Section 6.2 Orthogonal Sets

A set of vectors $\{\mathbf{u}_1, \mathbf{u}_2, ..., \mathbf{u}_p\}$ in \mathbf{R}^n is called an **orthogonal set** if $\mathbf{u}_i \cdot \mathbf{u}_j = 0$ whenever $i \neq j$.

EXAMPLE: Is
$$\left\{ \begin{bmatrix} 1 \\ -1 \\ 0 \end{bmatrix}, \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix} \right\}$$
 an orthogonal set?

Solution: Label the vectors $\mathbf{u}_1, \mathbf{u}_2$, and \mathbf{u}_3 respectively. Then

 $\mathbf{u}_1 \cdot \mathbf{u}_2 =$

 $\mathbf{U}_1 \cdot \mathbf{U}_3 =$

 $\mathbf{u}_2 \cdot \mathbf{u}_3 =$

Therefore, $\{\mathbf{u}_1, \mathbf{u}_2, \mathbf{u}_3\}$ is an orthogonal set.

THEOREM 4

Suppose $S = \{\mathbf{u}_1, \mathbf{u}_2, ..., \mathbf{u}_p\}$ is an orthogonal set of nonzero vectors in \mathbf{R}^n and $W = \text{span}\{\mathbf{u}_1, \mathbf{u}_2, ..., \mathbf{u}_p\}$. Then *S* is a linearly independent set and is therefore a basis for *W*.

Partial Proof: Suppose

$$c_1 \mathbf{u}_1 + c_2 \mathbf{u}_2 + \dots + c_p \mathbf{u}_p = \mathbf{0}$$

$$(c_1 \mathbf{u}_1 + c_2 \mathbf{u}_2 + \dots + c_p \mathbf{u}_p) \cdot = \mathbf{0} \cdot$$

$$(c_1 \mathbf{u}_1) \cdot \mathbf{u}_1 + (c_2 \mathbf{u}_2) \cdot \mathbf{u}_1 + \dots + (c_p \mathbf{u}_p) \cdot \mathbf{u}_1 = \mathbf{0}$$

$$c_1(\mathbf{u}_1 \cdot \mathbf{u}_1) + c_2(\mathbf{u}_2 \cdot \mathbf{u}_1) + \dots + c_p(\mathbf{u}_p \cdot \mathbf{u}_1) = \mathbf{0}$$

$$c_1(\mathbf{u}_1 \cdot \mathbf{u}_1) = \mathbf{0}$$

Since $\mathbf{u}_1 \neq \mathbf{0}$, $\mathbf{u}_1 \cdot \mathbf{u}_1 > 0$ which means $c_1 =$ ____.

In a similar manner, c_2, \ldots, c_p can be shown to by all 0. So *S* is a linearly independent set.

An **orthogonal basis** for a subspace W of \mathbb{R}^n is a basis for W that is also an orthogonal set.

EXAMPLE: Suppose $S = \{\mathbf{u}_1, \mathbf{u}_2, \dots, \mathbf{u}_p\}$ is an orthogonal basis for a subspace W of \mathbf{R}^n and suppose \mathbf{y} is in W. Find c_1, \dots, c_p so that

$$\mathbf{y} = c_1 \mathbf{u}_1 + c_2 \mathbf{u}_2 + \dots + c_p \mathbf{u}_p.$$

Solution:

$$\mathbf{y} \cdot = (c_1 \mathbf{u}_1 + c_2 \mathbf{u}_2 + \dots + c_p \mathbf{u}_p) \cdot$$

$$\mathbf{y} \cdot \mathbf{u}_1 = (c_1 \mathbf{u}_1 + c_2 \mathbf{u}_2 + \dots + c_p \mathbf{u}_p) \cdot \mathbf{u}_1$$

$$\mathbf{y} \cdot \mathbf{u}_1 = c_1(\mathbf{u}_1 \cdot \mathbf{u}_1) + c_2(\mathbf{u}_2 \cdot \mathbf{u}_1) + \dots + c_p(\mathbf{u}_p \cdot \mathbf{u}_1)$$

