#### A new variant of the interior point method, for large scale and warm started linear programs

Jos F. Sturm j.f.sturm@uvt.nl

http://center.uvt.nl/staff/sturm

CentER, Tilburg, The Netherlands

### Overview

- IPM vs. Other Approaches
- Linear Programming
- IPM Centrality
- Predictor-Corrector
- Aggregate Model Corrector
- Submodel Predictor
- **F**uture work

IPM iteration factors  $n \times n$  matrix variable Z in each iteration. Slow for large n.

- IPM iteration factors  $n \times n$  matrix variable Z in each iteration. Slow for large n.
- Bundle and NLP approaches merely need p such that  $p^T Z p < 0$ . Uses Lanczos. Fast for large n.

- IPM iteration factors  $n \times n$  matrix variable Z in each iteration. Slow for large n.
- Bundle and NLP approaches merely need p such that  $p^T Z p < 0$ . Uses Lanczos. Fast for large n.
- IPM works on complete model (A, b, c).

- IPM iteration factors  $n \times n$  matrix variable Z in each iteration. Slow for large n.
- Bundle and NLP approaches merely need p such that  $p^T Z p < 0$ . Uses Lanczos. Fast for large n.
- IPM works on complete model (A, b, c).
- **Simplex only on**  $(A_B, b, c_B)$ .

- IPM iteration factors  $n \times n$  matrix variable Z in each iteration. Slow for large n.
- Bundle and NLP approaches merely need p such that  $p^T Z p < 0$ . Uses Lanczos. Fast for large n.
- IPM works on complete model (A, b, c).
- **Simplex only on**  $(A_B, b, c_B)$ .
- **Simplex benefits from warm start.**

- IPM iteration factors  $n \times n$  matrix variable Z in each iteration. Slow for large n.
- Bundle and NLP approaches merely need p such that  $p^T Z p < 0$ . Uses Lanczos. Fast for large n.
- IPM works on complete model (A, b, c).
- **Simplex only on**  $(A_B, b, c_B)$ .
- **Simplex benefits from warm start.**
- Low rank updates.

- IPM iteration factors  $n \times n$  matrix variable Z in each iteration. Slow for large n.
- Bundle and NLP approaches merely need p such that  $p^T Z p < 0$ . Uses Lanczos. Fast for large n.
- **IPM** works on complete model (A, b, c).
- **Simplex only on**  $(A_B, b, c_B)$ .
- **Simplex benefits from warm start.**
- Low rank updates.
- **Exploiting structure**.

### Context

- Bundle: Helmberg, Rendl, Oustry, Madhu N. a.o.
- NLP approach of Burer, Monteiro, Zhang.
- Active set, simplex variants: Goldfarb, Y. Zhang.
- Projection methods: Lin-Han, Orsi-Rami-Moore.
- ACCPM: Goffin, Vial a.o.
- Low rank IPM: Karmarkar a.o.

### Linear Programming

$$\begin{array}{ll} \min \ c^{\mathrm{T}}x\\ (P) \ \mathrm{s.t.} & Ax-s=b\\ & x\in\Gamma,\,s\in\mathcal{K} \end{array}$$

$$\begin{array}{ll} \max & b^{\mathrm{T}}y \\ (D) & \mathrm{s.t.} & A^{\mathrm{T}}y + z = c \\ & z \geq \Gamma^{*}, y \in \mathcal{K}^{*} \end{array}$$

Here  $\mathcal{K} = \{0\}^m$  or  $\mathcal{K} = \Re^m_+$ .



$$x = \begin{bmatrix} y \\ x' \end{bmatrix}, z = \begin{bmatrix} s \\ z' \end{bmatrix}$$
$$\forall i \in \mathcal{I} : \begin{cases} x_i \ge 0 \\ z_i \ge 0. \end{cases}$$
$$\forall i \notin \mathcal{I} : \begin{cases} x_i \text{ is free} \\ z_i = 0. \end{cases}$$

All slacks (P,D) in z.

