Solution to Practice 2k

B1(a) We are trying to find $x_1, x_2,$ and x_3 such that

$$x_{1} \begin{bmatrix} 1 \\ 1 \\ 0 \\ 1 \end{bmatrix} + x_{2} \begin{bmatrix} 2 \\ 0 \\ 0 \\ 2 \end{bmatrix} + x_{3} \begin{bmatrix} 0 \\ 2 \\ -1 \\ 1 \end{bmatrix} = \begin{bmatrix} -4 \\ -2 \\ 2 \\ -6 \end{bmatrix}$$

This is the same as a system of four equations in three unknowns, with augmented matrix

$$\begin{bmatrix}
1 & 2 & 0 & | & -4 \\
1 & 0 & 2 & | & -2 \\
0 & 0 & -1 & 2 \\
1 & 2 & 1 & | & -6
\end{bmatrix}$$

To solve this, we will row reduce the augmented matrix:

$$\begin{bmatrix} 1 & 2 & 0 & | & -4 \\ 1 & 0 & 2 & | & -2 \\ 0 & 0 & -1 & | & 2 \\ 1 & 2 & 1 & | & -6 \end{bmatrix} R_2 - R_1 \sim \begin{bmatrix} 1 & 2 & 0 & | & -4 \\ 0 & -2 & 2 & | & 2 \\ 0 & 0 & -1 & | & 2 \\ 0 & 0 & 1 & | & -2 \end{bmatrix} (1/2)R_2 - R_3$$

$$\sim \begin{bmatrix} 1 & 2 & 0 & | & -4 \\ 0 & 1 & -1 & | & -1 \\ 0 & 0 & 1 & | & -2 \\ 0 & 0 & 1 & | & -2 \end{bmatrix} R_4 - R_3 \sim \begin{bmatrix} 1 & 2 & 0 & | & -4 \\ 0 & 1 & -1 & | & -1 \\ 0 & 0 & 1 & | & -2 \\ 0 & 0 & 0 & | & 0 \end{bmatrix} R_2 + R_3$$

$$\sim \begin{bmatrix} 1 & 2 & 0 & | & -4 \\ 0 & 1 & -1 & | & -1 \\ 0 & 0 & 1 & | & -2 \\ 0 & 0 & 0 & | & 0 \end{bmatrix} R_1 - 2R_2 \sim \begin{bmatrix} 1 & 0 & 0 & | & 2 \\ 0 & 1 & 0 & | & -3 \\ 0 & 0 & 1 & | & -2 \\ 0 & 0 & 0 & | & 0 \end{bmatrix}$$

From our final RREF matrix, we see that $x_1 = 2$, $x_2 = -3$, and $x_3 = -2$ is a solution to our system. As such, we have that

$$\begin{bmatrix} -4 \\ -2 \\ 2 \\ -6 \end{bmatrix} = 2 \begin{bmatrix} 1 \\ 1 \\ 0 \\ 1 \end{bmatrix} - 3 \begin{bmatrix} 2 \\ 0 \\ 0 \\ 2 \end{bmatrix} - 2 \begin{bmatrix} 0 \\ 2 \\ -1 \\ 1 \end{bmatrix}$$

B1(b) We are trying to find x_1 , x_2 , and x_3 such that

$$x_{1} \begin{bmatrix} 1 \\ 1 \\ 0 \\ 1 \end{bmatrix} + x_{2} \begin{bmatrix} 2 \\ 0 \\ 0 \\ 2 \end{bmatrix} + x_{3} \begin{bmatrix} 0 \\ 2 \\ -1 \\ 1 \end{bmatrix} = \begin{bmatrix} 6 \\ 0 \\ 0 \\ 3 \end{bmatrix}$$

This is the same as a system of four equations in three unknowns, with augmented matrix

$$\left[\begin{array}{ccc|c}
1 & 2 & 0 & 6 \\
1 & 0 & 2 & 0 \\
0 & 0 & -1 & 0 \\
1 & 2 & 1 & 3
\end{array}\right]$$

