

**ALMOST COMPLEX MANIFOLDS – ASSIGNMENT 2 SOLUTIONS**

**1. Let  $(M, J)$  be an almost complex manifold and set  $N_J(X, Y) = [X, Y] + J[JX, Y] + J[X, JY] - [JX, JY]$ . Show the following:**

- (a)  $N_J(X, Y) = -N_J(Y, X)$ ,
- (b)  $N_J(JX, Y) = -JN_J(X, Y)$ , and
- (c)  $N_J(fX, Y) = fN_J(X, Y)$  for  $f \in C^\infty(M)$ .

*Solution:* (a)

$$\begin{aligned}
 N_J(X, Y) &= [X, Y] + J[JX, Y] + J[X, JY] - [JX, JY] \\
 &= -[Y, X] - J[Y, JX] - J[JY, X] + [JY, JX] \\
 &= -[Y, X] - J[JY, X] - J[Y, JX] + [JY, JX] \\
 &= -([Y, X] + J[JY, X] + J[Y, JX] - [JY, JX]) \\
 &= -N_J(Y, X).
 \end{aligned}$$

(b)

$$\begin{aligned}
 N_J(JX, Y) &= [JX, Y] + J[J(JX), Y] + J[JX, JY] - [J(JX), JY] \\
 &= [JX, Y] - J[X, Y] + J[JX, JY] + [X, JY] \\
 &= -J(J[JX, Y] + [X, Y] - [JX, JY] + J[X, JY]) \\
 &= -J([X, Y] + J[JX, Y] + J[X, JY] - [JX, JY]) \\
 &= -JN_J(X, Y).
 \end{aligned}$$

(c)

$$\begin{aligned}
 N_J(fX, Y) &= [fX, Y] + J[J(fX), Y] + J[fX, JY] - [J(fX), JY] \\
 &= [fX, Y] + J[fJX, Y] + J[fX, JY] - [fJX, JY] \\
 &= f[X, Y] - Y(f)X + J(f[JX, Y] - Y(f)JX) + J(f[X, JY] - (JY)(f)X) \\
 &\quad - f[JX, JY] + (JY)(f)JX \\
 &= f[X, Y] - Y(f)X + fJ[JX, Y] + Y(f)X + fJ[X, JY] - (JY)(f)JX \\
 &\quad - f[JX, JY] + (JY)(f)JX \\
 &= f[X, Y] + fJ[JX, Y] + fJ[X, JY] - f[JX, JY] \\
 &= fN_J(X, Y).
 \end{aligned}$$

**2. Consider the almost complex structure  $J$  on  $\mathbb{R}^4$  given by**

$$J = \begin{bmatrix} 0 & 1 & f & -g \\ -1 & 0 & g & f \\ 0 & 0 & 0 & -1 \\ 0 & 0 & 1 & 0 \end{bmatrix}$$

where  $f, g \in C^\infty(\mathbb{R}^4)$ .

- (a) Compute the Nijenhuis tensor of  $J$ . That is, compute  $N_J \left( \frac{\partial}{\partial x^j}, \frac{\partial}{\partial x^k} \right)$  for  $j, k \in \{1, 2, 3, 4\}$ .
- (b) For  $a, b \in \mathbb{R}$ , consider the function  $h : \mathbb{C} \rightarrow \mathbb{C}$  given by  $h_{a,b}(z) = f(x, y, a, b) + ig(x, y, a, b)$  where  $z = x + iy$ . Show that  $J$  is integrable if and only if  $h_{a,b}$  is holomorphic for all  $a, b \in \mathbb{R}$ .

*Solution:* (a) Denote  $\frac{\partial}{\partial x^j}$  by  $\partial_j$ .

