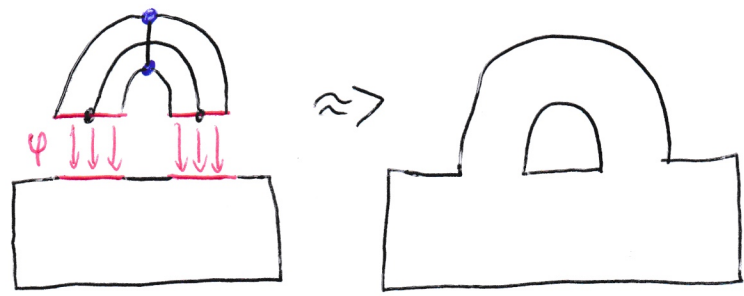


Handles II: Handle Decompositions

Last time: Defined handles $h^k \cong D^k \times D^{n-k} \sim k\text{-cell}$
 $k = \text{index}$, $n = \text{dimension}$.

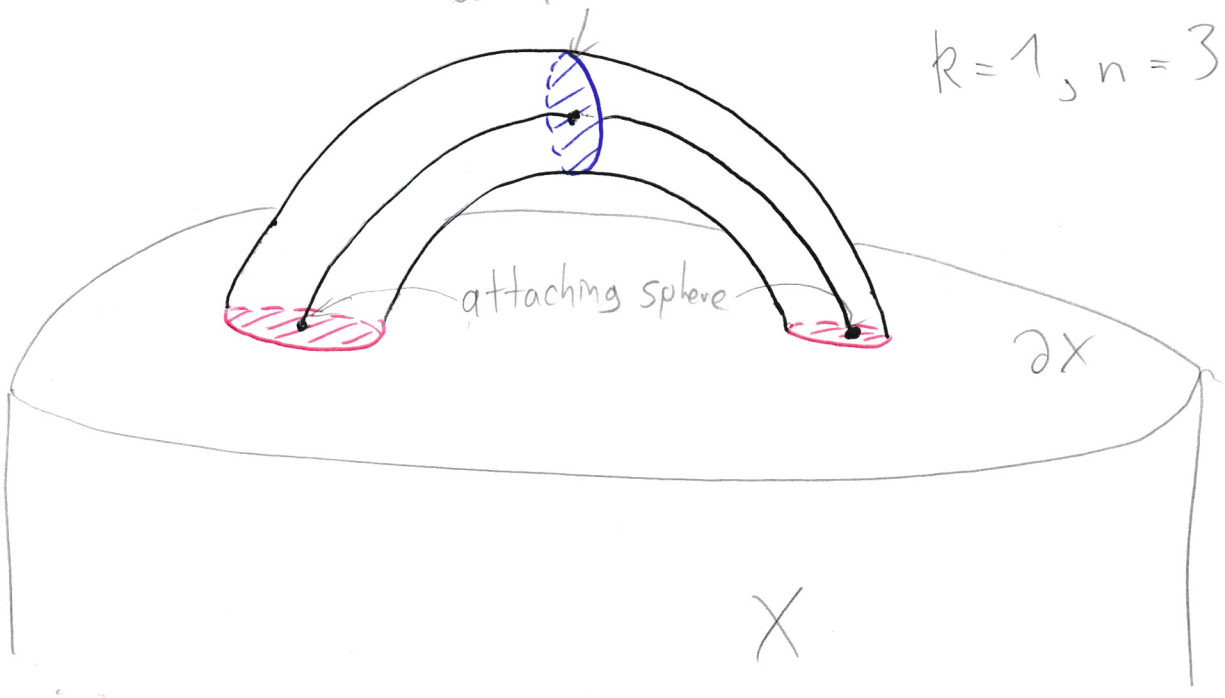
- Attaching handles to the (possibly empty) boundary of a manifold X^n :
 choosing an embedding $\psi: S^{k-1} \times D^{n-k} \hookrightarrow \partial X$ (codim 0)

Form $X \cup_{\psi} h^k$:



belt sphere

$k=1, n=3.$



Today

- I) Handlebodies and Handle Decompositions.
- II) Handle Decompositions Exist.
- III) Simplifying Handle Decompositions.
- ?) Example: $\mathbb{C}P^4$

Will assume all manifolds are compact.

