorem). The given graph is one of two obstacles to being able to draw a graph on the plane.

Solving the problems relies on finding a loop-hole in its statement.

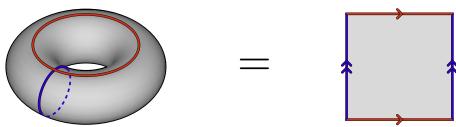


Solving the problems relies on finding a loop-hole in its statement.

One solution is that, as stated, the problem does not say that the houses are on a plane. We can draw them on a torus.

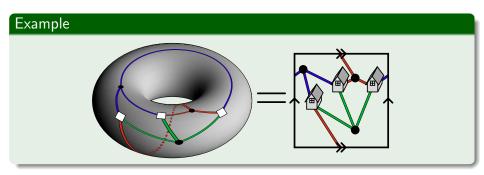
Representing Surfaces

The torus (or any surface) can be represented schematically in terms of the surgery required to stitch it together from a rubber sheet.

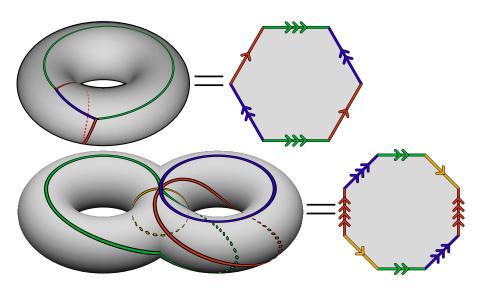


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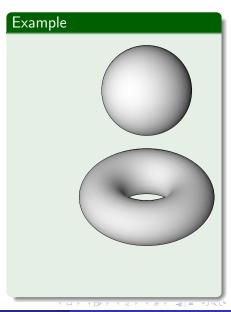
Other Surfaces are Also Obtained by Surgery



Graphs, Surfaces, and Maps

Definition

A surface is a compact 2-manifold without boundary.



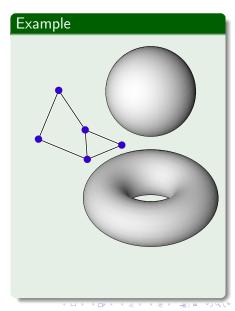
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A graph is a finite set of *vertices* together with a finite set of edges, such that each edge is associated with either one or two vertices.



Graphs, Surfaces, and Maps

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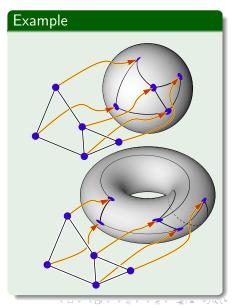
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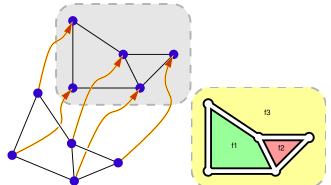
Definition

A map is a 2-cell embedding of a graph in a surface.



Maps and Faces

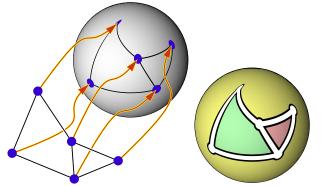
Once a graph is drawn, the unused portion of the paper is split into faces.



A map is a graph together with an embedding in a surfaces. It is defined by its vertices, edges, and faces.

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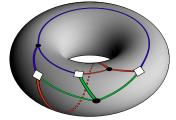


For symmetry, the outer face is thought of as part of a sphere.

A map is a graph together with an embedding in a surfaces. It is defined by its vertices, edges, and faces.

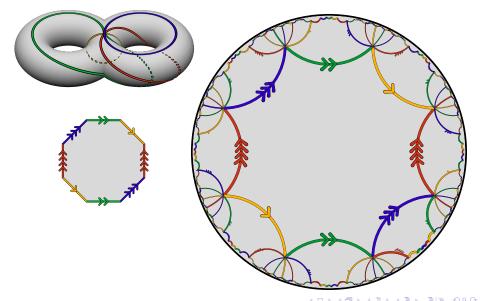
Tiling the Representation

The faces of a map can be made more evident by tessellating the tile that represents the surface.