By skew-symmetry, namely 1(a), we only have to calculate  $N_J(\partial_j, \partial_k)$  for  $1 \leq j < k \leq 4$ . In addition, by 1(b) we have  $N_J(\partial_1, \partial_k) = N_J(J\partial_2, \partial_k) = -JN_J(\partial_2, \partial_k)$ , so we only need to calculate  $N_J(\partial_j, \partial_k)$  for  $2 \leq j < k \leq 4$ , i.e.  $(j, k) \in \{(2, 3), (2, 4), (3, 4)\}$ . Using the fact that  $[\partial_j, \partial_k] = 0$  and  $[hX, Y] = h[X, Y] - Y(h)X$  (and hence  $[X, hY] = h[X, Y] + X(h)Y$  and  $[h_1X, h_2Y] = h_1h_2[X, Y] + h_1X(h_2)Y - h_2Y(h_1)X$ ), we have

$$\begin{aligned}
N_J(\partial_2, \partial_3) &= [\partial_2, \partial_3] + J[J\partial_2, \partial_3] + J[\partial_2, J\partial_3] - [J\partial_2, J\partial_3] \\
&= J[\partial_1, \partial_3] + J[\partial_2, f\partial_1 + g\partial_2 + \partial_4] - [\partial_1, f\partial_1 + g\partial_2 + \partial_4] \\
&= J[\partial_2, f\partial_1] + J[\partial_2, g\partial_2] + J[\partial_2, \partial_4] - [\partial_1, f\partial_1] - [\partial_1, g\partial_2] - [\partial_1, \partial_4] \\
&= J[f\partial_2, \partial_1] + \partial_2(f)\partial_1 + J[g\partial_2, \partial_2] + \partial_2(g)\partial_2 - f[\partial_1, \partial_1] - \partial_1(f)\partial_1 - g[\partial_1, \partial_2] - \partial_1(g)\partial_2 \\
&= \partial_2(f)J\partial_1 + \partial_2(g)J\partial_2 - \partial_1(f)\partial_1 - \partial_1(g)\partial_2 \\
&= -\partial_2(f)\partial_2 + \partial_2(g)\partial_1 - \partial_1(f)\partial_1 - \partial_1(g)\partial_2 \\
&= [\partial_2(g) - \partial_1(f)]\partial_1 - [\partial_1(g) + \partial_2(f)]\partial_2
\end{aligned}$$

$$\begin{aligned}
N_J(\partial_2, \partial_4) &= [\partial_2, \partial_4] + J[J\partial_2, \partial_4] + J[\partial_2, J\partial_4] - [J\partial_2, J\partial_4] \\
&= J[\partial_1, \partial_4] + J[\partial_2, -g\partial_1 + f\partial_2 - \partial_3] - [\partial_1, -g\partial_1 + f\partial_2 - \partial_3] \\
&= -J[\partial_2, g\partial_1] + J[\partial_2, f\partial_2] - J[\partial_2, \partial_3] + [\partial_1, g\partial_1] - [\partial_1, f\partial_2] + [\partial_1, \partial_3] \\
&= -J(g[\partial_2, \partial_1] + \partial_2(g)\partial_1) + J(f[\partial_2, \partial_2] + \partial_2(f)\partial_2) + g[\partial_1, \partial_1] + \partial_1(g)\partial_1 - f[\partial_1, \partial_2] - \partial_1(f)\partial_2 \\
&= -\partial_2(g)J\partial_1 + \partial_2(f)J\partial_2 + \partial_1(g)\partial_1 - \partial_1(f)\partial_2 \\
&= \partial_2(g)\partial_2 + \partial_2(f)\partial_1 + \partial_1(g)\partial_1 - \partial_1(f)\partial_2 \\
&= [\partial_1(g) + \partial_2(f)]\partial_1 + [\partial_2(g) - \partial_1(f)]\partial_2
\end{aligned}$$

