

Solution to Practice 3i

B3(a) The domain of f is \mathbb{R}^2 , and the codomain of f is \mathbb{R}^2 as well. We show that f preserves addition as follows:

$$\begin{aligned}f(x_1 + y_1, x_2 + y_2) &= (2(x_2 + y_2), (x_1 + y_1) - (x_2 - y_2)) \\&= (2x_2 + 2y_2, (x_1 - x_2) + (y_1 - y_2)) \\&= (2x_2, x_1 - x_2) + (2y_2, y_1 - y_2) \\&= f(x_1, x_2) + f(y_1, y_2)\end{aligned}$$

We show that f preserves scalar multiplication as follows:

$$\begin{aligned}f(tx_1, tx_2) &= (2tx_2, tx_1 - tx_2) \\&= (t(2x_2), t(x_1 - x_2)) \\&= t(2x_2, x_1 - x_2) \\&= tf(x_1, x_2)\end{aligned}$$

Thus, f IS a linear mapping.

B3(b) The domain of g is \mathbb{R}^2 and the codomain of g is \mathbb{R}^2 as well. But g is NOT a linear mapping. As a counterexample, consider that $g(0, 0) = (1, 0)$ and $g(1, \pi) = (-1, \pi^3)$, so $g(0, 0) + g(1, \pi) = (1, 0) + (-1, \pi^3) = (0, \pi^3)$. But $g((0, 0) + (1, \pi)) = g(1, \pi) = (-1, \pi^3) \neq g(0, 0) + g(1, \pi)$.

B3(c) The domain of h is \mathbb{R}^3 and the codomain of h is \mathbb{R}^3 as well. We show that h preserves addition as follows:

$$\begin{aligned}h(x_1 + y_1, x_2 + y_2, x_3 + y_3) &= (0, 0, (x_1 + y_1) + (x_2 + y_2) + (x_3 + y_3)) \\&= (0, 0, (x_1 + x_2 + x_3) + (y_1 + y_2 + y_3)) \\&= (0, 0, x_1 + x_2 + x_3) + (0, 0, y_1 + y_2 + y_3) \\&= h(x_1, x_2, x_3) + h(y_1, y_2, y_3)\end{aligned}$$

We show that h preserves scalar multiplication as follows:

$$\begin{aligned}h(tx_1, tx_2, tx_3) &= (0, 0, tx_1 + tx_2 + tx_3) \\&= (t(0), t(0), t(x_1 + x_2 + x_3)) \\&= t(0, 0, x_1 + x_2 + x_3) \\&= th(x_1, x_2, x_3)\end{aligned}$$

Thus, h IS a linear mapping.

B3(d) The domain of k is \mathbb{R}^3 , and the codomain of k is \mathbb{R}^3 as well. We see that k preserves addition as follows:

$$\begin{aligned}k(x_1 + y_1, x_2 + y_2, x_3 + y_3) &= (0, 0, 0) \\&= (0, 0, 0) + (0, 0, 0) \\&= k(x_1, x_2, x_3) + k(y_1, y_2, y_3)\end{aligned}$$

We show that h preserves scalar multiplication as follows:

$$\begin{aligned}
k(tx_1, tx_2, tx_3) &= (0, 0, 0) \\
&= (t(0), t(0), t(0)) \\
&= t(0, 0, 0) \\
&= tk(x_1, x_2, x_3)
\end{aligned}$$

Thus, k IS a linear mapping.

B3(e) The domain of l is \mathbb{R}^4 , and the codomain of l is \mathbb{R}^3 . But l is NOT a linear mapping. As a counterexample, consider that $l(1, 0, 0, 0) = (1, 1, 0)$ and $l(0, 1, 0, 0) = (0, 1, 0)$, so $l(1, 0, 0, 0) + l(0, 1, 0, 0) = (1, 1, 0) + (0, 1, 0) = (1, 2, 0)$. But $l((1, 0, 0, 0) + (0, 1, 0, 0)) = l(1, 1, 0, 0) = (1, 1, 0) \neq l(1, 0, 0, 0) + l(0, 1, 0, 0)$.

B3(f) The domain of m is \mathbb{R}^4 , and the codomain of m is $\mathbb{R}^1 = \mathbb{R}$. We show that m preserves addition as follows:

$$\begin{aligned}
m(x_1 + y_1, x_2 + y_2, x_3 + y_3, x_4 + y_4) &= ((x_1 + y_1) + (x_2 + y_2) - (x_3 + y_3)) \\
&= ((x_1 + x_2 - x_3) + (y_1 + y_2 - y_3)) \\
&= (x_1 + x_2 - x_3) + (y_1 + y_2 - y_3) \\
&= m(x_1, x_2, x_3, x_4) + m(y_1, y_2, y_3, y_4)
\end{aligned}$$

We show that m preserves scalar multiplication as follows:

$$\begin{aligned}
m(tx_1, tx_2, tx_3, tx_4) &= (tx_1 + tx_2 - tx_3) \\
&= t(x_1 + x_2 - x_3) \\
&= tm(x_1, x_2, x_3, x_4)
\end{aligned}$$

Course Author question: Let $f(\vec{0}) = \vec{x}$, where $\vec{x} \neq \vec{0}$. Then $2\vec{x} \neq \vec{x}$. And we have $f(2(\vec{0})) = f(\vec{0}) = \vec{x}$, but $2f(\vec{0}) = 2\vec{x}$. So $f(2(\vec{0})) \neq 2f(\vec{0})$, and so we see that f does not preserve scalar multiplication.