

CO350 Linear Programming

Chapter 5: Basic Solutions

1st June 2005

Recap

On Monday, we learned

- **Theorem 5.3**

Consider an LP in SEF with $\text{rank}(A) = \# \text{ rows}$. Then
 x^* is bfs $\iff x^*$ is extreme point of the feasible region.

- Definition of basic feasible solution for LP problems in SIF.

- **Theorem 5.4**

Consider an LP in SIF. Then

x^* is bfs $\iff x^*$ is extreme point of the feasible region.

Why consider basic feasible solutions?

Theorem 5.5 (Pg 65) Let A be m by n with rank m . Consider the LP in SEF

$$\begin{aligned} & \max. \quad c^T x \\ (P) \quad & \text{s.t.} \quad Ax = b \\ & \quad \quad x \geq 0 \end{aligned}$$

If (P) has an optimal solution
then (P) has an optimal solution that is basic.

Proof: (Almost the same as the proof on page 66)

Key ingredient:

Show that if x^* is optimal but not basic, then there is an optimal solution with more zeros entries than x^* .

Suppose that x^* is optimal but not basic.

From proof of previous theorem (also emphasized in the remarks after proof), we know that

$\exists d \in \mathbf{R}^n$, $d \neq 0$, $d_j = 0$ whenever $x_j^* = 0$, and $Ad = 0$, and
 $\exists \varepsilon > 0$, both $x^1 = x^* + \varepsilon d$ and $x^2 = x^* - \varepsilon d$ are feasible.

We now show that $c^T d = 0$.

If $c^T d > 0$, then

$$c^T x^1 = c^T x^* + \varepsilon c^T d > c^T x^*$$

contradicts x^* is optimal.

Similarly, $c^T d < 0 \implies c^T x^2 > c^T x^*$ contradicts x^* optimal.

Proof: (cont'd)

Key ingredient:

Show that if x^* is optimal but not basic, then there is an optimal solution with more zeros entries than x^* .

So far we assumed x^* optimal but not basic and obtained non-zero vector $d \in \mathbf{R}^n$ such that

(1) $Ad = 0$, $c^T d = 0$, and

(2) $d_j = 0$ whenever $x_j^* = 0$.

Since d has at least one non-zero component, we may assume that $d_k < 0$ for some k . (Consider $-d$ otherwise.)

Let $x(t) = x^* + td$. Note that $Ax(t) = Ax^* + tAd = b$.

As t increases from 0, at least one component of $x(t)$ decreases towards 0. (E.g., the k -th component.)

So there is a largest value of t for which $x(t)$ stays feasible.

At that largest value of t , at least one component of $x(t)$ went from positive to 0.

At the same time, all those components that were 0 remains at 0 (because of (2)).

So $x(t)$ is a feasible solution with more zero components than x^* .

Moreover, $c^T x(t) = c^T x^* + tc^T d = c^T x^* \implies x(t)$ optimal.

Conclusion: an optimal solution x^* with most possible number of zero component must be basic. ■

Theorem 5.5 (Pg 65) Let A be m by n with rank m . Consider the LP in SEF

$$\begin{array}{ll} \max. & c^T x \\ (P) \quad \text{s.t.} & Ax = b \\ & x \geq 0 \end{array}$$

If (P) has an optimal solution
then (P) has an optimal solution that is basic.

A few remarks: (Not in notes)

- The assumption “ **A has rank m** ” is necessary!
Without it, we cannot even define a basis of A .
In this case, the theorem fails because (P) may still have optimal solutions but there are no basic solutions.
- The theorem does **NOT** say that all optimal solutions are basic.

However, there is a very special case for which all optimal solutions are basic.

All optimal solutions are basic if and only if there is exactly one optimal solution. (Prove it!)

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Chapter 6: The Simplex Method

1st June 2005

Motivation

Consider LP in SEF where A is m -by- n with rank m .

$$\begin{array}{ll} \max. & c^T x \\ (P) \quad \text{s.t.} & Ax = b \\ & x \geq 0 \end{array}$$

- We know that if (P) has an optimal solution, then there is one which is basic.
- So we only need to look at basic feasible solutions.
- We start at a bfs x^* , and check if x^* is optimal. (Recall C.S. Theorem!)
- If x^* is not optimal, we move to a “neighbouring” bfs that has better objective value, and repeat.

A few details to fill in

1. How do we find a bfs x^* to start with?
2. How do we move to a “neighbouring” bfs?
3. How to we know that we will find an optimal x^* after a finite number of repetitions?

