## Solution to Practice 1q

**D4(a)** 
$$D(1) = 0$$
, so  $[D(1)]_{\mathcal{C}} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$ ,  $D(x) = 1$ , so  $[D(x)]_{\mathcal{C}} = \begin{bmatrix} 1 \\ 0 \end{bmatrix}$ , and  $D(x^2) = 2x$ , so  $[D(x^2)]_{\mathcal{C}} = \begin{bmatrix} 0 \\ 2 \end{bmatrix}$ . Thus,

$$_{\mathcal{C}}[D]_{\mathcal{B}} = \left[ \begin{array}{ccc} 0 & 1 & 0 \\ 0 & 0 & 2 \end{array} \right]$$

**D4(b)** 
$$L\left(\begin{bmatrix} 1 \\ -1 \end{bmatrix}\right) = x^2$$
, so  $\left[L\left(\begin{bmatrix} 1 \\ -1 \end{bmatrix}\right)\right]_{\mathcal{C}} = \begin{bmatrix} 0 \\ 1 \\ 1 \end{bmatrix}$ . And  $L\left(\begin{bmatrix} 1 \\ 2 \end{bmatrix}\right) = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$ 

 $3+x^2$ , but  $[3+x^2]_{\mathcal{C}}$  is not immediately obvious. To find  $[3+x^2]_{\mathcal{C}}$ , we need to find  $a,b,c\in\mathbb{R}$  such that

$$a(1+x^2) + b(1+x) + c(-1-x+x^2) = 3+x^2$$

This is the same as

$$(a+b-c) + (b-c)x + (a+c)x^2 = 3 + x^2$$

and this is equivalent to the system

$$a +b -c = 3$$

$$b -c = 0$$

$$a +c = 1$$

To solve this system, we row reduce its augmented matrix:

$$\begin{bmatrix} 1 & 1 & -1 & 3 \\ 0 & 1 & -1 & 0 \\ 1 & 0 & 1 & 1 \end{bmatrix} R_3 - R_1 \sim \begin{bmatrix} 1 & 1 & -1 & 3 \\ 0 & 1 & -1 & 0 \\ 0 & -1 & 2 & -2 \end{bmatrix} R_1 - R_2$$

$$\sim \begin{bmatrix} 1 & 0 & 0 & 3 \\ 0 & 1 & -1 & 0 \\ 0 & 0 & 1 & -2 \end{bmatrix} R_2 + R_3 \sim \begin{bmatrix} 1 & 0 & 0 & 3 \\ 0 & 1 & 0 & -2 \\ 0 & 0 & 1 & -2 \end{bmatrix}$$

And so we see that  $a=3,\,b=-2,$  and c=-2, which means that  $[L\left(\left[\begin{array}{c}1\\2\end{array}\right]\right)]_{\mathcal{C}}=$ 

$$[3+x^2]_{\mathcal{C}} = \begin{bmatrix} 3 \\ -2 \\ -2 \end{bmatrix}$$
. Which tells us that

$$_{\mathcal{C}}[L]_{\mathcal{B}} = \left[ \begin{array}{cc} 0 & 3\\ 1 & -2\\ 1 & -2 \end{array} \right]$$

 $\mathbf{D4(c)} \text{ First we note that } T\left(\left[\begin{array}{c}2\\-1\end{array}\right]\right) = \left[\begin{array}{c}1&0\\0&3\end{array}\right] \text{ and } T\left(\left[\begin{array}{c}1\\2\end{array}\right]\right) = \left[\begin{array}{c}3&0\\0&-1\end{array}\right].$  To find  $\left[\begin{array}{c}1&0\\0&3\end{array}\right]_{\mathcal{C}}$ , we need to find  $a_1,b_1,c_1,d_1\in\mathbb{R}$  such that

$$\begin{bmatrix} 1 & 0 \\ 0 & 3 \end{bmatrix} = a_1 \begin{bmatrix} 1 & 1 \\ 0 & 0 \end{bmatrix} + b_1 \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} + c_1 \begin{bmatrix} 1 & 1 \\ 0 & 1 \end{bmatrix} + d_1 \begin{bmatrix} 0 & 0 \\ 1 & 0 \end{bmatrix}$$
$$= \begin{bmatrix} a_1 + b_1 + c_1 & a_1 + c_1 \\ d_1 & b_1 + c_1 \end{bmatrix}$$