# **IPM vs. Active Set**

Active Set moves along the *boundary* 

# **IPM vs. Active Set**

- Active Set moves along the *boundary*
- Warm start initiates from *complementary* solution

# **IPM vs. Active Set**

Active Set moves along the *boundary* 

Warm start initiates from *complementary* solution

**But IPM follows Central Path in** *interior***!** 



Let

$$w_i = x_i z_i, \ i \in \mathcal{I}.$$

Let

$$w_i = x_i z_i, \ i \in \mathcal{I}.$$

#### Central path

$$\{w \mid w_i = w_j > 0 \,\forall i, j \in \mathcal{I}\}.$$

Let

$$w_i = x_i z_i, \ i \in \mathcal{I}.$$

Central path

$$w \mid w_i = w_j > 0 \,\forall i, j \in \mathcal{I} \}.$$

#### Central region (CR)

$$\{w \mid |\mathcal{I}| \min_{i \in \mathcal{I}} w_i \ge \theta \sum_i w_i > 0\}.$$

Let

$$w_i = x_i z_i, \ i \in \mathcal{I}.$$

Central path

$$\{w \mid w_i = w_j > 0 \,\forall i, j \in \mathcal{I}\}.$$

Central region (CR)

$$\{w \mid |\mathcal{I}| \min_{i \in \mathcal{I}} w_i \ge \theta \sum_i w_i > 0\}.$$

 $\theta = 1$  yields CP; choose  $0 < \theta < 1$ .

# Wide Region(2)

•  $w^{\theta}$  is projection of w onto CR

# Wide Region(2)

w<sup>θ</sup> is projection of w onto CR
Proximity measure (Roos et al.)

$$\delta_w^\theta = \frac{\|w^\theta - w\|_w}{\|w\|_w},$$

with  $||x||_{w}^{2} = \sum_{i \in \mathcal{I}} \frac{x_{i}^{2}}{w_{i}}$ .

# Wide Region(2)

w<sup>θ</sup> is projection of w onto CR
Proximity measure (Roos et al.)

$$\delta_w^\theta = \frac{\|w^\theta - w\|_w}{\|w\|_w},$$

with  $||x||_w^2 = \sum_{i \in \mathcal{I}} \frac{x_i^2}{w_i}$ . Neighborhood  $\{w | \delta_w^{\theta} \le \beta\}$ .

#### **Predictor-Corrector Method**

Corrector Step reduces  $\delta_w^{\theta} \leq \beta$  to  $O(\beta^2)$ . (Newton step to  $x_i z_i = w_i^{\theta}$ .)

Predictor Step reduces duality gap until  $\delta_w^{\theta} \approx \beta$ .

#### **Corrector Basics**

Linearize

$$(x_i + \Delta x_i)(z_i + \Delta z_i) = w_i^{\theta}$$

yielding

$$w_i + x_i \Delta z_i + z_i \Delta x_i = w_i^{\theta}.$$

(  $i \in \mathcal{I}$  )

# **Centrality Plot**



# **Centrality Plot**



#### Why not aggregate

#### variables above threshold?

#### First some details...

# **Optimality Conditions**



with

 $x \ge 0, \ s \in \mathcal{K},$  $z \ge 0, y \in \mathcal{K}^*.$ 

IMA Workshop, March 2003 – p.15/25

### **Skew-Symmetric Form**

Data matrix:  $M = -M^{\mathrm{T}}$ .

 $\begin{array}{ll} \min & b_0 y_0 \\ \text{s.t.} & M x + z = y_0 r \\ & r^{\mathrm{T}} x = b_0 \\ & x \in \Re^m \times \Re^n_+, \ z \in \{0\}^m \times \Re^n_+ \end{array}$ 

### **Skew-Symmetric Form**

Data matrix:  $M = -M^{\mathrm{T}}$ .

 $\begin{array}{ll} \min & b_0 y_0 \\ \text{s.t.} & M x + z = y_0 r \\ & r^{\mathrm{T}} x = b_0 \\ & x \in \Re^m \times \Re^n_+, \ z \in \{0\}^m \times \Re^n_+ \end{array}$ 

Observe:  $x^{T}z = y_0r^{T}x = b_0y_0 \ge 0$ . Optimum 0. r is residual vector (from initialization). Possible choice  $b_0 = 1$ .