Tiling the Representation

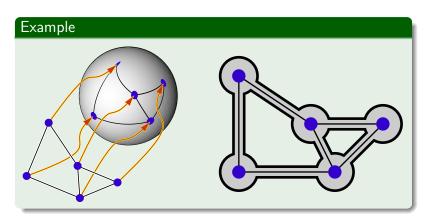


Outline

- Rooted Maps and Flags
- - Orientable Maps
 - Non-Orientable Maps
 - Hypermaps
 - Generating Series
- What does Jack have to do with it?
 - The invariants resolve a special case

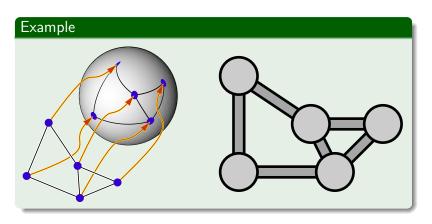


Ribbon Graphs



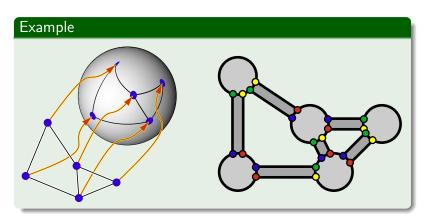
The homeomorphism class of an embedding is determined by a neighbourhood of the graph.

Ribbon Graphs



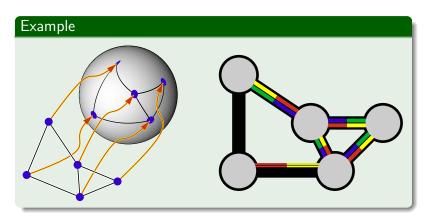
Neighbourhoods of vertices and edges can be replaced by discs and ribbons to form a ribbon graph.

Flags



The boundaries of ribbons determine flags.

Flags

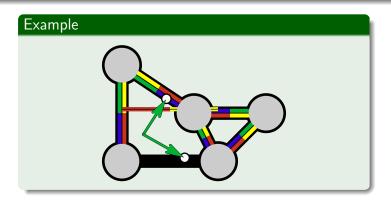


The boundaries of ribbons determine flags, and these can be associated with quarter edges.

Rooted Maps

Definition

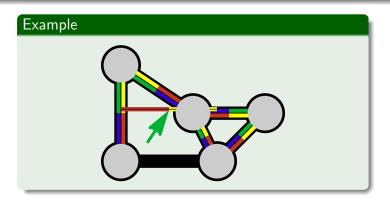
A rooted map is a map together with a distinguished orbit of flags under the action of its automorphism group.



Rooted Maps

Definition

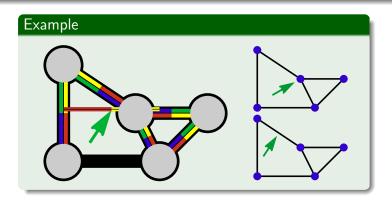
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A **rooted map** is a map together with a distinguished orbit of flags under the action of its automorphism group.



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Two models of 2-dimensional quantum gravity are analyzed by enumerating rooted orientable maps.

- The Penner Model involves all smooth maps.
- \bullet ϕ 4 model involves only 4-regular maps.

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The models have the same behaviour.

An algebraic explanation - A remarkable identity

Theorem (Jackson and Visentin)

$$Q(u^{2}, x, y, z) = \frac{1}{2}M(4u^{2}, y + u, y, xz^{2}) + \frac{1}{2}M(4u^{2}, y - u, y, xz^{2})$$

$$= bis_{even\ u}\ M(4u^{2}, y + u, y, xz^{2})$$

M is the genus series for rooted orientable maps, and Q is the corresponding series for 4-regular maps.

$$M(u^{2}, x, y, z) := \sum_{\mathfrak{m} \in \mathcal{M}} u^{2g(\mathfrak{m})} x^{v(\mathfrak{m})} y^{f(\mathfrak{m})} z^{e(\mathfrak{m})}$$

$$Q(u^2, x, y, z) := \sum_{\mathfrak{m} \in \mathbb{Q}} u^{2g(\mathfrak{m})} x^{v(\mathfrak{m})} y^{f(\mathfrak{m})} z^{e(\mathfrak{m})}$$

 $g(\mathfrak{m}), v(\mathfrak{m}), f(\mathfrak{m}), \text{ and } e(\mathfrak{m}) \text{ are genus, } \#\text{vertices, } \#\text{faces, and } \#\text{edges}$

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$$= bis_{even\ u}\ M(4u^{2}, y + u, y, xz^{2})$$

The right hand side is a generating series for a set $\bar{\mathcal{M}}$ consisting of elements of \mathcal{M} with

- each handle decorated independently in one of 4 ways, and
- an even subset of vertices marked.