$$\begin{aligned}
N_J(\partial_3, \partial_4) &= [\partial_3, \partial_4] + J[J\partial_3, \partial_4] + J[\partial_3, J\partial_4] - [J\partial_3, J\partial_4] \\
&= J[f\partial_1 + g\partial_2 + \partial_4, \partial_4] + J[\partial_3, -g\partial_1 + f\partial_2 - \partial_3] - [f\partial_1 + g\partial_2 + \partial_4, -g\partial_1 + f\partial_2 - \partial_3] \\
&= J[f\partial_1, \partial_4] + J[g\partial_2, \partial_4] + J[\partial_4, \partial_4] - J[\partial_3, g\partial_1] + J[\partial_3, f\partial_2] - J[\partial_3, \partial_3] + [f\partial_1, g\partial_1] \\
&\quad - [f\partial_1, f\partial_2] + [f\partial_1, \partial_3] + [g\partial_2, g\partial_1] - [g\partial_2, f\partial_2] + [g\partial_2, \partial_3] + [\partial_4, g\partial_1] - [\partial_4, f\partial_2] + [\partial_4, \partial_3] \\
&= J(f[\partial_1, \partial_4] - \partial_4(f)\partial_1) + J(g[\partial_2, \partial_4] - \partial_4(g)\partial_2) - J(g[\partial_3, \partial_1] + \partial_3(g)\partial_1) + J(f[\partial_3, \partial_2] \\
&\quad + \partial_3(f)\partial_2) + fg[\partial_1, \partial_1] + f\partial_1(g)\partial_1 - g\partial_1(f)\partial_1 - (f^2[\partial_1, \partial_2] + f\partial_1(f)\partial_2 - f\partial_2(f)\partial_1) \\
&\quad + f[\partial_1, \partial_3] - \partial_3(f)\partial_1 + g^2[\partial_2, \partial_1] + g\partial_2(g)\partial_1 - g\partial_1(g)\partial_2 - (gf[\partial_2, \partial_2] + g\partial_2(f)\partial_2 - f\partial_2(g)\partial_2) \\
&\quad + g[\partial_2, \partial_3] - \partial_3(g)\partial_2 + g[\partial_4, \partial_1] + \partial_4(g)\partial_1 - (f[\partial_4, \partial_2] + \partial_4(f)\partial_2) \\
&= -\partial_4(f)J\partial_1 - \partial_4(g)J\partial_2 - \partial_3(g)J\partial_1 + \partial_3(f)J\partial_2 + f\partial_1(g)\partial_1 - g\partial_1(f)\partial_1 - f\partial_1(f)\partial_2 + f\partial_2(f)\partial_1 \\
&\quad - \partial_3(f)\partial_1 + g\partial_2(g)\partial_1 - g\partial_1(g)\partial_2 - g\partial_2(f)\partial_2 + f\partial_2(g)\partial_2 - \partial_3(g)\partial_2 + \partial_4(g)\partial_1 - \partial_4(f)\partial_2 \\
&= \partial_4(f)\partial_2 - \partial_4(g)\partial_1 + \partial_3(g)\partial_2 + \partial_3(f)\partial_1 + f\partial_1(g)\partial_1 - g\partial_1(f)\partial_1 - f\partial_1(f)\partial_2 + f\partial_2(f)\partial_1 \\
&\quad - \partial_3(f)\partial_1 + g\partial_2(g)\partial_1 - g\partial_1(g)\partial_2 - g\partial_2(f)\partial_2 + f\partial_2(g)\partial_2 - \partial_3(g)\partial_2 + \partial_4(g)\partial_1 - \partial_4(f)\partial_2 \\
&= f\partial_1(g)\partial_1 - g\partial_1(f)\partial_1 - f\partial_1(f)\partial_2 + f\partial_2(f)\partial_1 + g\partial_2(g)\partial_1 - g\partial_1(g)\partial_2 - g\partial_2(f)\partial_2 + f\partial_2(g)\partial_2
\end{aligned}$$

$$\begin{aligned}
&= [f\partial_1(g) - g\partial_1(f) + f\partial_2(f) + g\partial_2(g)]\partial_1 + [-f\partial_1(f) - g\partial_1(g) - g\partial_2(f) + f\partial_2(g)]\partial_2 \\
&= [f(\partial_1(g) + \partial_2(f)) + g(-\partial_1(f) + \partial_2(g))]\partial_1 + [f(-\partial_1(f) + \partial_2(g)) + g(-\partial_1(g) - \partial_2(f))]\partial_2
\end{aligned}$$

Setting  $A = \partial_1(g) + \partial_2(f)$  and  $B = \partial_1(f) - \partial_2(g)$ , we have

$$[N_J(\partial_j, \partial_k)] = \begin{bmatrix} 0 & 0 & A & B \\ 0 & 0 & -B & A \\ -A & B & 0 & fA - gB \\ -B & -A & -fA + gB & 0 \end{bmatrix} \partial_1 + \begin{bmatrix} 0 & 0 & -B & A \\ 0 & 0 & -A & -B \\ B & A & 0 & -fB - gA \\ -A & B & fB + gA & 0 \end{bmatrix} \partial_2.$$

(b) By the Newlander-Nirenberg theorem,  $J$  is integrable if and only if  $N_J = 0$ . By our computation of  $N_J$  in (a), we see that  $N_J = 0$  if and only if  $A = B = 0$ .