For partition (B, N) aggregate at  $(x^k, z^k)$ 

$$a_0 := M_{BN} x_N^k$$

$$r_0 := r_N^{\mathrm{T}} x_N^k$$

Aggregate model:

min 
$$b_0 y_0$$
  
s.t.  $M_{BB} x_B + x_0 a_0 + z_B = y_0 r_B$   
 $-a_0^T x_B + z_0 = y_0 r_0$   
 $r_B^T x_B + r_0 x_0 = b_0$ 

Currently  $x_0^k = 1, z_0^k = (x_N^k)^T z_N^k$ .

IMA Workshop, March 2003 – p.17/25

#### Initialize

 $B = \{i | |\mathcal{I}| w_i < \theta \sum_{\mathcal{I}} w_j \}$ 

IMA Workshop, March 2003 – p.18/25

Initialize

$$B = \{i | |\mathcal{I}| w_i < \theta \sum_{\tau} w_j\}$$

As long as the inner centrality condition is not met in Master Problem, we disaggregate the most-violating variables.

**I**nitialize

$$B = \{i | |\mathcal{I}| w_i < \theta \sum_{\tau} w_j\}$$

- As long as the inner centrality condition is not met in Master Problem, we disaggregate the most-violating variables.
- Single disaggregation dominated by rank-1 update (quadratic time, not cubic).

**I**nitialize

$$B = \{i | |\mathcal{I}| w_i < \theta \sum_{\tau} w_j\}$$

- As long as the inner centrality condition is not met in Master Problem, we disaggregate the most-violating variables.
- Single disaggregation dominated by rank-1 update (quadratic time, not cubic).
- Efficiency determined by size of final *B*.

**I**nitialize

$$B = \{i | |\mathcal{I}| w_i < \theta \sum_{\tau} w_j\}$$

- As long as the inner centrality condition is not met in Master Problem, we disaggregate the most-violating variables.
- Single disaggregation dominated by rank-1 update (quadratic time, not cubic).
- Efficiency determined by size of final *B*.
- SDP: achieve centrality only in subproblem)

#### **Predictor Basics**

Linearize

 $\overline{(x_i + \Delta x_i)(z_i + \Delta z_i)} = 0$ 

yielding

 $w_i + x_i \Delta z_i + z_i \Delta x_i = 0.$ 

#### Select only *B*-variables:

$$\begin{array}{ll} \min & \tilde{b}_0 y_0 \\ \text{s.t.} & M_{BB} x_B + z_B = y_0 \tilde{r}_B \\ & \tilde{r}_B^{\mathrm{T}} x_B = \tilde{b}_0 \end{array} \end{array}$$

with residual  $y_0^k \tilde{r}_B = M_{BB} x_B^k + z_B^k$ ,

$$y_0(r_B - \tilde{r}_B) = M_{BN} x_N.$$

In Master Model:

$$x_N = \frac{y_0}{y_0^k} x_N^k.$$

Initialize B with estimate of binding dual constraints.First step: based on warm start. Subsequent steps:based on previous step.

Initialize B with estimate of binding dual constraints.First step: based on warm start. Subsequent steps:based on previous step.

**Step length based on**  $\|\Delta X_B \Delta z_B\|_w$ .

- Initialize B with estimate of binding dual constraints.
   First step: based on warm start. Subsequent steps: based on previous step.
- **Step length based on**  $\|\Delta X_B \Delta z_B\|_w$ .
- If not in Master Problem's neighborhood then introduce the most-violating variable  $j \in N$ , i.e.

$$w_j \le 0 \text{ or } j \in rg\max_i \frac{(w_i - w_i^{\theta})^2}{w_i}$$

Rank-1 update.

- Initialize B with estimate of binding dual constraints.
   First step: based on warm start. Subsequent steps: based on previous step.
- **Step length based on**  $\|\Delta X_B \Delta z_B\|_w$ .
- If not in Master Problem's neighborhood then introduce the most-violating variable  $j \in N$ , i.e.

$$w_j \le 0 \text{ or } j \in rg\max_i \frac{(w_i - w_i^{\theta})^2}{w_i}$$

Rank-1 update.