Recall: Transversality

$$X \xrightarrow{f} Z \xleftarrow{g} Y$$

f, g are transverse ($f \pitchfork g$) if

$$\forall x \in X \forall y \in Y \quad f(x) = g(y) \Rightarrow f_* T_x X + g_* T_y Y = T_{f(x)} Z$$

Suppose f, g are embeddings, and $f \pitchfork g$.

$$\Rightarrow \dim(X \cap Y) = \dim X + \dim Y - \dim Z.$$

• If $\dim X + \dim Y = \dim Z$, $\dim(X \cap Y) = 0$.

• If $\dim X + \dim Y < \dim Z$, $X \cap Y = \emptyset$.

§ I. Handlebodies and Handle Decompositions

Def

Let Y^{n-1} be closed (and possibly empty).

- Say a relative handlebody built on Y is a manifold of the form

$$(Y \times I) \cup_{\psi_1} h_1^{k_1} \cup \dots \cup_{\psi_m} h_m^{k_m}$$

where we interpret the union by attaching the $(i+1)$ -st handle to $(Y \times I) \cup_{j=1}^i h_j^{k_j} \setminus (Y \times \{0\})$

If $Y = \emptyset$ we just call it a handlebody.

Note: If $Y = \emptyset$, the first handle attachment must be a 0-handle, since the attaching region is $(\partial D^0) \times D^n = \emptyset$.

- Let X^n be a manifold with $\partial X = \partial_+ X \sqcup \overline{\partial_- X}$.

A handle decomposition of X is a diffeomorphism

$$X \cong_{\partial_- X} Z$$

where Z is a relative handlebody built on $\partial_- X$.

II) Handle Decompositions Exist.

Morse Theory

(good reference: Milnor, 1963)

Idea: Non-degenerate critical points of smooth functions tell us about topological changes.

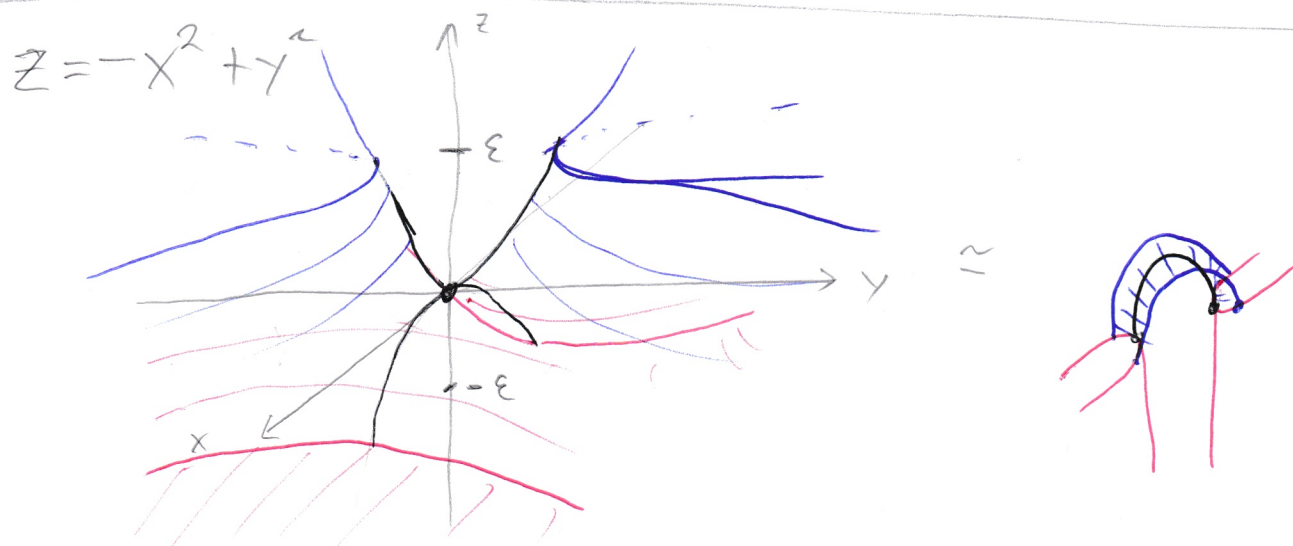
Morse Lemma

Let $f: X^n \rightarrow \mathbb{R}$ be smooth, and let $p \in X$ be a non-degenerate critical point, i.e. has a non-singular Hessian.