Note that

$$\begin{aligned}
\frac{\partial f}{\partial x}(x, y, a, b) &= \frac{\partial}{\partial x}(f(x, y, a, b)) & \frac{\partial g}{\partial x}(x, y, a, b) &= \frac{\partial}{\partial x}(g(x, y, a, b)) \\
\frac{\partial f}{\partial y}(x, y, a, b) &= \frac{\partial}{\partial y}(f(x, y, a, b)) & \frac{\partial g}{\partial y}(x, y, a, b) &= \frac{\partial}{\partial y}(g(x, y, a, b)).
\end{aligned}$$

It follows that  $A(x, y, a, b) = 0$  and  $B(x, y, a, b) = 0$  are precisely the Cauchy-Riemann equations for the real and imaginary parts of  $h_{a,b}$ . Therefore  $h_{a,b}$  is holomorphic for all  $a, b \in \mathbb{R}$  if and only if  $A = B = 0$  which is equivalent to integrability of  $J$ .

**3. Let  $(Y, J)$  be an almost complex manifold with a properly embedded submanifold  $X$  such that  $T_x X \subseteq T_x Y$  is a complex subspace for all  $x \in X$ . Show that  $J$  induces an almost complex structure  $J_X$  on  $X$ , and if  $J$  is integrable, so too is  $J_X$ .**

*Solution:* Let  $i : X \rightarrow Y$  be the inclusion. Then  $i_*(T_x X) \subseteq T_{i(x)} Y = T_x Y$  is a complex subspace. Therefore, if  $v \in T_x X$ , then  $i_*v \in i_*(T_x X)$  and  $J(i_*v) \in i_*(T_x X)$ . Since  $i$  is an embedding,  $i_*$  is injective, so there is a unique  $w \in T_x X$  such that  $J(i_*v) = i_*w$ . We define  $J_X v = w$ , so that  $J(i_*v) = i_*(J_X v)$ . Note that  $i_*(J_X^2 v) = J(i_*(J_X v)) = J^2(i_*v) = -i_*v = i_*(-v)$ , so by the injectivity of  $i_*$ , we have  $J_X^2 = -\text{id}_{T_X}$ , and hence  $J_X$  is an almost complex structure on  $X$ .

Let  $U, V$  be vector fields on  $X$ . Since  $X$  is properly embedded in  $Y$ , we can extend  $U, V$  to vector fields  $\tilde{U}, \tilde{V}$  on  $Y$ . Note that for  $x \in X$ , we have  $i_*U_x = U_{i(x)} = U_x = \tilde{U}_x$ , so  $U$  and  $\tilde{U}$  are  $i$ -related, and similarly for  $V$  and  $\tilde{V}$ . We also have  $i_*(J_X U_x) = J(i_*U_x) = J\tilde{U}_x$ , so  $J_X U$  and  $J\tilde{U}$  are  $i$ -related, as are  $J_X V$  and  $J\tilde{V}$ . So, for any  $x \in X$ , we have

$$\begin{aligned}
i_*N_{J_X}(U, V)_x &= i_*[U, V]_x + i_*J_X[J_X U, V]_x + i_*J_X[U, J_X V]_x - i_*[J_X U, J_X V]_x \\
&= i_*[U, V]_x + Ji_*[J_X U, V]_x + Ji_*[U, J_X V]_x - i_*[J_X U, J_X V]_x \\
&= [\tilde{U}, \tilde{V}]_x + J[J\tilde{U}, \tilde{V}]_x + J[\tilde{U}, J\tilde{V}]_x - [J\tilde{U}, J\tilde{V}]_x \\
&= N_J(\tilde{U}, \tilde{V})_x \\
&= 0.
\end{aligned}$$

Since  $i_*$  is injective, we see that  $N_{J_X}(U, V)_x = 0$ . Since  $U, V$ , and  $x$  were arbitrary,  $N_{J_X} = 0$  and hence  $J_X$  is integrable.