An algebraic explanation - A remarkable identity

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q-Conjecture (Jackson and Visentin)

The identity is explained by a **natural** bijection ϕ from $\overline{\mathcal{M}}$ to \mathcal{Q} .

A decorated map with

- v vertices
- 2k marked vertices
- e edges
- f faces
- genus q

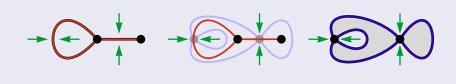


A 4-regular map with

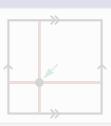
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- 2e edges
- f + v 2k faces
- genus q + k

Two Clues

The radial construction for undecorated maps

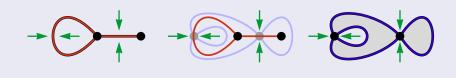






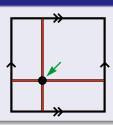
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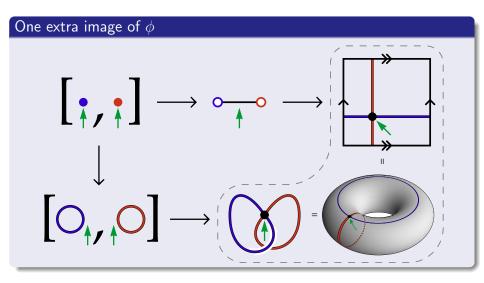


One extra image of ϕ





Two Clues



A refined q-Conjecture

Conjecture (La Croix)

There is a natural bijection ϕ from $\overline{\mathcal{M}}$ to \mathcal{Q} such that:

A decorated map with

- v vertices
- 2k marked vertices
- e edges
- f faces
- genus q



A 4-regular map with

- e vertices
- 2e edges
- f + v 2k faces
- genus q + k

and

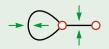
the root edge of $\phi(\mathfrak{m})$ is face-separating

if and only if

the root vertex of m is not decorated.

Root vertices in $\overline{\mathcal{M}}$ are related to root edges in \mathcal{Q}

Example (planar maps with 2 edges and 2 decorated vertices)



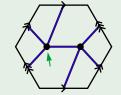


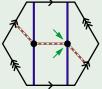


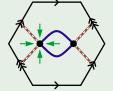


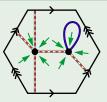
Nine of eleven rooted maps have a decorated root vertex.

Example (4-regular maps on the torus with two vertices)









Nine of fifteen rooted maps have face-non-separating root edges.

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The Map Series

Extra symmetry makes it easier to work with a more refined series.

An enumerative problem associated with maps is to determine the number of rooted maps with specified vertex- and face- degree partitions.

Definition

The map series for a set \mathcal{M} of rooted maps is the combinatorial sum

$$M(\mathbf{x}, \mathbf{y}, z) := \sum_{\mathbf{m} \in \mathcal{M}} \mathbf{x}^{\nu(\mathbf{m})} \mathbf{y}^{\phi(\mathbf{m})} z^{|E(\mathbf{m})|}$$

where $\nu(\mathfrak{m})$ and $\phi(\mathfrak{m})$ are the the vertex- and face-degree partitions of \mathfrak{m} .





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Example

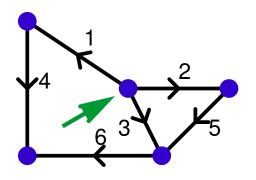
Rootings of



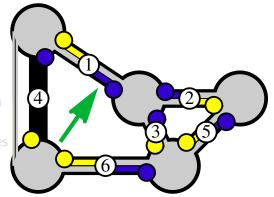
are enumerated by $(\mathbf{z_2^3} \mathbf{z_3^2}) (\mathbf{y_3} \mathbf{y_4} \mathbf{y_5}) z^6$.

