

C&O367: Nonlinear Optimization
(Winter 2013)
Assignment 2
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Due: Thursday, Jan. 31, 10:00AM (before class),

1 Convex Sets

1.1 Intersection of Convex Sets

Show that the intersection of convex sets is a convex set. Is the union of convex sets convex? (If not provide a counterexample.)

Solution: Let C_1, \dots, C_k be convex sets, and define $C := \bigcap C_k$. Assume $x, y \in C$ and $\lambda \in [0, 1]$. By definition of C we have $x, y \in C_i$, $i \in \{1, \dots, k\}$, and by convexity we have $\lambda x + (1-\lambda)y \in C_i$, $i \in \{1, \dots, k\}$. This means $\lambda x + (1-\lambda)y \in C$, so C is convex. (A similar argument holds for an infinite number of sets.)

This is not true for the union of convex sets. Let $C_1 := \{0\}$ and $C_2 := \{1\}$ as subsets of \mathbb{R} . Both sets are clearly convex, but the union of them is not convex.

1.2 Midpoint Convex

A set $C \subseteq \mathbb{R}^n$ is *midpoint convex* if whenever $x, y \in C$ we have $\frac{1}{2}(x + y) \in C$. It is clear that C convex implies that C is midpoint convex.

1. Suppose that C is a *closed* midpoint convex set. Show that C is a convex set.

Solution: Let $x, y \in C$ and assume that z is a point on the line segment between x and y . We construct a sequence $\{z_i\} := \frac{x_i + y_i}{2}$, where $x_0 = x$, $y_0 = y$, and

$$x_{i+1} = \begin{cases} z_i & z_i \leq z \\ x_i & z_i > z \end{cases} \quad y_{i+1} = \begin{cases} z_i & z_i > z \\ y_i & z_i \leq z \end{cases}$$

By this construction, z is always on the line segment between x_i and y_i , so we have $\|z_i - z\| \leq \|x - y\| 2^{-i}$ which means $\{z_i\}$ converges to z . By midpoint convexity of C we have $z_i \in C$ for all i , and because C is closed we have $z \in C$. This is true for all z on the line segment between x and y , so C is convex.

2. Find an example of a set C that is midpoint convex but is *not* a convex set.

Solution: \mathbb{Q} , the set of all rational numbers is midpoint convex, but clearly is not convex.

1.3 Halfspaces

1. Give conditions that guarantee that one halfspace contains another, i.e.,

$$\{\mathbf{x} \in \mathbb{R}^n : \mathbf{a}^\top \mathbf{x} \leq \mathbf{b}\} \subseteq \{\mathbf{x} \in \mathbb{R}^n : \bar{\mathbf{a}}^\top \mathbf{x} \leq \bar{\mathbf{b}}\},$$

where both $\mathbf{a}, \bar{\mathbf{a}}$ are not zero.

Solution: Let's denote the first halfspace $\{\mathbf{x} \in \mathbb{R}^n : \mathbf{a}^\top \mathbf{x} \leq \mathbf{b}\}$ by H_1 and the other one by H_2 . First I prove that there exists $\alpha > 0$ such that $\mathbf{a} = \alpha \bar{\mathbf{a}}$, i.e., \mathbf{a} and $\bar{\mathbf{a}}$ are parallel. If not, there exists a vector \mathbf{w} such that $\mathbf{a}^\top \mathbf{w} = 0$ and $\bar{\mathbf{a}}^\top \mathbf{w} > 0$. Now for any point $\mathbf{x} \in H_1$, we have $\mathbf{a}^\top (\mathbf{x} + \lambda \mathbf{w}) = \mathbf{a}^\top \mathbf{x} \leq \mathbf{b}$. This means for all values $\lambda > 0$, $\mathbf{a}^\top (\mathbf{x} + \lambda \mathbf{w}) \in H_1$. However, we have $\bar{\mathbf{a}}^\top (\mathbf{x} + \lambda \mathbf{w}) \rightarrow \infty$ when λ goes to $+\infty$, and $\bar{\mathbf{a}}^\top (\mathbf{x} + \lambda \mathbf{w})$ is not in H_2 for all values of λ which is a contradiction. Hence, $\mathbf{a} = \alpha \bar{\mathbf{a}}$. It's easy to show that for $H_1 \subseteq H_2$, we must have $\mathbf{b} \leq \alpha \bar{\mathbf{b}}$.