**4. Let  $(M, J)$  be an almost complex manifold.**

(a) Show that  $\bar{\mu}^2 = 0$ .

$$\text{Let } E^{p,q}(M) = H^{p,q}(\mathcal{E}^{\bullet, \bullet}(M), \bar{\mu}) := \frac{\ker(\bar{\mu} : \mathcal{E}^{p,q}(M) \rightarrow \mathcal{E}^{p-1,q+2}(M))}{\text{im}(\bar{\mu} : \mathcal{E}^{p+1,q-2}(M) \rightarrow \mathcal{E}^{p,q}(M))}.$$

(b) Show that  $\bar{\partial} : \mathcal{E}^{p,q}(M) \rightarrow \mathcal{E}^{p,q+1}(M)$  descends to a well-defined map  $\bar{\partial} : E^{p,q}(M) \rightarrow E^{p,q+1}(M)$ ,  $[\alpha] \mapsto [\bar{\partial}\alpha]$ .

(c) Show that  $\bar{\partial} : E^{p,q}(M) \rightarrow E^{p,q+1}(M)$  satisfies  $\bar{\partial}^2 = 0$ .

*Solution:* (a) Since  $d = \mu + \partial + \bar{\partial} + \bar{\mu}$ , the operator  $d^2$  is a sum of 16 terms. We can separate them into 7 operators

$$\begin{aligned} \mu^2 &: \mathcal{E}^{p,q}(M) \rightarrow \mathcal{E}^{p+4,q-2}(M) \\ \mu\partial + \partial\mu &: \mathcal{E}^{p,q}(M) \rightarrow \mathcal{E}^{p+3,q-1}(M) \\ \partial^2 + \mu\bar{\partial} + \bar{\partial}\mu &: \mathcal{E}^{p,q}(M) \rightarrow \mathcal{E}^{p+2,q}(M) \\ \mu\bar{\mu} + \bar{\mu}\mu + \partial\bar{\partial} + \bar{\partial}\partial &: \mathcal{E}^{p,q}(M) \rightarrow \mathcal{E}^{p+1,q+1}(M) \\ \bar{\partial}^2 + \bar{\mu}\partial + \partial\bar{\mu} &: \mathcal{E}^{p,q}(M) \rightarrow \mathcal{E}^{p,q+2}(M) \\ \bar{\mu}\bar{\partial} + \bar{\partial}\bar{\mu} &: \mathcal{E}^{p,q}(M) \rightarrow \mathcal{E}^{p-1,q+3}(M) \\ \bar{\mu}^2 &: \mathcal{E}^{p,q}(M) \rightarrow \mathcal{E}^{p-2,q+4}(M). \end{aligned}$$

Since  $d^2 = 0$ , each of these operators is the zero map as well. In particular, we have  $\bar{\mu}^2 = 0$ .

(b) By the argument in part (a), we have  $\bar{\mu}\bar{\partial} + \bar{\partial}\bar{\mu} = 0$ . Let  $\alpha \in \mathcal{E}^{p,q}(M)$  with  $\bar{\mu}\alpha = 0$ . Note that  $\bar{\partial}\alpha \in \mathcal{E}^{p,q+1}(M)$  satisfies  $\bar{\mu}\bar{\partial}\alpha = -\bar{\partial}\bar{\mu}\alpha = 0$ , so  $[\bar{\partial}\alpha] \in E^{p,q+1}(M)$  is defined.

Suppose now that  $\beta \in \mathcal{E}^{p,q}(M)$  with  $\bar{\mu}\beta = 0$  and  $[\alpha] = [\beta]$ . Then there is  $\gamma \in \mathcal{E}^{p+1,q-2}(M)$  with  $\alpha = \beta + \bar{\mu}\gamma$ , so  $\bar{\partial}\alpha = \bar{\partial}\beta + \bar{\partial}\bar{\mu}\gamma = \bar{\partial}\beta - \bar{\mu}\bar{\partial}\gamma$ . Therefore  $[\bar{\partial}\alpha] = [\bar{\partial}\beta - \bar{\mu}\bar{\partial}\gamma] = [\bar{\partial}\beta]$ , so  $\bar{\partial} : E^{p,q}(M) \rightarrow E^{p,q+1}(M)$  is well-defined.