$$\mathbf{y} \cdot \mathbf{u}_1 = c_1(\mathbf{u}_1 \cdot \mathbf{u}_1)$$

$$c_1 = \frac{\mathbf{y} \cdot \mathbf{u}_1}{\mathbf{u}_1 \cdot \mathbf{u}_1}$$

Similarly, $c_2 = , c_3 = ,..., c_p =$

THEOREM 5

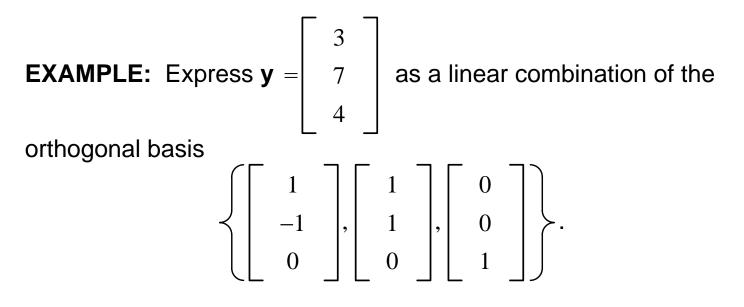
Let $\{\mathbf{u}_1, \mathbf{u}_2, \dots, \mathbf{u}_p\}$ be an orthogonal basis for a subspace *W* of \mathbf{R}^n . Then each **y** in *W* has a unique representation as a linear combination of $\mathbf{u}_1, \mathbf{u}_2, \dots, \mathbf{u}_p$. In fact, if

$$\mathbf{y} = c_1 \mathbf{u}_1 + c_2 \mathbf{u}_2 + \dots + c_p \mathbf{u}_p$$

then

$$c_j = \frac{\mathbf{y} \cdot \mathbf{u}_j}{\mathbf{u}_j \cdot \mathbf{u}_j} \qquad (j = 1, \dots, p)$$

3



Solution:

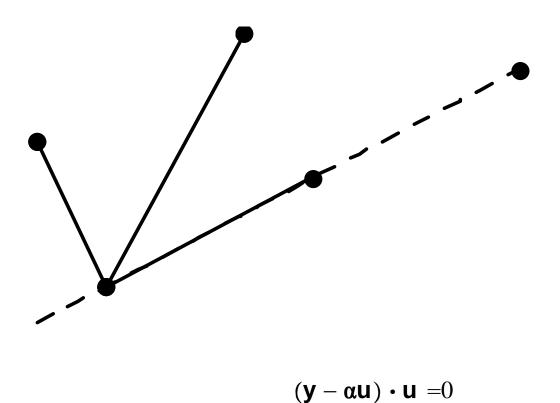
$$\frac{\mathbf{y} \cdot \mathbf{u}_1}{\mathbf{u}_1 \cdot \mathbf{u}_1} = \frac{\mathbf{y} \cdot \mathbf{u}_2}{\mathbf{u}_2 \cdot \mathbf{u}_2} = \frac{\mathbf{y} \cdot \mathbf{u}_3}{\mathbf{u}_3 \cdot \mathbf{u}_3} =$$

$$\mathbf{y} = \underline{\qquad} \mathbf{u}_1 + \underline{\qquad} \mathbf{u}_2 + \underline{\qquad} \mathbf{u}_3$$

Orthogonal Projections

For a nonzero vector \mathbf{u} in \mathbf{R}^n , suppose we want to write \mathbf{y} in \mathbf{R}^n as the the following