To solve this, we will row reduce the augmented matrix:

$$\begin{bmatrix} 1 & 2 & 0 & | & 6 \\ 1 & 0 & 2 & | & 0 \\ 0 & 0 & -1 & | & 0 \\ 1 & 2 & 1 & | & 3 \end{bmatrix} R_2 - R_1 \sim \begin{bmatrix} 1 & 2 & 0 & | & 6 \\ 0 & -2 & 2 & | & -6 \\ 0 & 0 & -1 & | & 0 \\ 0 & 0 & 1 & | & -3 \end{bmatrix} (1/2)R_2 - R_3$$

$$\sim \begin{bmatrix} 1 & 2 & 0 & | & 6 \\ 0 & 1 & -1 & | & 3 \\ 0 & 0 & 1 & | & 0 \\ 0 & 0 & 1 & | & -3 \end{bmatrix} R_4 - R_3 \sim \begin{bmatrix} 1 & 2 & 0 & | & 6 \\ 0 & 1 & -1 & | & 3 \\ 0 & 0 & 1 & | & 0 \\ 0 & 0 & 0 & | & -3 \end{bmatrix}$$

At this point, our last row is a bad row, so we know that the system is inconsistent. That is, we know that we will not be able to find x_1 , x_2 and x_3 to satisfy

our equations. Thus,
$$\begin{bmatrix} 6 \\ 0 \\ 0 \\ 3 \end{bmatrix}$$
 is not in Span B .

B1(c) We are trying to find x_1 , x_2 , and x_3 such that

$$x_1 \begin{bmatrix} 1 \\ 1 \\ 0 \\ 1 \end{bmatrix} + x_2 \begin{bmatrix} 2 \\ 0 \\ 0 \\ 2 \end{bmatrix} + x_3 \begin{bmatrix} 0 \\ 2 \\ -1 \\ 1 \end{bmatrix} = \begin{bmatrix} 3 \\ -1 \\ 2 \\ 1 \end{bmatrix}$$

This is the same as a system of four equations in three unknowns, with augmented matrix

$$\left[\begin{array}{ccc|ccc}
1 & 2 & 0 & 3 \\
1 & 0 & 2 & -1 \\
0 & 0 & -1 & 2 \\
1 & 2 & 1 & 1
\end{array}\right]$$

To solve this, we will row reduce the augmented matrix:

$$\begin{bmatrix} 1 & 2 & 0 & 3 \\ 1 & 0 & 2 & -1 \\ 0 & 0 & -1 & 2 \\ 1 & 2 & 1 & 1 \end{bmatrix} R_2 - R_1 \sim \begin{bmatrix} 1 & 2 & 0 & 3 \\ 0 & -2 & 2 & -4 \\ 0 & 0 & -1 & 2 \\ 0 & 0 & 1 & -2 \end{bmatrix} (1/2)R_2 - R_3$$

$$\sim \begin{bmatrix}
1 & 2 & 0 & | & 3 \\
0 & 1 & -1 & | & 2 \\
0 & 0 & 1 & | & -2 \\
0 & 0 & 1 & | & -2
\end{bmatrix} R_4 - R_3 \sim \begin{bmatrix}
1 & 2 & 0 & | & 3 \\
0 & 1 & -1 & | & 2 \\
0 & 0 & 1 & | & -2 \\
0 & 0 & 0 & | & 0
\end{bmatrix} R_2 + R_3$$

$$\sim \begin{bmatrix}
1 & 2 & 0 & | & 3 \\
0 & 1 & 0 & | & 3 \\
0 & 1 & 0 & | & 0 \\
0 & 0 & 1 & | & -2 \\
0 & 0 & 0 & | & 0
\end{bmatrix}$$

$$\sim \begin{bmatrix}
1 & 0 & 0 & | & 3 \\
0 & 1 & 0 & | & 0 \\
0 & 0 & 1 & | & -2 \\
0 & 0 & 0 & | & 0
\end{bmatrix}$$