2. When are the halfspaces equal?

Solution: In this case we have $H_1 \subseteq H_2$ and $H_2 \subseteq H_1$. By the above explanation, there exists $\alpha > 0$ such that $\mathbf{a} = \alpha \bar{\mathbf{a}}$ and $\mathbf{b} = \alpha \bar{\mathbf{b}}$.

2 Convex Functions

2.1 Three slope rule

Suppose that $f : \mathbb{R} \rightarrow \mathbb{R}$ is convex and that $x < y < z$. Show that

$$\frac{f(y) - f(x)}{y - x} \leq \frac{f(z) - f(x)}{z - x} \leq \frac{f(z) - f(y)}{z - y}.$$

Solution: By simple calculations we can write y as the convex combination of x and z as follows:

$$\begin{aligned} y &= \frac{z - y}{z - x}x + \frac{y - x}{z - x}z, \\ \frac{z - y}{z - x} + \frac{y - x}{z - x} &= 1 \end{aligned}$$

convexity of f implies that

$$f(y) \leq \frac{z - y}{z - x}f(x) + \frac{y - x}{z - x}f(z).$$

Both of the inequalities are derived by simple reformulations.

2.2 Convex and Strictly Convex Functions

Are the following functions convex or strictly convex on the specified sets:

1. $f(x, y) = 5x^2 + 2xy + y^2 - x + 2y + 3$ on $D = \mathbb{R}^2$.

Solution: The Hessian of the function is

$$\nabla^2 f(x, y) = \begin{bmatrix} 10 & 2 \\ 2 & 2 \end{bmatrix},$$

which is positive definite, so the function is strictly convex.

2. $f(x, y) = c_1x_1 + c_2/x_1 + c_3x_2 + c_4/x_2$ on $D = \mathbb{R}_{++}^2$, where the c_i are all positive numbers.

Solution: The Hessian of the function is

$$\nabla^2 f(x, y) = \begin{bmatrix} 2c_2x^{-3} & 0 \\ 0 & 2c_4y^{-3} \end{bmatrix},$$

which is positive definite for $(x, y) \in \mathbb{R}_{++}^2$ and $c_i > 0$, so the function is strictly convex on the domain.

2.3 Quadratic Convex Functions

A quadratic function is one that can be expressed as

$$q(x) = x \cdot Ax + b \cdot x + \alpha,$$

where $A \in \mathcal{S}^n$, the space of real symmetric $n \times n$ matrices, $b \in \mathbb{R}^n$, and $\alpha \in \mathbb{R}$.

1. Show that the function

$$q(x) = (x_1 - x_2)^2 + (x_1 + 2x_2 + 1)^2 - 8x_1x_2$$

is a quadratic function by finding the appropriate A, b, α .

Solution: If you expand $q(x)$, you can see that it's a quadratic function with the following parameters:

$$A = \begin{bmatrix} 2 & -3 \\ -3 & 5 \end{bmatrix}, \quad b = \begin{bmatrix} 2 \\ 4 \end{bmatrix}, \quad \alpha = 1.$$

2. Compute the gradient and Hessian of $q(x)$ and express them using the A, b, α computed above in Item 1.

Solution: It is easy to check that $\nabla q(x) = 2Ax + b$ and $\nabla^2 q(x) = 2A$ which is true for any quadratic function.

3. Show that a quadratic function $q(\mathbf{x})$ is convex if, and only if, \mathbf{A} is positive semidefinite and it is strictly convex if \mathbf{A} is positive definite.