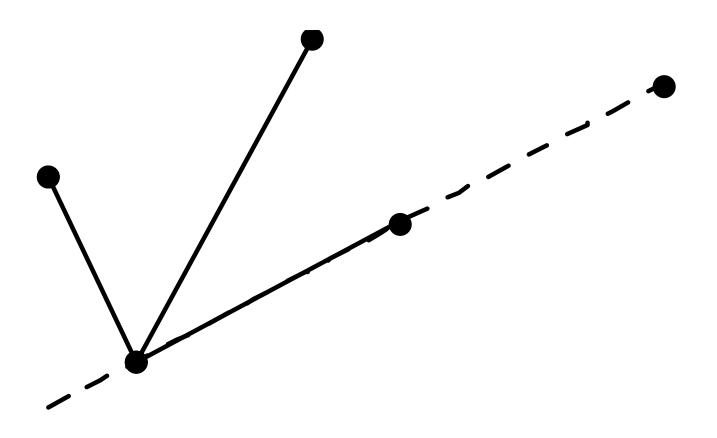
 $\mathbf{y} = ($ multiple of $\mathbf{u}) + ($ multiple a vector \perp to $\mathbf{u})$



 $\mathbf{y} \cdot \mathbf{u} - \mathbf{\alpha} (\mathbf{u} \cdot \mathbf{u}) = 0 \qquad \Rightarrow \qquad \alpha =$

 $\hat{y} = \frac{y \cdot u}{u \cdot u} u$ (orthogonal projection of y onto u) and

$$z = y - \frac{y \cdot u}{u \cdot u} u$$
 (component of y orthogonal to u)



EXAMPLE: Let
$$\mathbf{y} = \begin{bmatrix} -8 \\ 4 \end{bmatrix}$$
 and $\mathbf{u} = \begin{bmatrix} 3 \\ 1 \end{bmatrix}$. Compute the distance from \mathbf{y} to the line through $\mathbf{0}$ and \mathbf{u} .

Solution:

$$\hat{\mathbf{y}} = \frac{\mathbf{y} \cdot \mathbf{u}}{\mathbf{u} \cdot \mathbf{u}} \mathbf{u} =$$

Distance from \boldsymbol{y} to the line through $\boldsymbol{0}$ and $\boldsymbol{u}=$ distance from $\boldsymbol{\hat{y}}$ to \boldsymbol{y}

$$= \| \hat{\mathbf{y}} - \mathbf{y} \| =$$

Orthonormal Sets

A set of vectors $\{\mathbf{u}_1, \mathbf{u}_2, ..., \mathbf{u}_p\}$ in \mathbf{R}^n is called an **orthonormal set** if it is an orthogonal set of unit vectors.

If $W = \text{span}\{\mathbf{u}_1, \mathbf{u}_2, \dots, \mathbf{u}_p\}$, then $\{\mathbf{u}_1, \mathbf{u}_2, \dots, \mathbf{u}_p\}$ is an orthonormal basis for W.

Recall that **v** is a unit vector if $\|\mathbf{v}\| = \sqrt{\mathbf{v} \cdot \mathbf{v}} = \sqrt{\mathbf{v}^T \mathbf{v}} = 1$.

Suppose $U = \begin{bmatrix} \mathbf{u}_1 & \mathbf{u}_2 & \mathbf{u}_3 \end{bmatrix}$ where $\{\mathbf{u}_1, \mathbf{u}_2, \mathbf{u}_3\}$ is an orthonormal set.

It can be shown that $UU^T = I$ also. So $U^{-1} = U^T$ (such a matrix is called an **orthogonal matrix**).

THEOREM 6 An $m \times n$ matrix U has orthonormal columns if and only if $U^T U = I$.

THEOREM 7 Let *U* be an $m \times n$ matrix with orthonormal columns, and let **x** and **y** be in **R**^{*n*}. Then

a. $\|U\mathbf{x}\| = \|\mathbf{x}\|$

b.
$$(U\mathbf{x}) \cdot (U\mathbf{y}) = \mathbf{x} \cdot \mathbf{y}$$

c. $(U\mathbf{x}) \cdot (U\mathbf{y}) = 0$ if and only if $\mathbf{x} \cdot \mathbf{y} = 0$.

Proof of part b: $(U\mathbf{x}) \cdot (U\mathbf{y}) =$