Then there is a chart $\psi: U \hookrightarrow X^n$ with $\psi(0) = p$ s.t.

$$\forall (x_1, \dots, x_n) \in U \quad f \circ \psi(x_1, \dots, x_n) = f(p) + \sum_{i=1}^k -x_i^2 + \sum_{i=k+1}^n x_i^2$$

(We call k the index of p).

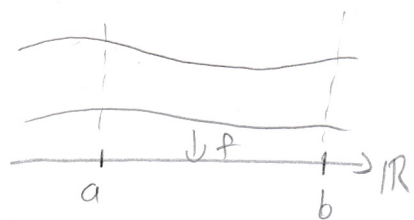


Def $f: X \rightarrow \mathbb{R}$ is Morse if all its critical points are non-degenerate.

Theorems

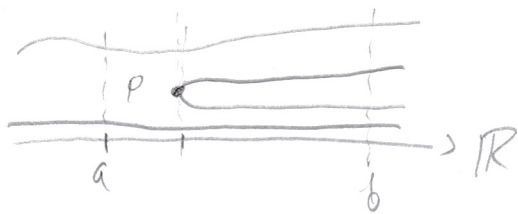
Say $f: X \rightarrow \mathbb{R}$ is smooth, $a < b \in \mathbb{R}$.

If $f^{-1}[a, b]$ contains no critical points then $X_a \cong X_b$,
and X_b deformation retracts onto X_a .



Now suppose $f^{-1}[a, b]$ contains a unique critical point $p \in f^{-1}(a, b)$, of index k .

Then $X_b \cong X_a \cup h^k$.



Morse functions are dense in $C(X, \mathbb{R})$

Corollary

Smooth manifolds have handle decompositions.

III) Simplifying Handle Decompositions.

Proposition 4.27

A handle decomposition can be modified so that handles of index k are added before handles of index $k' > k$. Handles of the same index can be attached in any order, or simultaneously. (Let $X_k = (2X \times I) \cup \{ \text{handles with index } \leq k \}$)

PF | Suppose we have handles $h^k, h^{k'} \quad k' \geq k$.

Suppose $h^{k'}$ is already attached. Its belt sphere has dimension $n - k' - 1$.

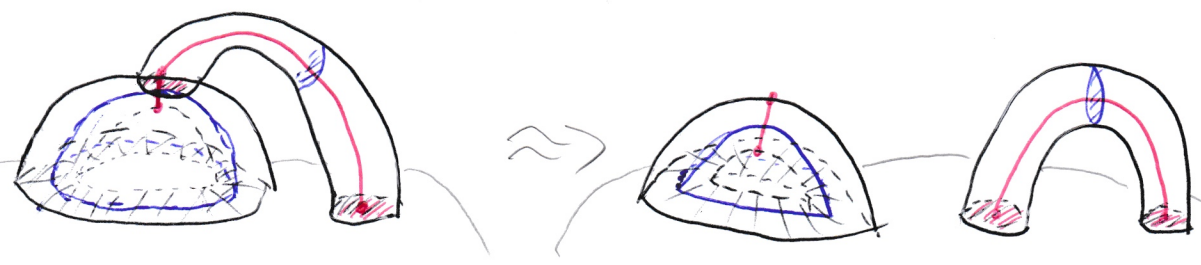
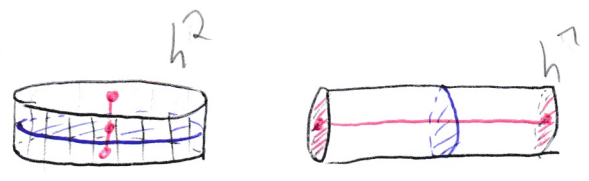
The attaching sphere of h^k has dimension $k - 1$.