(c) From the argument in part (a), we have  $\bar{\partial}^2 + \bar{\mu}\partial + \partial\bar{\mu} = 0$ , so for  $\alpha \in \mathcal{E}^{p,q}(M)$  with  $\bar{\mu}\alpha = 0$  we have  $\bar{\partial}^2\alpha = -\bar{\mu}\partial\alpha - \partial\bar{\mu}\alpha = -\bar{\mu}\partial\alpha$ , so  $\bar{\partial}^2[\alpha] = \bar{\partial}[\bar{\partial}\alpha] = [\bar{\partial}^2\alpha] = [-\bar{\mu}\partial\alpha] = [0] = 0$ .

**5. Let  $\alpha$  be a  $(p, q)$ -form on an almost complex manifold  $(M, J)$ . Find a formula for  $\mu(\alpha)$  in terms of the Nijenhuis tensor  $N_J$ . Use this to show (directly) that if  $\mu : \mathcal{E}^{0,1}(M) \rightarrow \mathcal{E}^{2,0}(M)$  is zero, then  $J$  is integrable.**

*Solution:* Note that  $\mu(\alpha)$  is the  $(p+2, q-1)$  component of  $d\alpha$ , so for  $X_1, \dots, X_{p+1} \in \Gamma(M, T^{1,0}M)$  and  $Y_1, \dots, Y_q \in \Gamma(M, T^{0,1}M)$ , then

$$\begin{aligned} &\mu(\alpha)(X_1, \dots, X_{p+2}, Y_1, \dots, Y_{q-1}) \\ &= (d\alpha)(X_1, \dots, X_{p+2}, Y_1, \dots, Y_{q-1}) \\ &= \sum_{k=1}^{p+2} (-1)^{k-1} X_k(\alpha(X_1, \dots, \widehat{X}_k, \dots, X_{p+2}, Y_1, \dots, Y_{q-1})) \\ &\quad + \sum_{k=1}^{q-1} (-1)^{(p+2+k)-1} Y_k(\alpha(X_1, \dots, X_{p+2}, Y_1, \dots, \widehat{Y}_k, \dots, Y_{q-1})) \\ &\quad + \sum_{1 \leq j < k \leq p+2} (-1)^{j+k} \alpha([X_j, X_k], X_1, \dots, \widehat{X}_j, \dots, \widehat{X}_k, \dots, X_{p+2}, Y_1, \dots, Y_{q-1}) \\ &\quad + \sum_{\substack{1 \leq j \leq p+2 \\ 1 \leq k \leq q-1}} (-1)^{(p+2+j)+k} \alpha([X_j, Y_k], X_1, \dots, \widehat{X}_j, \dots, X_{p+2}, Y_1, \dots, \widehat{Y}_k, \dots, Y_{q-1}) \\ &\quad + \sum_{1 \leq j < k \leq q-1} (-1)^{(p+2+j)+(p+2+k)} \alpha([Y_j, Y_k], X_1, \dots, X_{p+2}, Y_1, \dots, \widehat{Y}_j, \dots, \widehat{Y}_k, \dots, Y_{q-1}). \end{aligned}$$

Since  $\alpha$  is a  $(p, q)$ -form, the summands in the first, second, fourth, and fifth sums vanish. Now note that

$$\begin{aligned} & \alpha([X_j, X_k], X_1, \dots, \widehat{X_j}, \dots, \widehat{X_k}, \dots, X_{p+2}, Y_1, \dots, Y_{q-1}) \\ &= \alpha([X_j, X_k]^{1,0} + [X_j, X_k]^{0,1}, X_1, \dots, \widehat{X_j}, \dots, \widehat{X_k}, \dots, X_{p+2}, Y_1, \dots, Y_{q-1}) \\ &= \alpha([X_j, X_k]^{1,0}, X_1, \dots, \widehat{X_j}, \dots, \widehat{X_k}, \dots, X_{p+2}, Y_1, \dots, Y_{q-1}) \\ & \quad + \alpha([X_j, X_k]^{0,1}, X_1, \dots, \widehat{X_j}, \dots, \widehat{X_k}, \dots, X_{p+2}, Y_1, \dots, Y_{q-1}). \end{aligned}$$