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- Orient and label the edges.



- Orient and label the edges.
- This induces labels on flags.
- Face circulations are the cycles

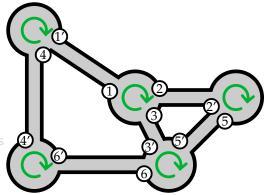


$$\epsilon = (1 \ 1')(2 \ 2')(3 \ 3')(4 \ 4')(5 \ 5')(6 \ 6')$$

$$\nu = (1 \ 2 \ 3)(1' \ 4)(2' \ 5)(3' \ 5' \ 6)(4' \ 6')$$

$$\epsilon \nu = \phi = (1 \ 4 \ 6' \ 3')(1' \ 2 \ 5 \ 6 \ 4')(2' \ 3 \ 5')$$

- Orient and label the edges.
- This induces labels on flags.
- Clockwise circulations at each vertex determine ν .

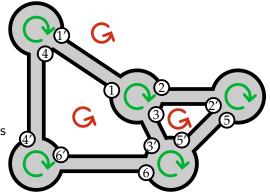


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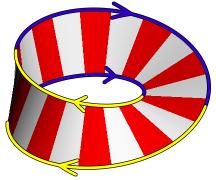
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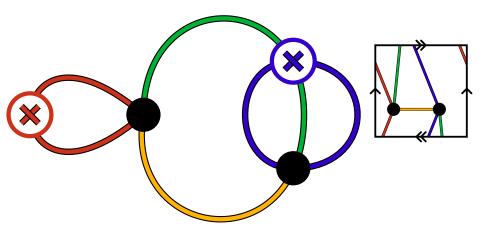
A Möbius Strip

Maps can also be drawn in surfaces that contain Möbius strips.



Encoding Locally Orientable Maps

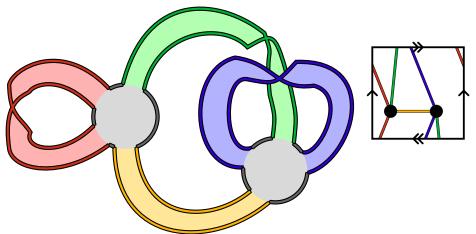
A new encoding is needed to record twisting.



Start with a ribbon graph.

Encoding Locally Orientable Maps

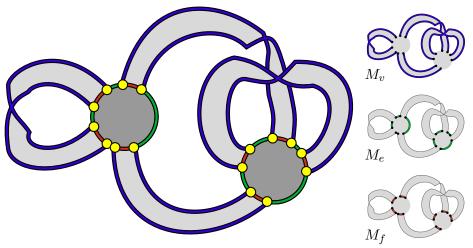
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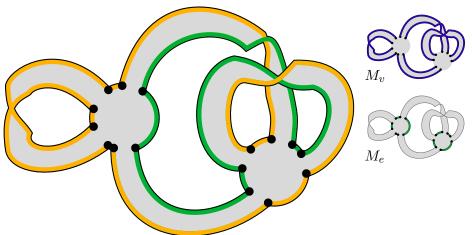
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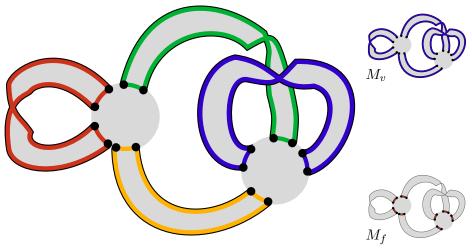
Ribbon boundaries determine 3 perfect matchings of flags.

A new encoding is needed to record twisting.



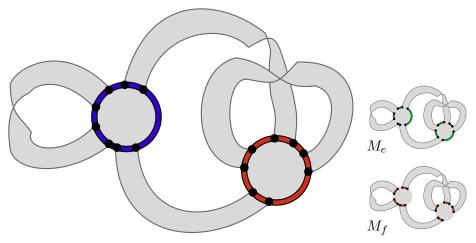
Pairs of matchings determine, faces,

A new encoding is needed to record twisting.