Notice

$$(n - k' - 1) + (k - 1) = n - (k' - k) - 2 \leq n - 2 < n - 1.$$

∴ Transversality means we can isotope the attaching map so these spheres are disjoint, and from there we can make the attaching region of h^k disjoint from $h^{k'}$ altogether.

E.g. $n=3, k=1, k'=2$.



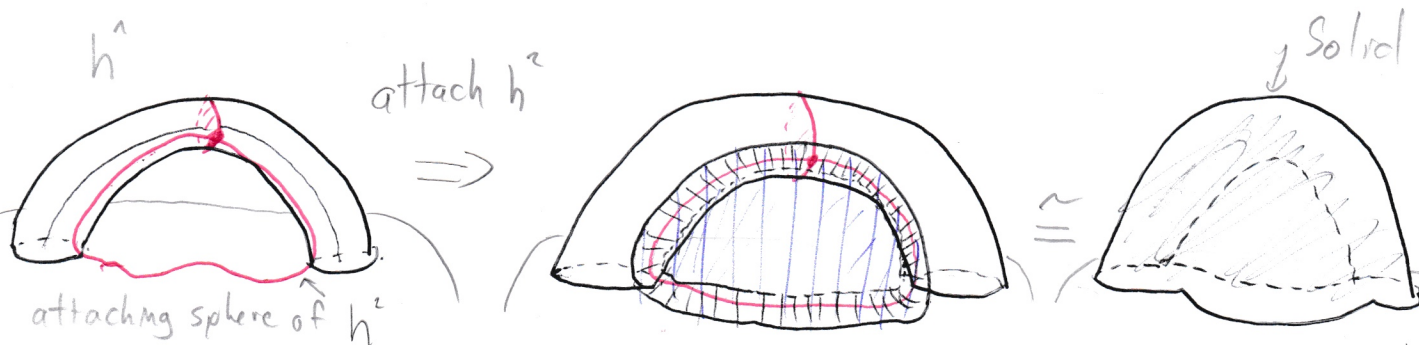
Handle Cancellation

Let h^{k-1}, h^k be $(k-1)$ - and k -handles respectively, $1 \leq k \leq n$.

Suppose we attach h^{k-1} and then h^k to ∂Y so that the attaching sphere of h^k intersects the belt sphere of h^{k-1} transversely at 1 point.

Then $Y \cup h^{k-1} \cup h^k \cong Y$.

PF



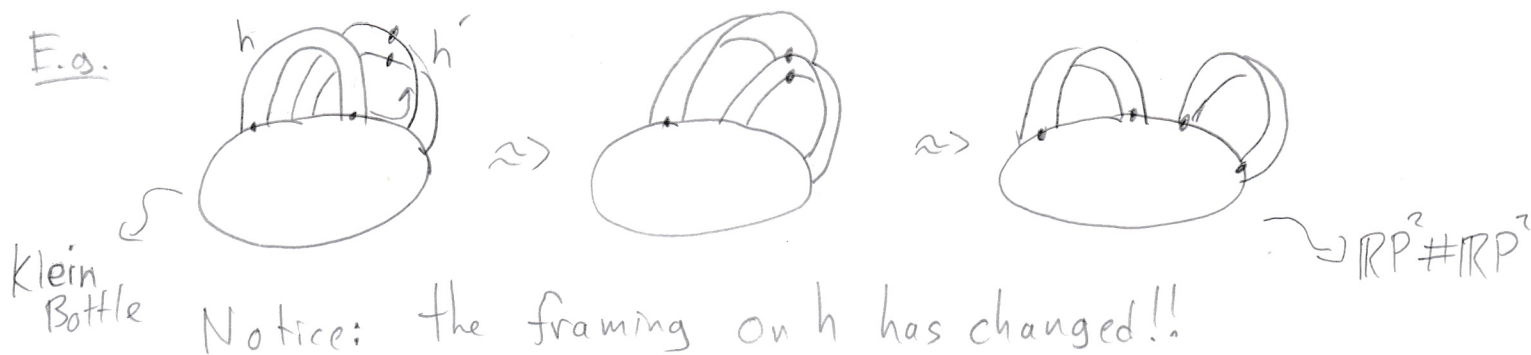
Defⁿ: Handle Slide

Say h, h' are two handles, disjointly attached to ∂Y .