Again, because  $\alpha$  is a  $(p, q)$ -form, the first term vanishes. Writing  $X_j = U_j - iJU_j$  and  $X_k = U_k - iJU_k$ , we see that  $[X_j, X_k]^{0,1} = [U_j - iJU_j, U_k - iJU_k]^{0,1} = N_J(U_j, U_k) + iJN_J(U_j, U_k) = 2N_J(U_j, U_k)^{0,1}$ . Therefore,

$$\begin{aligned} & \mu(\alpha)(X_1, \dots, X_{p+2}, Y_1, \dots, Y_{q-1}) \\ &= \sum_{1 \leq j < k \leq p+2} (-1)^{j+k} \alpha(2N_J(U_j, U_k)^{0,1}, X_1, \dots, \widehat{X_j}, \dots, \widehat{X_k}, \dots, X_{p+2}, Y_1, \dots, Y_{q-1}). \end{aligned}$$

When  $\alpha \in \mathcal{E}^{0,1}(M)$ , we have

$$\mu(\alpha)(X_1, X_2) = -\alpha(2N_J(U_1, U_2)^{0,1}) = -2\alpha(N_J(U_1, U_2)^{0,1}) = -2\alpha(N_J(U_1, U_2)).$$

Let  $g$  be a bundle metric on  $T^{0,1}M$  and consider  $\alpha \in \mathcal{E}^{0,1}(M)$  given by  $\alpha(X) = g(X^{0,1}, N_J(U_1, U_2)^{0,1})$ . Note that

$$\mu(\alpha)(X_1, X_2) = -2\alpha(N_J(U_1, U_2)) = -2g(N_J(U_1, U_2)^{0,1}, N_J(U_1, U_2)^{0,1}) = -2\|N_J(U_1, U_2)^{0,1}\|^2.$$

Therefore, if  $\mu : \mathcal{E}^{0,1}(M) \rightarrow \mathcal{E}^{0,2}(M)$  is the zero map, then  $N_J(U_1, U_2)^{0,1} = 0$ . Since  $N_J(U_1, U_2)$  is real, we also have  $N_J(U_1, U_2)^{1,0} = \overline{N_J(\partial_1, \partial_2)^{0,1}} = 0$  and hence  $N_J(U_1, U_2) = 0$ .

**6. Let  $(M, J)$  be an almost complex manifold. Show that if  $\bar{\partial}^2 = 0$ , then  $J$  is integrable. (Hint: compute  $\bar{\partial}^2 f$  for a function  $f$ .)**

*Solution:* Let  $Y_1, Y_2 \in \Gamma(M, T^{0,1}M)$ . Note that  $\bar{\partial}^2 f = \bar{\partial}(\bar{\partial}f)$  is the  $(0, 2)$  component of  $d(\bar{\partial}f)$ , so

$$\begin{aligned} (\bar{\partial}^2 f)(Y_1, Y_2) &= \bar{\partial}(\bar{\partial}f)(Y_1, Y_2) \\ &= d(\bar{\partial}f)(Y_1, Y_2) \\ &= Y_1(\bar{\partial}f)(Y_2) - Y_2(\bar{\partial}f)(Y_1) - (\bar{\partial}f)([Y_1, Y_2]) \end{aligned}$$

Since  $\bar{\partial}f$  is a  $(0, 1)$ -form, we have  $(\bar{\partial}f)([Y_1, Y_2]) = (\bar{\partial}f)([Y_1, Y_2]^{1,0} + [Y_1, Y_2]^{0,1}) = (\bar{\partial}f)([Y_1, Y_2]^{0,1})$ . Moreover, since  $\partial f$  is the  $(0, 1)$  component of  $df$ , we have

$$\begin{aligned} (\bar{\partial}^2 f)(Y_1, Y_2) &= Y_1(\bar{\partial}f)(Y_2) - Y_2(\bar{\partial}f)(Y_1) - (\bar{\partial}f)([Y_1, Y_2]^{0,1}) \\ &= Y_1(df)(Y_2) - Y_2(df)(Y_1) - (df)([Y_1, Y_2]^{0,1}) \\ &= Y_1Y_2f - Y_2Y_1f - [Y_1, Y_2]^{0,1}f \\ &= [Y_1, Y_2]f - [Y_1, Y_2]^{0,1}f \\ &= [Y_1, Y_2]^{1,0}f. \end{aligned}$$

So if  $\bar{\partial}^2 = 0$ , then  $[Y_1, Y_2]^{1,0}f = 0$  for all  $f \in C^\infty(M)$ , so  $[Y_1, Y_2]^{0,1} = 0$ . Since  $Y_1$  and  $Y_2$  are arbitrary, we see that  $\Gamma(M, T^{0,1}M)$  is closed under Lie bracket, and hence  $J$  is integrable.