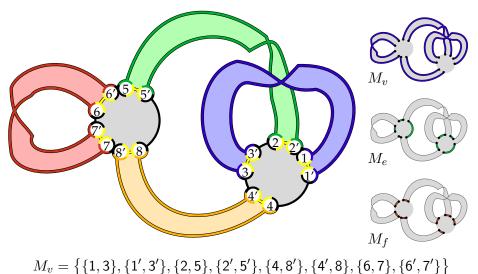


Pairs of matchings determine, faces, edges,

A new encoding is needed to record twisting.



Pairs of matchings determine, faces, edges, and vertices.



 $M_v = \{\{1, 3\}, \{1, 4\}, \{2, 3\}, \{2, 5\}, \{1, 6\}, \{1, 6\}, \{1, 7\}, \{0, 7\}\}\}$ $M_e = \{\{1, 2'\}, \{1', 4\}, \{2, 3'\}, \{3, 4'\}, \{5, 6'\}, \{5', 8\}, \{6, 7'\}, \{7, 8'\}\}\}$

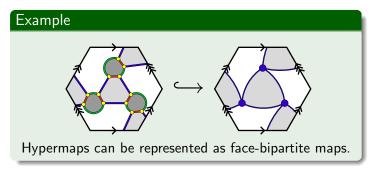
Michael La Croix (University of Waterloo) The Jack parameter and Map Enumeration

February 15, 2011 25

Hypermaps

Generalizing the combinatorial encoding, an arbitrary triple of perfect matchings determines a hypermap when the triple induces a connected graph, with cycles of $M_e \cup M_f$, $M_e \cup M_v$, and $M_v \cup M_f$ determining vertices, hyperfaces, and hyperedges. • Example

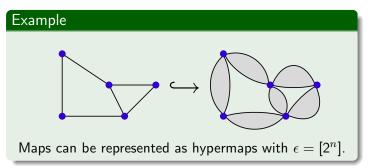
Hypermaps both **specialize** and generalize maps.



Hypermaps

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Hypermaps both specialize and generalize maps.



The Hypermap Series

Definition

The hypermap series for a set \mathcal{H} of hypermaps is the combinatorial sum

$$H(\mathbf{x}, \mathbf{y}, \mathbf{z}) := \sum_{\mathfrak{h} \in \mathcal{H}} \mathbf{x}^{\nu(\mathfrak{h})} \mathbf{y}^{\phi(\mathfrak{h})} \mathbf{z}^{\epsilon(\mathfrak{h})}$$

where $\nu(\mathfrak{h})$, $\phi(\mathfrak{h})$, and $\epsilon(\mathfrak{h})$ are the vertex-, hyperface-, and hyperedgedegree partitions of h. Example

$$M(\mathbf{x}, \mathbf{y}, z) = H(\mathbf{x}, \mathbf{y}, \mathbf{z})\Big|_{z_i = z\delta_{i,2}}$$

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Note

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- Instead of counting rooted maps, we can count labelled hypermaps. The numbers are different, but the correction factor is easy.
- Labelled counting problems are turned into problems involving
- These can be answered via character theory.
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Explicit Formulae

The hypermap series can be computed explicitly when ${\cal H}$ consists of all orientable or locally orientable hypermaps.

Theorem (Jackson and Visentin)

When \mathcal{H} is the set of orientable hypermaps,

$$H\Big(p(\mathbf{x}), p(\mathbf{y}), p(\mathbf{z}); 0\Big) = \left. t \frac{\partial}{\partial t} \ln \left(\sum_{\theta \in \mathscr{P}} H_{\theta} s_{\theta}(\mathbf{x}) s_{\theta}(\mathbf{y}) s_{\theta}(\mathbf{z}) \right) \right|_{t=0.}$$

Theorem (Goulden and Jackson)

When ${\cal H}$ is the set of locally orientable hypermaps,

$$H\Big(p(\mathbf{x}),p(\mathbf{y}),p(\mathbf{z});1\Big) = \left.2t\frac{\partial}{\partial t}\ln\left(\sum_{\theta\in\mathscr{P}}\frac{1}{H_{2\theta}}Z_{\theta}(\mathbf{x})Z_{\theta}(\mathbf{y})Z_{\theta}(\mathbf{z})\right)\right|_{t=0}.$$

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Outline

- - Orientable Maps
 - Non-Orientable Maps
 - Hypermaps
 - Generating Series
- What does Jack have to do with it?
 - The invariants resolve a special case



Parallel Problems

We started with two similar problems, applied similar techniques, and found similar looking solutions.