From our final RREF matrix, we see that $x_1 = 3$, $x_2 = 0$, and $x_3 = -2$ is a solution to our system. As such, we have that

$$\begin{bmatrix} 3 \\ -1 \\ 2 \\ 1 \end{bmatrix} = 3 \begin{bmatrix} 1 \\ 1 \\ 0 \\ 1 \end{bmatrix} + 0 \begin{bmatrix} 2 \\ 0 \\ 0 \\ 2 \end{bmatrix} - 2 \begin{bmatrix} 0 \\ 2 \\ -1 \\ 1 \end{bmatrix}$$

$$\mathbf{B3(a)} \begin{bmatrix} 1 & 1 & x_1 \\ -1 & 2 & x_2 \\ 2 & 5 & x_3 \end{bmatrix} \xrightarrow{R_2 + R_1} \sim \begin{bmatrix} 1 & 1 & x_1 \\ 0 & 3 & x_1 + x_2 \\ 0 & 3 & -2x_1 + x_3 \end{bmatrix} \xrightarrow{R_3 - R_2}$$

$$\sim \begin{bmatrix} 1 & 1 & x_1 \\ 0 & 3 & x_1 + x_2 \\ 0 & 0 & -3x_1 - x_2 + x_3 \end{bmatrix}$$

From this row echelon form matrix, we see that the system is consistent if and only if $-3x_1 - x_2 + x_3 = 0$.

$$\mathbf{B3(d)} \begin{bmatrix} 1 & 0 & | & x_1 \\ 3 & -1 & | & x_2 \\ 0 & 3 & | & x_3 \\ -2 & 4 & | & x_4 \end{bmatrix} R_2 - 3R_1 \sim \begin{bmatrix} 1 & 0 & | & x_1 \\ 0 & -1 & | & -3x_1 + x_2 \\ 0 & 3 & | & x_3 \\ 0 & 4 & | & 2x_1 + x_4 \end{bmatrix} R_3 + 3R_2$$

$$\sim \begin{bmatrix} 1 & 0 & | & x_1 \\ 0 & -1 & | & -3x_1 + x_2 \\ 0 & 0 & | & -3x_1 + x_2 \\ -9x_1 + 3x_2 + x_3 \\ 0 & 0 & | & -10x_1 + 4x_2 + x_4 \end{bmatrix}$$

We see from this last matrix that the system is consistent if and only if $\begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{bmatrix}$

is a solution to the homogeneous system

$$-9x_1 + 3x_2 + x_3 = 0$$

 $-10x_1 + 4x_2 + x_4 = 0$

$$\mathbf{B3(e)}\begin{bmatrix} 1 & -1 & 0 & x_1 \\ 1 & 3 & -2 & x_2 \\ 1 & 3 & -5 & x_3 \\ -1 & 1 & 2 & x_4 \end{bmatrix} \begin{matrix} R_2 - R_1 \\ R_3 - R_1 \\ R_4 + R_1 \end{matrix} \sim \begin{bmatrix} 1 & -1 & 0 & x_1 \\ 0 & 4 & -2 & -x_1 + x_2 \\ 0 & 0 & 2 & x_1 + x_4 \end{bmatrix} \begin{matrix} R_3 - R_2 \end{matrix}$$

$$\sim \begin{bmatrix} 1 & -1 & 0 & x_1 \\ 0 & 4 & -2 & -x_1 + x_2 \\ 0 & 0 & -3 & -x_2 + x_3 \\ 0 & 0 & 2 & x_1 + x_4 \end{bmatrix} \begin{matrix} \sum_{0 = 1}^{\infty} \left[1 & -1 & 0 & x_1 \\ 0 & 4 & -2 & -x_1 + x_2 \\ 0 & 0 & -6 & -2x_2 + 2x_3 \\ 0 & 0 & 6 & 3x_1 + 3x_4 \end{bmatrix} \begin{matrix} x_1 \\ x_2 + x_3 \\ x_3 + x_4 \end{matrix} \right] \begin{matrix} x_1 \\ x_4 + x_3 \end{matrix}$$

$$\sim \begin{bmatrix} 1 & -1 & 0 & x_1 \\ 0 & 4 & -2 & -x_1 + x_2 \\ 0 & 0 & -6 & -2x_2 + 2x_3 \\ 0 & 0 & -6 & -2x_2 + 2x_3 \\ 0 & 0 & 0 & 3x_1 - 2x_2 - 2x_3 + 3x_4 \end{bmatrix}$$

From this row echelon form matrix, we see that the system is consistent if and only if $3x_1 - 2x_2 - 2x_3 + 3x_4 = 0$.