which is equivalent to the system

We also need to find  $\begin{bmatrix} 3 & 0 \\ 0 & -1 \end{bmatrix}_{\mathcal{C}}$ , which means we need to find  $a_2, b_2, c_2, d_2 \in \mathbb{R}$  such that

$$\begin{bmatrix} 3 & 0 \\ 0 & -1 \end{bmatrix} = a_2 \begin{bmatrix} 1 & 1 \\ 0 & 0 \end{bmatrix} + b_2 \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} + c_2 \begin{bmatrix} 1 & 1 \\ 0 & 1 \end{bmatrix} + d_2 \begin{bmatrix} 0 & 0 \\ 1 & 0 \end{bmatrix}$$
$$= \begin{bmatrix} a_2 + b_2 + c_2 & a_2 + c_2 \\ d_2 & b_2 + c_2 \end{bmatrix}$$

which is equivalent to the system

Since our two systems have the same coefficient matrix, we can solve them simultaneously by row reducing the following doubly augmented matrix:

$$\begin{bmatrix} 1 & 1 & 1 & 0 & 1 & 3 \\ 1 & 0 & 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 & 0 & 0 \\ 0 & 1 & 1 & 0 & 3 & -1 \end{bmatrix} R_2 - R_1 \sim \begin{bmatrix} 1 & 1 & 1 & 0 & 1 & 3 \\ 0 & -1 & 0 & 0 & -1 & -3 \\ 0 & 1 & 1 & 0 & 3 & -1 \end{bmatrix} R_1 + R_2$$

$$\sim \begin{bmatrix} 1 & 0 & 1 & 0 & 0 & 0 \\ 0 & -1 & 0 & 0 & -1 & -3 \\ 0 & 0 & 1 & 0 & 0 & -1 \\ 0 & 0 & 0 & 1 & 0 & 2 \\ 0 & 0 & 0 & 1 & 0 & 0 \end{bmatrix} R_1 - R_3 \sim \begin{bmatrix} 1 & 0 & 0 & 0 & -2 & 4 \\ 0 & 1 & 0 & 0 & 1 & 3 \\ 0 & 0 & 1 & 0 & 2 & -4 \\ 0 & 0 & 0 & 1 & 0 & 0 \end{bmatrix}$$

This tells us that  $a_1 = -2$ ,  $b_1 = 1$ ,  $c_1 = 2$ ,  $d_1 = 0$ ,  $a_2 = 4$ ,  $b_2 = 3$ ,  $c_2 = -4$ , and  $d_4 = 0$ . Which in turn tells us that

$$\begin{bmatrix} T\left(\begin{bmatrix} 2\\-1 \end{bmatrix}\right) \end{bmatrix}_{\mathcal{C}} \begin{bmatrix} -2\\1\\2\\0 \end{bmatrix} \text{ and } \begin{bmatrix} T\left(\begin{bmatrix} 1\\2 \end{bmatrix}\right) \end{bmatrix}_{\mathcal{C}} = \begin{bmatrix} 4\\3\\-4\\0 \end{bmatrix}$$

and from this we get

$$c[T]_{\mathcal{B}} = \begin{bmatrix} -2 & 4\\ 1 & 3\\ 2 & -4\\ 0 & 0 \end{bmatrix}$$

$$\mathbf{D4(d)}\ L(1+x^2) = \begin{bmatrix} 2\\-1 \end{bmatrix} = 3\begin{bmatrix} 1\\0 \end{bmatrix} - \begin{bmatrix} 1\\1 \end{bmatrix}, \text{ so } [L(1+x^2)]_{\mathcal{C}} = \begin{bmatrix} 3\\-1 \end{bmatrix}.$$

$$L(1+x) = \begin{bmatrix} 1\\0 \end{bmatrix} = 1\begin{bmatrix} 1\\0 \end{bmatrix} + 0\begin{bmatrix} 1\\1 \end{bmatrix}, \text{ so } [L(1+x)]_{\mathcal{C}} = \begin{bmatrix} 1\\0 \end{bmatrix}.\ L(-1+x+x^2) = \begin{bmatrix} 0\\2 \end{bmatrix} = -2\begin{bmatrix} 1\\0 \end{bmatrix} + 2\begin{bmatrix} 1\\1 \end{bmatrix}, \text{ so } [L(-1+x+x^2)]_{\mathcal{C}} = \begin{bmatrix} -2\\2 \end{bmatrix}.$$