The natural question is, "Could we have solved both problems at once?"

Jack Symmetric Functions

Jack symmetric functions, pefinition, are a one-parameter family, denoted by $\{J_{\theta}(\alpha)\}_{\theta}$, that generalizes both Schur functions and zonal polynomials.

Proposition (Stanley)

Jack symmetric functions are related to Schur functions and zonal polynomials by:

$$J_{\lambda}(1) = H_{\lambda} s_{\lambda},$$
 $\langle J_{\lambda}, J_{\lambda} \rangle_{1} = H_{\lambda}^{2},$

$$J_{\lambda}(2) = Z_{\lambda},$$
 and $\langle J_{\lambda}, J_{\lambda} \rangle_{2} = H_{2\lambda},$

where 2λ is the partition obtained from λ by multiplying each part by two.

A Generalized Series

b-Conjecture (Goulden and Jackson)

The generalized series,

$$egin{aligned} H\Big(p(\mathbf{x}),p(\mathbf{y}),p(\mathbf{z});b\Big) \ &:= (1+b)trac{\partial}{\partial t}\ln\left(\sum_{ heta\in\mathscr{P}}rac{J_{ heta}(\mathbf{x};1+b)J_{ heta}(\mathbf{y};1+b)J_{ heta}(\mathbf{z};1+b)}{\langle J_{ heta},J_{ heta}
angle_{1+b}}
ight)igg|_{t=0} \ &= \sum_{n\geq 0}\sum_{
u,\phi,\epsilon\vdash n}c_{
u,\phi,\epsilon}(b)p_{
u}(\mathbf{x})p_{\phi}(\mathbf{y})p_{\epsilon}(\mathbf{z}), \end{aligned}$$

has an combinatorial interpretation involving hypermaps. In particular $c_{\nu,\phi,\epsilon}(b) = \sum b^{\beta(\mathfrak{h})}$ for some invariant β of rooted hypermaps. heHude

b is ubiquitous

The many lives of b			
	b = 0		b = 1
Hypermaps	Orientable	?	Locally Orientable
Symmetric Functions	$s_{ heta}$	$J_{\theta}(b)$	$Z_{ heta}$
Matrix Integrals	Hermitian	?	Real Symmetric
Moduli Spaces	over $\mathbb C$?	over $\mathbb R$
Matching Systems	Bipartite	?	All

The b-Conjecture assumes that $c_{\nu,\phi,\epsilon}(b)$ is a polynomial, and numerical evidence suggests that its degree is the genus of the hypermaps it enumerates. A b-invariant must:



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Example

Rootings of precisely three maps are enumerated by $c_{[4],[4],[2^2]}(b) = 1 + b + 3b^2$.

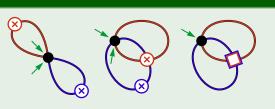


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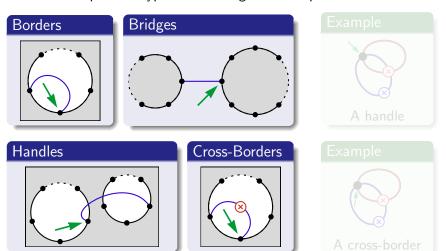
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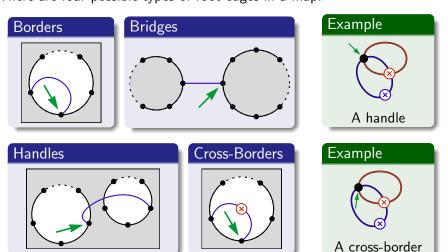
A root-edge classification

There are four possible types of root edges in a map.



