### 2.3 Characterizations of Invertible Matrices

## Theorem 8 (The Invertible Matrix Theorem)

Let $A$ be a square $n \times n$ matrix. The the following statements are equivalent (i.e., for a given $A$, they are either all true or all false).
a. $A$ is an invertible matrix.
b. $A$ is row equivalent to $I_{n}$.
c. $A$ has $n$ pivot positions.
d. The equation $A \mathbf{x}=\mathbf{0}$ has only the trivial solution.
e. The columns of $A$ form a linearly independent set.
f. The linear transformation $\mathbf{x} \rightarrow A \mathbf{x}$ is one-to-one.
g. The equation $A \mathbf{x}=\mathbf{b}$ has at least one solution for each $\mathbf{b}$ in $\mathbf{R}^{n}$.
h. The columns of $A$ span $\mathbf{R}^{n}$.
i. The linear transformation $\mathbf{x} \rightarrow A \mathbf{x}$ maps $\mathbf{R}^{n}$ onto $\mathbf{R}^{n}$.
j. There is an $n \times n$ matrix $C$ such that $C A=I_{n}$.
k. There is an $n \times n$ matrix $D$ such that $A D=I_{n}$.
I. $A^{T}$ is an invertible matrix.

EXAMPLE: Use the Invertible Matrix Theorem to determine if $A$ is invertible, where

$$
A=\left[\begin{array}{rrr}
1 & -3 & 0 \\
-4 & 11 & 1 \\
2 & 7 & 3
\end{array}\right]
$$

Solution

$$
A=\left[\begin{array}{rrr}
1 & -3 & 0 \\
-4 & 11 & 1 \\
2 & 7 & 3
\end{array}\right] \sim \cdots \sim \underbrace{\left[\begin{array}{rrr}
1 & -3 & 0 \\
0 & -1 & 1 \\
0 & 0 & 16
\end{array}\right]}_{3 \text { pivots positions }}
$$

Circle correct conclusion: Matrix $A$ is / is not invertible.

EXAMPLE: Suppose $H$ is a $5 \times 5$ matrix and suppose there is a vector $\mathbf{v}$ in $\mathbf{R}^{5}$ which is not a linear combination of the columns of $H$. What can you say about the number of solutions to $H \mathbf{x}=\mathbf{0}$ ?

Solution $\quad$ Since $\mathbf{v}$ in $\mathbf{R}^{5}$ is not a linear combination of the columns of $H$, the columns of $H$ do not $\qquad$ $\mathbf{R}^{5}$.

So by the Invertible Matrix Theorem, $H \mathbf{x}=\mathbf{0}$ has

## Invertible Linear Transformations

For an invertible matrix $A$,

$$
\begin{aligned}
& A^{-1} A \mathbf{x}=\mathbf{x} \text { for all } \mathbf{x} \text { in } \mathbf{R}^{n} \\
& \quad \text { and } \\
& A A^{-1} \mathbf{x}=\mathbf{x} \text { for all } \mathbf{x} \text { in } \mathbf{R}^{n} .
\end{aligned}
$$

## Pictures:

A linear transformation $T: \mathbf{R}^{n} \rightarrow \mathbf{R}^{n}$ is said to be invertible if there exists a function $S: \mathbf{R}^{n} \rightarrow \mathbf{R}^{n}$ such that

$$
\begin{aligned}
S(T(\mathbf{x}))= & \mathbf{x} \text { for all } \mathbf{x} \text { in } \mathbf{R}^{n} \\
& \quad \text { and } \\
T(S(\mathbf{x}))= & \mathbf{x} \text { for all } \mathbf{x} \text { in } \mathbf{R}^{n} .
\end{aligned}
$$

Theorem 9
Let $T: \mathbf{R}^{n} \rightarrow \mathbf{R}^{n}$ be a linear transformation and let $A$ be the standard matrix for $T$. Then $T$ is invertible if and only if $A$ is an invertible matrix. In that case, the linear transformation $S$ given by $S(\mathbf{x})=A^{-1} \mathbf{x}$ is the unique function satisfying

$$
\begin{aligned}
S(T(\mathbf{x}))= & \mathbf{x} \text { for all } \mathbf{x} \text { in } \mathbf{R}^{n} \\
& \quad \text { and } \\
T(S(\mathbf{x}))= & \mathbf{x} \text { for all } \mathbf{x} \text { in } \mathbf{R}^{n} .
\end{aligned}
$$