Solution: By the fact that $\nabla^2 q(\mathbf{x}) = 2\mathbf{A}$, the result is clear from the theorem proved for a general convex function. But we use the following proof which also solves the next question. For any $\mathbf{x}, \mathbf{y} \in \mathbb{R}^n$ and any $\lambda \in (0, 1)$, let's define $Q(\mathbf{x}, \mathbf{y}, \lambda)$ as

$$Q(\mathbf{x}, \mathbf{y}, \lambda) := \lambda q(\mathbf{x}) + (1 - \lambda)q(\mathbf{y}) - q(\lambda\mathbf{x} + (1 - \lambda)\mathbf{y}) = \lambda(1 - \lambda)(\mathbf{x} - \mathbf{y})^T \mathbf{A}(\mathbf{x} - \mathbf{y})$$

$q(\mathbf{x})$ is convex if and only if $Q(\mathbf{x}, \mathbf{y}, \lambda) \geq 0$ for all $\mathbf{x}, \mathbf{y} \in \mathbb{R}^n$ and any $\lambda \in (0, 1)$. As $\lambda(1 - \lambda) > 0$, this is true if and only if \mathbf{A} is positive semidefinite. $q(\mathbf{x})$ is strictly convex if and only if $Q(\mathbf{x}, \mathbf{y}, \lambda) > 0$ for all $\mathbf{x}, \mathbf{y} \in \mathbb{R}^n$ and any $\lambda \in (0, 1)$, which is true if and only if \mathbf{A} is positive definite.

4. Suppose that the quadratic function $q(\mathbf{x})$ is strictly convex. Is the matrix \mathbf{A} positive definite?

Solution: Yes, Proved in the previous question.

5. Suppose that $q(\mathbf{x})$ is a quadratic function of n variables such that the corresponding matrix \mathbf{A} is positive definite. Show that $\mathbf{0} = 2\mathbf{A}\mathbf{x} + \mathbf{b}$ has a unique solution and that this solution is the strict global minimizer of $q(\mathbf{x})$.

Solution: \mathbf{A} is positive definite, so is invertible. Then $2\mathbf{A}\mathbf{x} + \mathbf{b} = \mathbf{0}$ has the unique solution $\mathbf{x}^* = -\frac{1}{2}\mathbf{A}^{-1}\mathbf{b}$. \mathbf{x}^* is a critical point and $q(\mathbf{x})$ is strictly convex, so \mathbf{x}^* is the unique global minimizer.

6. Suppose that $q(\mathbf{x})$ is a quadratic function of n variables. Find necessary and sufficient conditions for $q(\mathbf{x})$ to be bounded below.

Solution: I claim that $q(\mathbf{x})$ is bounded below if and only if \mathbf{A} is positive semidefinite and $\mathbf{b} \in \mathcal{R}(\mathbf{A})$ (range of \mathbf{A}). First note that for a convex function, point \mathbf{x}^* is a global minimizer if and only if it's gradient is equal to zero (this is true only for convex functions). Assume that \mathbf{A} is positive semidefinite and $\mathbf{b} \in \mathcal{R}(\mathbf{A})$, then by the above results, $q(\mathbf{x})$ is convex. $\mathbf{b} \in \mathcal{R}(\mathbf{A})$ means that $2\mathbf{A}\mathbf{x} + \mathbf{b} = \mathbf{0}$ has a solution which is a global minimizer; $q(\mathbf{x})$ is bounded below.

Now, assume that $q(\mathbf{x})$ is bounded below. If \mathbf{A} is not positive semidefinite, then there exists \mathbf{y} such that $\mathbf{y}^T \mathbf{A} \mathbf{y} < 0$. We may assume that $\mathbf{b}^T \mathbf{y} \leq 0$, otherwise take $-\mathbf{y}$ instead. Then $q(\lambda\mathbf{y})$ goes to $-\infty$ when λ goes to $+\infty$ which is a contradiction. Hence, \mathbf{A} is positive semidefinite. If $\mathbf{b} \notin \mathcal{R}(\mathbf{A})$, then \mathbf{b} is not orthogonal to the null space of $\mathbf{A}^T = \mathbf{A}$. Hence, there exists \mathbf{y} such that $\mathbf{y}^T \mathbf{A} \mathbf{y} = 0$ and $\mathbf{b}^T \mathbf{y} < 0$. Again, $q(\lambda\mathbf{y})$ goes to $-\infty$ when λ goes to $+\infty$ which is a contradiction; we must have $\mathbf{b} \in \mathcal{R}(\mathbf{A})$.