# CO350 Linear Programming Chapter 8: Degeneracy and Finite Termination

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# Recap

#### The perturbation method

$$\begin{array}{cccc} & \max & c^T x \\ (P) & \text{s.t.} & Ax & = & b \\ & x & > & 0 \end{array}$$

Assumption: B is a feasible basis with  $A_B = I$ .

Perturb the right hand side to  $b' = b + [\varepsilon, \varepsilon^2, \dots, \varepsilon^m]^T$  to get

$$(P')$$
  $\max c^T x$   $s.t.$   $Ax = b'$   $x \geq 0$ 

We showed that B is also a feasible basis of (P').

Tableaux for (P') and (P) differ in right hand side only  $\implies$  choices of leaving variables are affected.

#### Lemma 8.2

If  $\varepsilon$  is positive and sufficiently small, then

$$\alpha_0 + \alpha_1 \varepsilon + \alpha_2 \varepsilon^2 + \dots + \alpha_m \varepsilon^m < \beta_0 + \beta_1 \varepsilon + \beta_2 \varepsilon^2 + \dots + \beta_m \varepsilon^m$$

$$\iff (\alpha_0, \alpha_1, \alpha_2, \dots, \alpha_m) \stackrel{L}{<} (\beta_0, \beta_1, \beta_2, \dots, \beta_m)$$

### Example (cycling example on pg 107)

Initial tableau:

$$z - 2x_1 - 3x_2 + x_3 + 12x_4 = 0$$

$$- 2x_1 - 9x_2 + x_3 + 9x_4 + x_5 = 0$$

$$\frac{1}{3}x_1 + x_2 - \frac{1}{3}x_3 - 2x_4 + x_6 = 0$$

Tableau for perturbed problem:

$$z - 2x_1 - 3x_2 + x_3 + 12x_4 = 0$$

$$- 2x_1 - 9x_2 + x_3 + 9x_4 + x_5 = \varepsilon$$

$$\frac{1}{3}x_1 + x_2 - \frac{1}{3}x_3 - 2x_4 + x_6 = \varepsilon^2$$

 $\bar{c}_2$  is largest positive reduced cost, so  $x_2$  enters.  $\min\{-, \varepsilon^2/1\} = \varepsilon^2$ , so  $x_6$  leaves. Pivot on (6, 2):

$$z - x_1 + 6x_4 + 3x_6 = 3\varepsilon^2$$

$$x_1 - 2x_3 - 9x_4 + x_5 + 9x_6 = \varepsilon + 9\varepsilon^2$$

$$\frac{1}{3}x_1 + x_2 - \frac{1}{3}x_3 - 2x_4 + x_6 = \varepsilon^2$$

 $\overline{c}_1$  is only positive reduced costs, so  $x_1$  enters.  $\min\{(\varepsilon+9\varepsilon^2)/1, \varepsilon^2/\frac{1}{3}\} = 3\varepsilon^2$ , so  $x_2$  leaves. Pivot on (2,1):

$$z + 3x_{2} - x_{3} + 6x_{6} = 6\varepsilon^{2}$$

$$- 3x_{2} - x_{3} - 3x_{4} + x_{5} + 6x_{6} = \varepsilon + 6\varepsilon^{2}$$

$$x_{1} + 3x_{2} - x_{3} - 6x_{4} + 3x_{6} = 3\varepsilon^{2}$$

The perturbed problem is unbounded.

Same pivots on original problem gives same conclusion.

#### Theorem 8.3 (pg 111)

- (a) (P') is nondegenerate.
- (b) B is a feasible basis of (P')  $\implies B$  is a feasible basis of (P).
- (c) B is an optimal basis of (P')  $\implies B$  is an optimal basis of (P).
- (d)  $x_k$  can enter and  $x_r$  can leave in tableau for (P') corresponding to B  $\Longrightarrow$  same for tableau for (P) corresponding to B.
- (e) Tableau for (P') corresponding to B detects unboundedness
  - $\implies$  same for tableau for (P) corresponding to B.

(a) (P') is nondegenerate.

**Proof:** (Contradiction)

Suppose (P') has degenerate basis B.

Let  $x^*$  be basic solution of (P') determined by B.

So  $x^*$  solves  $A_B x_B^* = b'$  and  $x_N^* = 0$ .