From this we get

$$_{\mathcal{C}}[L]_{\mathcal{B}} = \left[ \begin{array}{ccc} 3 & 1 & -2 \\ -1 & 0 & 2 \end{array} \right]$$

**B1(a)**  $L(\vec{v}_1) = \vec{v}_1 + 3\vec{v}_2$ , so  $[L(\vec{v}_1)]_{\mathcal{B}} = \begin{bmatrix} 1\\3 \end{bmatrix}$ , while  $L(\vec{v}_2) = 5\vec{v}_1 - 7\vec{v}_2$ , so  $[L(\vec{v}_2)]_{\mathcal{B}} = \begin{bmatrix} 5\\-7 \end{bmatrix}$ . This means that  $[L]_{\mathcal{B}} = \begin{bmatrix} 1&5\\3&-7 \end{bmatrix}$ . We use this to find that

$$[L(\vec{x})]_{\mathcal{B}} = [L]_{\mathcal{B}}[\vec{x}]_{\mathcal{B}} = \begin{bmatrix} 1 & 5 \\ 3 & -7 \end{bmatrix} \begin{bmatrix} 4 \\ -2 \end{bmatrix} = \begin{bmatrix} -6 \\ 26 \end{bmatrix}$$

$$\begin{aligned} \mathbf{B1(b)} \ L(\vec{v}_1) &= 2\vec{v}_1 - 3\vec{v}_2, \text{ so } [L(\vec{v}_1)]_{\mathcal{B}} = \begin{bmatrix} 2 \\ -3 \\ 0 \end{bmatrix}. \ L(\vec{v}_2) = 3\vec{v}_1 + 4\vec{v}_2 - v_3, \text{ so } \\ [L(\vec{v}_2)]_{\mathcal{B}} &= \begin{bmatrix} 3 \\ 4 \\ -1 \end{bmatrix}. \text{ And } L(\vec{v}_3) = -\vec{v}_1 + 2\vec{v}_2 + 6v_3, \text{ so } [L(\vec{v}_3)]_{\mathcal{B}} = \begin{bmatrix} -1 \\ 2 \\ 6 \end{bmatrix}. \text{ This } \\ \text{means that } [L]_{\mathcal{B}} &= \begin{bmatrix} 2 & 3 & -1 \\ -3 & 4 & 2 \\ 0 & -1 & 6 \end{bmatrix}. \text{ We use this to find that } \end{aligned}$$

$$[L(\vec{x})]_{\mathcal{B}} = [L]_{\mathcal{B}}[\vec{x}]_{\mathcal{B}} = \begin{bmatrix} 2 & 3 & -1 \\ -3 & 4 & 2 \\ 0 & -1 & 6 \end{bmatrix} \begin{bmatrix} 5 \\ -3 \\ 1 \end{bmatrix} = \begin{bmatrix} 0 \\ -25 \\ 9 \end{bmatrix}$$

**B5(a)** We need to find  $a, b, c \in \mathbb{R}$  such that

$$\begin{bmatrix} 5 \\ 2 \\ 1 \end{bmatrix} = a \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix} + b \begin{bmatrix} 0 \\ 1 \\ 1 \end{bmatrix} + c \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix} = \begin{bmatrix} a+c \\ a+b \\ b+c \end{bmatrix}$$

This is equivalent to the system

$$\begin{array}{cccc}
a & +c & = 5 \\
a & +b & = 2 \\
b & +c & = 1
\end{array}$$

To solve this system, we row reduce its augmented matrix.

