

### Solution to Practice 3r

**D4** Let  $\{\vec{v}_1, \vec{v}_2, \vec{v}_3\}$  be a basis for  $\mathbb{R}^3$ . We want to show that  $\{\vec{v}_1, \vec{v}_2, \vec{v}_3\}$  is also a basis for  $\mathbb{C}^3$ , so we need to show that it is linearly independent and that it is a spanning set for  $\mathbb{C}^3$ .

linear independence: Let  $\alpha_1, \alpha_2, \alpha_3 \in \mathbb{C}$  be such that

$$\alpha_1 \vec{v}_1 + \alpha_2 \vec{v}_2 + \alpha_3 \vec{v}_3 = \vec{0}$$

and let  $\alpha_1 = a_1 + b_1 i$ ,  $\alpha_2 = a_2 + b_2 i$ , and  $\alpha_3 = a_3 + b_3 i$ , for  $a_1, a_2, a_3, b_1, b_2, b_3 \in \mathbb{R}$ . Then we can rewrite our equation as

$$a_1 \vec{v}_1 + a_2 \vec{v}_2 + a_3 \vec{v}_3 + i(b_1 \vec{v}_1 + b_2 \vec{v}_2 + b_3 \vec{v}_3) = \vec{0} + i\vec{0}$$

This means that

$$a_1 \vec{v}_1 + a_2 \vec{v}_2 + a_3 \vec{v}_3 = \vec{0}$$

and

$$b_1 \vec{v}_1 + b_2 \vec{v}_2 + b_3 \vec{v}_3 = \vec{0}$$

in the real numbers. Since  $\{\vec{v}_1, \vec{v}_2, \vec{v}_3\}$  is linearly independent in  $\mathbb{R}$ , we must have that  $a_1 = a_2 = a_3 = 0$  and  $b_1 = b_2 = b_3 = 0$ . And this means that  $\alpha_1 = 0 + 0i = 0$ ,  $\alpha_2 = 0 + 0i = 0$ , and  $\alpha_3 = 0 + 0i = 0$ . And so we see that the only solution to the equation

$$\alpha_1 \vec{v}_1 + \alpha_2 \vec{v}_2 + \alpha_3 \vec{v}_3 = \vec{0}$$

is  $\alpha_1 = \alpha_2 = \alpha_3 = 0$ , which means that  $\{\vec{v}_1, \vec{v}_2, \vec{v}_3\}$  is linearly independent.

span: Let  $\vec{z} \in \mathbb{C}^3$ , and let  $\vec{x}, \vec{y} \in \mathbb{R}^3$  be such that  $\vec{z} = \vec{x} + i\vec{y}$ . Since  $\vec{x}, \vec{y} \in \mathbb{R}^3$ , there must be scalars  $s_1, s_2, s_3, t_1, t_2, t_3 \in \mathbb{R}$  such that

$$s_1 \vec{v}_1 + s_2 \vec{v}_2 + s_3 \vec{v}_3 = \vec{x} \quad \text{and} \quad t_1 \vec{v}_1 + t_2 \vec{v}_2 + t_3 \vec{v}_3 = \vec{y}$$

Then we have that

$$\begin{aligned} (s_1 + it_1) \vec{v}_1 + (s_2 + it_2) \vec{v}_2 + (s_3 + it_3) \vec{v}_3 &= s_1 \vec{v}_1 + s_2 \vec{v}_2 + s_3 \vec{v}_3 + i(t_1 \vec{v}_1 + t_2 \vec{v}_2 + t_3 \vec{v}_3) \\ &= \vec{x} + i\vec{y} \\ &= \vec{z} \end{aligned}$$

And so we see that for any  $\vec{z} \in \mathbb{C}^3$ ,  $\vec{z} \in \text{Span}\{\vec{v}_1, \vec{v}_2, \vec{v}_3\}$ , which means that  $\{\vec{v}_1, \vec{v}_2, \vec{v}_3\}$  is a spanning set for  $\mathbb{C}^3$ .