I.e.,  $x_B^* = A_B^{-1}b' \text{ and } x_N^* = 0.$ 

 $B \text{ degenerate} \implies x_B^* \text{ has a zero component}$  (say the h-th component is zero).

$$0 = h\text{-th component of } x_B^*$$

$$= (h\text{-th row of } A_B^{-1})b'$$

$$= [\alpha_1, \alpha_2, \dots, \alpha_m] \begin{pmatrix} b + \varepsilon^2 \\ \varepsilon^2 \\ \vdots \\ \varepsilon^m \end{pmatrix}$$

$$= \alpha_0 + \alpha_1 \varepsilon + \alpha_2 \varepsilon^2 + \dots + \alpha_m \varepsilon^m$$

So by Lemma 8.2,  $\alpha_i=0$  for  $i=0,1,2,\ldots,m$ . Hence  $[\alpha_1,\alpha_2,\ldots,\alpha_m]=(h\text{-th row of }A_B^{-1})$  is a zero row.

This contradicts  $A_B^{-1}$  is nonsingular.

(b) B is a feasible basis of (P')  $\implies B$  is a feasible basis of (P).

#### **Proof:**

Let  $x^*$  be the basic solution of (P') determined by B.

Let  $\hat{x}$  be the basic solution of (P) determined by B.

B feasible for  $(P') \implies x_i^* \ge 0$  for all  $i \in B$ .

Part (a)  $\implies$  B is nondegenerate  $\implies$   $x_i^* > 0$  for all  $i \in B$ 

 $\hat{\boldsymbol{x}}_i = (h\text{-th row of } A_B^{-1})b$ 

$$egin{aligned} oldsymbol{x_i^*} &= (h ext{-th row of } A_B^{-1}) \left( b + \left[ egin{array}{c} arepsilon \\ arepsilon \end{array} 
ight) \\ &= \hat{oldsymbol{x}}_i + lpha_1 arepsilon + \cdots + lpha_m arepsilon^m \end{aligned}$$

For all 
$$i \in B$$
,  $x_i^* > 0 \implies (\hat{x}_i, \alpha_1, \dots, \alpha_m) \stackrel{L}{>} (0, 0, \dots, 0)$   $\implies \hat{x}_i \ge 0$ 

Thus  $\hat{x}_i \geq 0$  for all  $i \in B \implies B$  feasible for (P).

(c) B is an optimal basis of (P')  $\implies B$  is an optimal basis of (P).

#### **Proof:**

Let (T') be the tableau for (P') corresponding to B. Let (T) be the tableau for (P) corresponding to B.

B optimal for (P')  $\implies B$  feasible for (P') and all  $\bar{c}_i$  in (T') are  $\leq 0$ .

Part (b)  $\implies$  B feasible for (P).

 $ar{c}_j$  are the same in both (T') and (T)

 $\implies$  all  $\bar{c}_j$  in (T) are  $\leq 0$ .

B feasible for (P) and all  $\bar{c}_j$  in (T) are  $\leq 0$ 

 $\implies B$  optimal for (P).

(d)  $x_k$  can enter and  $x_r$  can leave in tableau for (P') corresponding to B

 $\implies$  same for tableau for (P) corresponding to B.

#### **Proof:**

Let (T') be the tableau for (P') corresponding to B. Let (T) be the tableau for (P) corresponding to B.

 $x_k$  can enter in (T')

 $\implies \bar{c}_k > 0 \text{ in } (T')$ 

 $\implies \bar{c}_k > 0 \text{ in } (T)$ 

 $\implies x_k$  can enter in (T)

 $x_r$  can leave in (T')

 $\implies \bar{a}_{rk} > 0$  in (T') and  $\bar{b}_r/\bar{a}_{rk} = \min$ . ratio

 $\implies \bar{a}_{rk} > 0$  in (T') and new basis is feasible for (P')

 $\implies \bar{a}_{rk} > 0$  in (T) and new basis is feasible for (P)

 $\implies x_r$  can leave in (T)

(e) Tableau for (P') corresponding to B detects unboundedness

 $\implies$  same for tableau for (P) corresponding to B.

#### **Proof:**

Let (T') be the tableau for (P') corresponding to B. Let (T) be the tableau for (P) corresponding to B.

(T') detects unboundedness

 $\implies \bar{c}_k > 0 \text{ in } (T')$ 

and  $\bar{a}_{ik}$  in (T') are  $\leq 0$  for all  $i \in B$ 

 $\implies \bar{c}_k > 0 \text{ in } (T) \text{ (from part (d))}$ 

and  $\bar{a}_{ik}$  in (T) are  $\leq 0$  for all  $i \in B$ 

 $\implies$  (T) detects unboundedness

We have proved

#### Theorem 8.3 (pg 111)

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- (b) B is a feasible basis of (P')  $\implies B$  is a feasible basis of (P).
- (c) B is an optimal basis of (P')  $\implies B$  is an optimal basis of (P).
- (d)  $x_k$  can enter and  $x_r$  can leave in tableau for (P') corresponding to B  $\implies$  same for tableau for (P) corresponding to B.
- (e) Tableau for (P') corresponding to B detects unboundedness  $\implies$  same for tableau for (P) corresponding to B.