Suppose they both have index k , $0 < k < n$.

We handle slide h by isotoping its attaching sphere to pass through the belt sphere of h' .

E.g.



Notice: the framing on h has changed!!

Theorem (Cerf)

This is a sufficient set of moves.

That is, given two handle decompositions of $(X, \partial_- X)$, there is a sequence of

- handle slides
- handle pair creation/cancellation
- isotopies within levels

taking one decomposition to the other.

Continuing to simplify:

Proposition

If X^n is compact and connected, then

- If $\partial_- X = \emptyset$, X has a handle decomp with 1 0-handle
- If $\partial_- X \neq \emptyset$, " " " 0 0-handles

Similarly

- If $\partial_+ X = \emptyset$, we can assume 1 n -handle
- If $\partial_+ X \neq \emptyset$, " " 0 n -handles

Proof / If $\partial_- X = \emptyset$ there must be at least one 0-handle.

If there are more than one, they must be connected by a 1-handle, since h^k $k > 1$ has a connected attaching sphere.

But we can cancel one of the 0-handles with the 1-handle, and proceed by induction.

What about the "similarly" part?

Dual Handle Decompositions

Given a relative handlebody built on $\partial_- X$, we can dualize each handle $h^k \cong D^k \times D^{n-k} = D^k \times D^{n-k} \cong h_{n-k}$ and attach them in reverse order to $\overline{\partial_+ X}$.

The belt sphere of h^k becomes the attaching sphere of h_{n-k} and vice-versa.

In terms of Morse functions, if our handle decomposition is induced by $f: X \rightarrow [0, 1]$ then the dual is induced by $\tilde{f}(x) = 1 - f(x)$.

Now we can finish the proof of the proposition by applying the argument to the dual decomposition.

Example $\mathbb{C}P^2$

Standard charts $\gamma_i: \mathbb{C}^2 \rightarrow \mathbb{C}P^2$ position i
 $(z_1, z_2) \mapsto [z_1: \dots: 1: \dots: z_2]$

Fix $D = \{z \in \mathbb{C} \mid |z| \leq 1\}$, and let $B_i = \gamma_i(D \times D)$.

Idea: B_0, B_1, B_2 are the 0-, 2-, and 4-handle of our decomposition.

For $p \in \mathbb{C}P^2$, write $p = [z_0: z_1: z_2]$ where $\max_i |z_i| = 1$.

Then 1) $p \in B_i$ iff $|z_i| = 1$

2) $p \in \text{int} B_i$ iff $|z_j| < 1$ for $j \neq i$.

i.o. They intersect along points where multiple coordinates have norm 1.

If $p \in B_0 \cap B_1$, we can write

$$p = [1: w_1: w_2] = [z_1: 1: z_2]$$

$$\Rightarrow w_1 = z_1^{-1} \text{ and } w_2 = z_1^{-1} z_2$$

B_1 intersects B_0 at $\gamma_1(\partial D \times D)$ where $\partial D \times D \cong S^1 \times D^2 \subset \partial D^3$

So we can view B_1 as a 2-handle attached to B_0 via

$$\varphi: S^1 \times D^2 \hookrightarrow \partial B_0$$

$$(z_1, z_2) \mapsto [1: z_1^{-1}: z_1^{-1} z_2]$$

Viewing $S^1 \times D^2$ as a disk bundle, Ψ preserves the fibres.

If we traverse the S^1 factor via $z_1 = e^{2\pi i t}$, then our disk coordinate is sent to $e^{-2\pi i t} z_2$.

$\approx \Rightarrow$ this rotates the fibres once realizing a generator of $\pi_1(O(2)) \cong \mathbb{Z}$.

$\Rightarrow \therefore B_0 \cup B_1$ is a disc bundle over S^2 with Euler class $+1$.

The boundary is then the circle-bundle over S^2 with Euler class $+1$.

But attaching $B_2 \cong D^4 \times D^0$ results in a closed manifold, so we must have $\partial(B_0 \cup B_1) \cong S^3$.

$\approx \Rightarrow$ Have a bundle $S^1 \hookrightarrow S^3 \twoheadrightarrow S^2$,

the Hopf fibration.