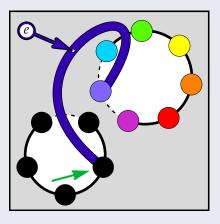
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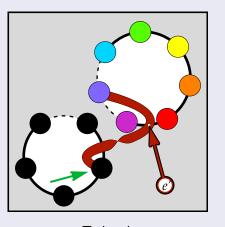
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A root-edge classification

Handles occur in pairs





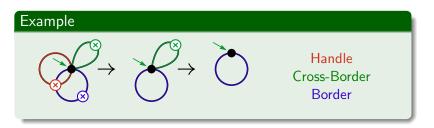
Untwisted

Twisted

A family of invariants

The invariant η

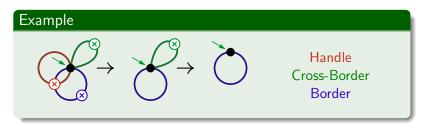
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- Different handle twisting determines a different invariant.



A family of invariants

The invariant η

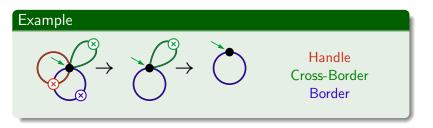
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Theorem (La Croix)

If ϕ partitions 2n and η is a member of the family of invariants then,

$$d_{v,\phi}(b) := \sum_{\ell(\nu)=v} c_{\nu,\phi,[2^n]}(b) = \sum_{\mathfrak{m}\in\mathcal{M}_{v,\phi}} b^{\eta(\mathfrak{m})}.$$

- Distinguish between root and non-root faces in the generating series.
- Show that this series satisfies a PDE with a unique solution.
- Predict an expression for the corresponding algebraic refinement.
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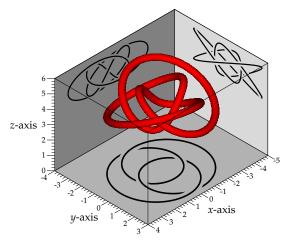
Root-edge type	Schematic	Contribution to M
Cross-border		$z\sum_{i\geq 0}(i+1)br_{i+2}\frac{\partial}{\partial r_i}M$
Border		$z \sum_{i \ge 0} \sum_{j=1}^{i+1} r_j y_{i-j+2} \frac{\partial}{\partial r_i} M$
Handle		$z\sum_{i,j\geq 0} (1+b)jr_{i+j+2} \frac{\partial^2}{\partial r_i \partial y_j} M$
Bridge		$z \sum_{i,j \ge 0} r_{i+j+2} \left(\frac{\partial}{\partial r_i} M \right) \left(\frac{\partial}{\partial r_j} M \right)$

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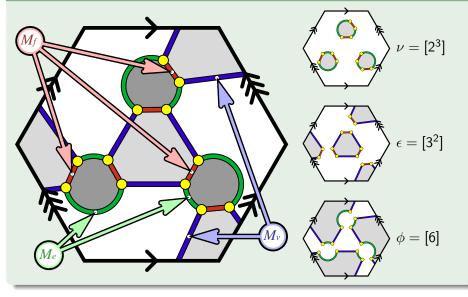
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The End

Thank You

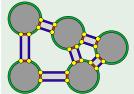
Example



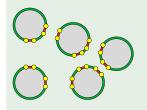


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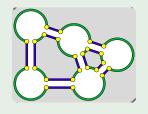
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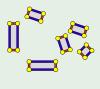
is enumerated by $(x_2^3 x_3^2) (y_3 y_4 y_5) (z_2^6)$.



$$\nu = [2^3, 3^2]$$



$$\phi = [3, 4, 5]$$



$$\epsilon = [2^6]$$

Jack Symmetric Functions

With respect to the inner product defined by

$$\langle p_{\lambda}(\mathbf{x}), p_{\mu}(\mathbf{x}) \rangle = \delta_{\lambda,\mu} \frac{|\lambda|!}{|C_{\lambda}|} \alpha^{\ell(\lambda)},$$

Jack symmetric functions are the unique family satisfying:

- (P1) (Orthogonality) If $\lambda \neq \mu$, then $\langle J_{\lambda}, J_{\mu} \rangle_{\alpha} = 0$.
- (P2) (Triangularity) $J_{\lambda} = \sum_{\mu \preccurlyeq \lambda} v_{\lambda\mu}(\alpha) m_{\mu}$, where $v_{\lambda\mu}(\alpha)$ is a rational function in α , and ' \preccurlyeq ' denotes the natural order on partitions.
- (P3) (Normalization) If $|\lambda| = n$, then $v_{\lambda,[1^n]}(\alpha) = n!$.

◆ Return