For now, we consider the second question, and leave the remaining questions for later.

Bases and Tableaux

Consider LP in SEF where A is m -by- n with rank m .

$$\begin{aligned} \max. \quad & c^T x \\ (P) \quad & \text{s.t.} \quad Ax = b \\ & x \geq 0 \end{aligned}$$

In this chapter, we assume that we have a basis B that determines a bfs x^* .

Tableau – “an effective way to store ALL information about the LP problem at a basis B ”.

(Defn) Basic and Nonbasic Variables

Let N be the set $\{1, 2, \dots, n\} \setminus B$.

x_j ($j \in B$) are called basic variables.

x_j ($j \in N$) are called nonbasic variables.

To find the basic solution determined by B , we need to solve

$$\begin{aligned} Ax &= b \\ x_j &= 0 \quad (j \notin B) \end{aligned}$$

To retain information about original LP, we

1. express basic variables in terms of nonbasic variables,
2. set nonbasic variables to zeros.

Example (See pg 70 for more examples)

$$\begin{array}{rclclclclclcl}
 \text{max. } z & = & 5x_1 & + & 3x_2 & & & & & & \\
 \text{s.t.} & & 2x_1 & + & 3x_2 & + & x_3 & & & & = 15 \\
 & & 2x_1 & + & x_2 & & & + & x_4 & & = 9 \\
 & & x_1 & - & x_2 & & & & & + & x_5 = 3 \\
 & & x_1 & , & x_2 & , & x_3 & , & x_4 & , & x_5 \geq 0
 \end{array}$$

For the basis $B = \{3, 4, 5\}$, we already have the basic variables x_3, x_4, x_5 in terms of the nonbasic variables x_1, x_2 .

$$\begin{array}{rclclclclclcl}
 z & - & 5x_1 & - & 3x_2 & & & & & & = 0 \\
 & & 2x_1 & + & 3x_2 & + & x_3 & & & & = 15 \\
 & & 2x_1 & + & x_2 & & & + & x_4 & & = 9 \\
 & & x_1 & - & x_2 & & & & & + & x_5 = 3
 \end{array}$$

For the basis $B = \{1, 2, 3\}$, we perform elementary row operations to get the basics in terms of the nonbasics.

$$\begin{array}{rclclclclclcl}
 z & & & & + & \frac{8}{3}x_4 & - & \frac{1}{3}x_5 & = & 23 \\
 & & x_2 & & + & \frac{1}{3}x_4 & - & \frac{2}{3}x_5 & = & 1 \\
 & & x_1 & & + & \frac{1}{3}x_4 & + & \frac{1}{3}x_5 & = & 4 \\
 & & & x_3 & - & \frac{5}{3}x_4 & + & \frac{4}{3}x_5 & = & 4
 \end{array}$$

For the basis $B = \{2, 3, 5\}$, we perform elementary row operations to get

$$\begin{array}{rcccccccl} z & + & x_1 & & + & 3x_4 & & = & 27 \\ & & 2x_1 & + & x_2 & & + & x_4 & = & 9 \\ & -4x_1 & & + & x_3 & - & 3x_4 & & = & -12 \\ & & 3x_1 & & & & + & x_4 & + & x_5 & = & 12 \end{array}$$

For the basis $B = \{1, 2, 5\}$, we perform elementary row operations to get

$$\begin{array}{rcccccccl} z & & & + & \frac{1}{4}x_3 & + & \frac{9}{4}x_4 & & = & 24 \\ & & x_2 & + & \frac{1}{2}x_3 & - & \frac{1}{2}x_4 & & = & 3 \\ & x_1 & & - & \frac{1}{4}x_3 & + & \frac{3}{4}x_4 & & = & 3 \\ & & & & \frac{3}{4}x_3 & - & \frac{5}{4}x_4 & + & x_5 & = & 3 \end{array}$$

For the basis $B = \{2, 4, 5\}$, we perform elementary row operations to get

$$\begin{array}{rcccccccl} z & - & 3x_1 & & + & x_3 & & = & 15 \\ & & \frac{2}{3}x_1 & + & x_2 & + & \frac{1}{3}x_3 & & = & 5 \\ & & \frac{4}{3}x_1 & & - & \frac{1}{3}x_3 & + & x_4 & = & 4 \\ & & \frac{5}{3}x_1 & & + & \frac{1}{3}x_3 & & + & x_5 & = & 8 \end{array}$$