• Worst-case rate  $1 - 1/O(\sqrt{|B|})$ .

# (SDP remarks)

- Update increments order of matrix variable, thus low (not 1) rank update
- **MP:** maintain feasibility
- SP: also centrality

#### **Predictor Issues**

# For Master-Problem $\Delta x^{\mathrm{T}} \Delta z \neq 0$ hence normalization $b_0$ changes. Merit Function.

#### **Predictor Issues**

# For Master-Problem $\Delta x^{\mathrm{T}} \Delta z \neq 0$ hence normalization $b_0$ changes. Merit Function.

Impact on centrality, especially if  $\Delta x^{\mathrm{T}} \Delta z > 0$ .

#### **Predictor Issues**

- For Master-Problem  $\Delta x^{\mathrm{T}} \Delta z \neq 0$  hence normalization  $b_0$  changes. Merit Function.
- Impact on centrality, especially if  $\Delta x^{\mathrm{T}} \Delta z > 0$ .
- Alternative: keep  $b_0$  constant,  $\Delta x^T \Delta z = 0$  by changing  $r_N$ . Maintain  $-r_{\infty} \leq r_N \leq r_{\infty}$ .

Rank deficiency of reduced system  $A_B D A_B^T$ . Standard rank-1 update formula not applicable.

Rank deficiency of reduced system  $A_B D A_B^T$ . Standard rank-1 update formula not applicable.

Remedy: product-form-Cholesky

 $L_0L_1\ldots L_k\Theta_kL_k^{\mathrm{T}}L_{k-1}^{\mathrm{T}}\ldots L_0^{\mathrm{T}}.$ 

Rank deficiency of reduced system  $A_B D A_B^T$ . Standard rank-1 update formula not applicable.

Remedy: product-form-Cholesky

$$L_0 L_1 \dots L_k \Theta_k L_k^{\mathrm{T}} L_{k-1}^{\mathrm{T}} \dots L_0^{\mathrm{T}}.$$

Not only columns, also rows may be added

- Rank deficiency of reduced system  $A_B D A_B^T$ . Standard rank-1 update formula not applicable.
- Remedy: product-form-Cholesky

$$L_0L_1\ldots L_k\Theta_kL_k^{\mathrm{T}}L_{k-1}^{\mathrm{T}}\ldots L_0^{\mathrm{T}}.$$

Not only columns, also rows may be addedExploiting sparsity

- Rank deficiency of reduced system  $A_B D A_B^T$ . Standard rank-1 update formula not applicable.
- Remedy: product-form-Cholesky

$$L_0L_1\ldots L_k\Theta_kL_k^{\mathrm{T}}L_{k-1}^{\mathrm{T}}\ldots L_0^{\mathrm{T}}.$$

- Not only columns, also rows may be added
  Exploiting sparsity
- Pivot ordering in augmented self-dual system

- Rank deficiency of reduced system A<sub>B</sub>DA<sub>B</sub><sup>T</sup>. Standard rank-1 update formula not applicable.
- Remedy: product-form-Cholesky

$$L_0L_1\ldots L_k\Theta_kL_k^{\mathrm{T}}L_{k-1}^{\mathrm{T}}\ldots L_0^{\mathrm{T}}.$$

Not only columns, also rows may be added
Exploiting sparsity
Pivot ordering in augmented self-dual system
Prepare for future extensions

- Rank deficiency of reduced system A<sub>B</sub>DA<sub>B</sub><sup>T</sup>. Standard rank-1 update formula not applicable.
- Remedy: product-form-Cholesky

$$L_0L_1\ldots L_k\Theta_kL_k^{\mathrm{T}}L_{k-1}^{\mathrm{T}}\ldots L_0^{\mathrm{T}}.$$

Not only columns, also rows may be added
Exploiting sparsity
Pivot ordering in augmented self-dual system
Prepare for future extensions
Submodel pre-solving?



- Computational savings
- Iterates potentially more powerful
- Benefits from warm start
- Both rows and columns can be discarded
- Modifications for large SDP.
- More at ISMP2003, SIOPT2005, ISMP2006.