**7. Let  $E$  be a real rank  $2n$  bundle equipped with an orientation and a bundle metric. Let  $P_{SO(2n)}(E)$  denote the oriented orthonormal frame bundle of  $E$ , i.e. the induced principal  $SO(2n)$ -bundle which gives a reduction of structure group of  $P_{GL(2n, \mathbb{R})}(E)$  to  $SO(2n)$ . Show that  $P_{SO(2n)}(E)$  admits a reduction of structure group to  $U(n)$  if and only if  $E$  admits an almost complex structure which induces the given orientation and is compatible with the given bundle metric.**

*Solution:* Suppose  $E$  admits an almost complex structure  $J$  which induces the given orientation and is compatible with the given bundle metric. Since  $J$  is compatible with the given bundle metric, it gives rise to a hermitian bundle metric on the complex vector bundle  $(E, J)$ . Then the unitary frame bundle  $P_{U(n)}(E) \subset P_{SO(2n)}(E)$  is a principal  $U(n)$ -bundle, so  $P_{SO(2n)}(E)$  admits a reduction of structure group to  $U(n)$ .

Conversely, let  $P_{U(n)} \hookrightarrow P_{SO(2n)}(E)$  be a reduction of structure group. If  $v \in E_x$  and  $f \in P_{U(n)}$  is a frame for  $E_x$ , we set  $Jv = fJ_{2n}f^{-1}(v)$ . To see this is well-defined, note that if  $f' \in P_{U(n)}$ , then  $f' = f \circ A$  for some  $A \in U(n)$  so

$$f' \circ J_{2n} \circ (f')^{-1} = (f \circ A) \circ J_{2n} \circ (f \circ A)^{-1} = f \circ (A \circ J_{2n} \circ A^{-1}) \circ f^{-1} = f \circ J_{2n} \circ f^{-1}.$$

Clearly  $J^2 = -\text{id}_E$ . If  $V$  is a non-empty open set over which  $E$  is trivial (as a complex vector bundle), then  $P_{U(n)}(E|_V) = P_{U(n)}(E)|_V$  is trivial, so one can find a continuous section  $\sigma : V \rightarrow P_{U(n)}(E|_V)$ . Then  $J|_V = \sigma \circ J_{2n} \circ \psi$  where  $\psi(v) = \sigma(v)^{-1}$ . Since  $\sigma$  is continuous, so too is  $\psi$ , and hence  $J$  is a continuous section of  $\text{End}(E)$ .

To see that  $J$  induces the given orientation, note that if  $\{e_1, \dots, e_{2n}\}$  is the standard basis for  $\mathbb{R}^{2n}$ , and  $v_j := f(e_j)$ , then  $\{v_1, \dots, v_{2n}\}$  is an oriented basis for  $E_x$  (since  $f$  preserves orientation). As  $v_{2j} = f(e_{2j}) = f(J_{2n}e_{2j-1}) = f(J_{2n}f^{-1}(v_{2j-1})) = Jv_{2j-1}$ , we see that  $\{v_1, Jv_1, v_3, Jv_3, \dots, v_{2n-1}, Jv_{2n-1}\}$  is an oriented basis for  $E_x$ , and hence  $J$  induces the correct orientation.

Finally, denote the bundle metric on  $E$  by  $g$  and let  $g_{\text{Eucl}}$  denote the standard inner product on  $\mathbb{R}^{2n}$ . Then we have

$$\begin{aligned} g(Ju_1, Ju_2) &= g(f(J_{2n}f^{-1}u_1), f(J_{2n}f^{-1}u_2)) \\ &= g_{\text{Eucl}}(J_{2n}f^{-1}u_1, J_{2n}f^{-1}u_2) \\ &= g_{\text{Eucl}}(f^{-1}u_1, f^{-1}u_2) \\ &= g(u_1, u_2), \end{aligned}$$

so  $J$  is compatible with  $g$ .