$$\begin{bmatrix} 1 & 0 & 1 & | & 5 \\ 1 & 1 & 0 & | & 2 \\ 0 & 1 & 1 & | & 1 \end{bmatrix} R_2 - R_1 \sim \begin{bmatrix} 1 & 0 & 1 & | & 5 \\ 0 & 1 & -1 & | & -3 \\ 0 & 1 & 1 & | & 1 \end{bmatrix} R_3 - R_2$$

$$\sim \begin{bmatrix} 1 & 0 & 1 & | & 5 \\ 0 & 1 & -1 & | & -3 \\ 0 & 0 & 2 & | & 4 \end{bmatrix} (1/2)R_3 \sim \begin{bmatrix} 1 & 0 & 1 & | & 5 \\ 0 & 1 & -1 & | & -3 \\ 0 & 0 & 1 & | & 2 \end{bmatrix} R_1 - R_3$$

$$\sim \begin{bmatrix} 1 & 0 & 0 & | & 3 \\ 0 & 1 & 0 & | & -1 \\ 0 & 0 & 1 & | & 2 \end{bmatrix}$$

This means that 
$$a=3,\,b=-1,$$
 and  $c=2.$  And so we have that  $\begin{bmatrix}5\\2\\1\end{bmatrix}_{\mathcal{B}}=\begin{bmatrix}3\\-1\\2\end{bmatrix}$ 

$$\mathbf{B5(b)}\ L\left(\begin{bmatrix}1\\1\\0\end{bmatrix}\right) = \begin{bmatrix}0\\5\\5\end{bmatrix}, \text{ so } \left[L\left(\begin{bmatrix}1\\1\\0\end{bmatrix}\right)\right]_{\mathcal{B}} = \begin{bmatrix}0\\5\\0\end{bmatrix}.\ L\left(\begin{bmatrix}0\\1\\1\end{bmatrix}\right) = \begin{bmatrix}2\\0\\2\end{bmatrix}, \text{ so } \left[L\left(\begin{bmatrix}0\\1\\1\end{bmatrix}\right)\right]_{\mathcal{B}} = \begin{bmatrix}0\\0\\2\end{bmatrix}.\ \text{And } L\left(\begin{bmatrix}1\\0\\1\end{bmatrix}\right) = \begin{bmatrix}5\\2\\1\end{bmatrix}, \text{ so our result}$$
 from B5(a) tells us that 
$$\left[L\left(\begin{bmatrix}1\\1\\0\end{bmatrix}\right)\right]_{\mathcal{B}} = \begin{bmatrix}3\\-1\\2\end{bmatrix}.\ \text{We use these to find that}$$
 
$$[L]_{\mathcal{B}} = \begin{bmatrix}0&0&3\\5&0&-1\\0&2&2\end{bmatrix}$$

**B5(c)** First, we know that

$$\begin{bmatrix} L\left(\begin{bmatrix} 5\\2\\1 \end{bmatrix}\right) \end{bmatrix}_{\mathcal{B}} = [L]_{\mathcal{B}} \begin{bmatrix} 5\\2\\1 \end{bmatrix}_{\mathcal{B}}$$

$$= \begin{bmatrix} 0 & 0 & 3\\5 & 0 & -1\\0 & 2 & 2 \end{bmatrix} \begin{bmatrix} 3\\-1\\2 \end{bmatrix}$$

$$= \begin{bmatrix} 6\\13\\2 \end{bmatrix}$$

Since 
$$\left[L\left(\begin{bmatrix} 5\\2\\1 \end{bmatrix}\right)\right]_{\mathcal{B}} = \begin{bmatrix} 6\\13\\2 \end{bmatrix}$$
, we have 
$$L\left(\begin{bmatrix} 5\\2\\1 \end{bmatrix}\right) = 6\begin{bmatrix}1\\1\\0 \end{bmatrix} + 13\begin{bmatrix}0\\1\\1 \end{bmatrix} + 2\begin{bmatrix}1\\0\\1 \end{bmatrix} = \begin{bmatrix}8\\19\\15 \end{bmatrix}$$