#### Corollary 8.3 (pg 112)

The simplex method applied to the perturbed problem (P') starting from a feasible basis B with  $A_B = I$  will terminate after a finite number of iterations. Moreover, B' optimal for  $(P') \implies B'$  optimal for (P), and (P') unbounded  $\implies (P)$  unbounded.

# The Lexicographical Simplex Method

It is an implementation of the simplex method on the perturbed problem (P').

#### We established that

the difference between (P) and (P') is the choice of leaving variables.

#### Moreover

all pivots on (P') can be performed on (P).

#### Conclusion:

Simplex method on (P') is the same as simplex method on (P) with a special choice rule for leaving variables.

This special rule is called the lexicographical rule.

The resulting simplex method is called the <u>lexicographical</u> simplex method.

#### Lexicographical rule

R.h.s. of  $x_i$ -row (T') is

$$\overline{b}_i' = \overline{b}_i + \beta_{i1}\varepsilon + \beta_{i2}\varepsilon^2 + \dots + \beta_{im}\varepsilon^m$$

where  $[\beta_{i1}, \beta_{i2}, \dots, \beta_{im}]$  is the h-th row of the matrix  $A_B^{-1}$  and i is the h-th index in the basis B.

In choosing leaving variable, we pick r such that

$$ar{a}_{rk} > 0$$
 and  $rac{ar{b}'_r}{ar{a}_{rk}} = \min\left\{rac{ar{b}'_i}{ar{a}_{ik}}: ar{a}_{ik} > 0
ight\}$ 

I.e., we pick the minimum of

$$\frac{\bar{b}_i + \beta_{i1}\varepsilon + \beta_{i2}\varepsilon^2 + \dots + \beta_{im}\varepsilon^m}{\bar{a}_{ik}} \quad \text{over} \quad \{i \in B : \bar{a}_{ik} > 0\}$$

I.e., we pick the lexicographical minimum of

$$\frac{(\bar{b}_i, \beta_{i1}, \beta_{i2}, \dots, \beta_{im})}{\bar{a}_{ik}} \quad \text{over} \quad \{i \in B : \bar{a}_{ik} > 0\}$$

All we need are

$$ar{A}$$
,  $ar{b}$  and  $A_B^{-1}$ .

Note: This always give a unique choice:

Otherwise the next tableau is degenerate (but we know that (P') is nondegenerate).

## $A_B^{-1}$ appears in the tableau!

We assumed initial basis B' has  $A_{B'} = I$ .

In the tableau corresponding to current basis B,

the 
$$x_i$$
-rows are  $A_B^{-1}Ax = A_B^{-1}b$ 

i.e. 
$$ar{A}=A_{B}^{-1}A$$
 and  $ar{b}=A_{B}^{-1}b$ 

Magically, 
$$\bar{A}_{B'} = A_{B}^{-1} A_{B'} = A_{B}^{-1}$$

i.e.,  $A_B^{-1}$  appears in the tableau corresponding to B as columns indexed by B'.

#### Example (Not in notes)

Solve using lexicographical simplex method.

Initial tableau:

$$z - x_1 - 2x_2 = 0$$
  
 $2x_1 + 4x_2 + 6x_3 + x_4 = 6$   
 $x_1 + 3x_2 + 3x_3 + x_5 = 3$ 

 $\overline{c}_2$  is the largest positive reduced cost, so  $x_2$  enters.  $\min\left\{\frac{(6,1,0)}{4},\frac{(3,0,1)}{3}\right\}=\left(1,0,\frac{1}{3}\right)$ , so  $x_5$  leaves.

Pivot on (5,2):

$$z - \frac{1}{3}x_1 + 2x_3 + \frac{2}{3}x_5 = 2$$

$$\frac{2}{3}x_1 + 2x_3 + x_4 - \frac{4}{3}x_5 = 2$$

$$\frac{1}{3}x_1 + x_2 + x_3 + \frac{1}{3}x_5 = 1$$

 $\bar{c}_1$  is the only positive reduced cost, so  $x_1$  enters.

$$\min\left\{\frac{(2,1,-4/3)}{2/3},\frac{(1,0,1/3)}{1/3}\right\}=(3,0,1)$$
, so  $x_2$  leaves.

Pivot on (2,1):

This tableau is optimal.