

Generating and Measuring Instances of Hard Semidefinite Programs

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Outline

- 1 SDP Background
 - Problem Statement
 - Theoretical/Numerical Difficulties in SDP
- 2 Hard SDP Instances
 - Definitions
 - Generating Hard SDP Instances
 - Generating Hard SDP Instances with Slater Condition
- 3 Measures for Strict Complementarity Nullity
- 4 Numerical Results
 - Randomly Generated Instances
 - Plots
 - Correlation Matrix
 - SDPLIB Instances
- 5 Conclusion

SDP Models

Primal SDP

$$\begin{array}{ll} (PSDP) & p^* := \min \quad \text{trace } CX \\ & \text{s.t. } \mathcal{A}(X) = b \\ & X \succeq 0 \end{array}$$

Dual SDP

$$\begin{array}{ll} (DSDP) & d^* := \max \quad b^T y \\ & \text{s.t. } \mathcal{A}^*(y) + Z = C \\ & Z \succeq 0, \end{array}$$

where $C, X, Z \in \mathcal{S}^n$, $n \times n$ real symmetric matrices, $y, b \in \mathbb{R}^m$,
(\succeq) \succ denotes positive (semi)definiteness.

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(Near) Loss of Slater Condition/Strict Feasibility

Primal/Dual Slater

- $\mathcal{A}(X) = b, X \succ 0$
- $\mathcal{A}^*(y) \prec C$

Theoretical/Numerical Difficulties

- Primal Slater condition implies strong duality, i.e. zero duality gap **AND** dual attainment.
- (Near) loss of strict feasibility is used as a measure in complexity theory. (e.g. Renegar/95, Freund/01, Lara and Tuncel/02)
- (Near) loss of strict feasibility correlates with number of iterations and loss of accuracy in interior-point methods (e.g. Freund/Ordóñez/Toh 2006)

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Loss of Strict Complementarity, (SC)

Strict Complementary Optimal Primal-Dual Pair

- There exists an optimal primal-dual pair X, Z such that

$$X + Z \succ 0$$

Theoretical Difficulties

- Convergence proofs for asymptotic quadratic superlinear convergence require SC.
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Other Theoretical/Numerical Difficulties

- The Primal-Dual: **Feasibility , Complementary Slackness Optimality Conditions** are overdetermined; symmetrizations to use Newton's method result in ill-posed problems.
- High accuracy solutions are hard/impossible to obtain; sparsity is hard to exploit; large scale is still an open area of research.

Hard SDP Instances/Definitions

Maximal Complementary Solution Pair:

- A primal-dual pair of optimal solutions $(\bar{X}, \bar{Z}) \in \mathcal{P}^* \times \mathcal{D}^*$ is called a maximal complementary solution pair to the problems (PSDP) and (DSDP), if the pair maximizes the sum $\text{rank}(X) + \text{rank}(Z)$ over all primal-dual optimal solution pairs (X, Z) .

Strict Complementarity Nullity:

- $g = n - \text{rank}(\bar{X}) - \text{rank}(\bar{Z})$, where (\bar{X}, \bar{Z}) is a maximal complementary solution pair

Hard SDP Instances:

- problems where strict complementarity fails (nullity is nonzero)

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Algorithm for Given Nullity g

Algorithm

- Given: positive integers $r > 0$ and $m > 1$: the rank of an optimum X and the number of constraints, resp.
- Let $Q = [Q_P | Q_N | Q_D]$ be an orthogonal matrix, where the dimensions of Q_P , Q_N , Q_D are $n \times r$, $n \times g$, $n \times (n - r - g)$, respectively, and $r > 0$. Construct positive semidefinite matrices X and Z as follows:

$$X := Q_P D_X Q_P^T, \quad Z := Q_D D_Z Q_D^T,$$

where D_X and D_Z are diagonal positive definite.

- cont...

Algorithm cont...

Algorithm cont...

- Define

$$A_1 = [Q_P | Q_N | Q_D] \begin{bmatrix} 0 & 0 & Y_2^T \\ 0 & Y_1 & Y_3^T \\ Y_2 & Y_3 & Y_4 \end{bmatrix} [Q_P | Q_N | Q_D]^T,$$

where Y_1 , Y_2 , Y_3 , and Y_4 are block matrices of appropriate dimensions, $Y_1 \succ 0$, Y_4 symmetric, and $Q_D Y_2 \neq 0$.

- Choose $A_i \in \mathcal{S}^n$, $i = 2, \dots, m$, such that $\{A_1 Q_P, A_2 Q_P, \dots, A_m Q_P\}$ is a linearly independent set. (Note that $A_1 Q_P = Q_D Y_2 \neq 0$.)
- Set $b := \mathcal{A}(X)$, $C := \mathcal{A}^*(y) + Z$,
 with $y \in \Re^m$ randomly generated.

Theorem for Generating Hard Instances

Theorem

The data (\mathcal{A}, b, C) constructed in the above algorithm gives a *hard* SDP instance with a strict complementarity nullity g .

Proof Outline

- Step 2 guarantees $X, Z \succeq 0, XZ = 0$ but strict complementarity fails.
- step 5 guarantees primal-dual feasibility, i.e. XZ are an optimal pair.
- Steps 3,4 guarantee X, Z are a maximal complementary solution pair.

Generating Hard Instances with Slater Condition

Corollary

With data (\mathcal{A}, b, C) constructed using above algorithm:

- 1 If the following additional condition on A_2 is satisfied

$$[Q_P | Q_N]^T A_2 [Q_P | Q_N] \succ 0,$$

then Slater's condition holds for the dual program (DSDP).

- 2 If the following additional conditions on $A_i, i = 1, \dots, m$, are satisfied,

$$\begin{aligned} \text{trace } Y_4 &= -\text{trace } Y_1 \\ \alpha > 0, \quad \text{trace } A_i X &= \alpha \text{trace } A_i, \quad i = 2, \dots, m, \end{aligned}$$

then $\hat{X} = \alpha I \succ 0$ is feasible for (PSDP).

Measures g_t, g_s, κ

g_t, g_s, κ

- $g_t := |\{w_i^d : T_l < w_i^d < T_u\}|$,
 where $w^d = \frac{1}{2}\lambda(X^{-1}Z + ZX^{-1})$; T_l, T_u are two tolerances.
 ($O(1)$ indicates nullity; $0, \infty$ otherwise)
- $g_s := |\{w_j^s : w_j^s \leq T\}|$, where $w^s := \frac{1}{2\sqrt{\mu}}\lambda(X + Z)$; T is a tolerance.
- (proposed by Freund, Ordóñez, and Toh.) given tolerance T , $T^s := \{j : w_j^s \leq T\}$.,

$$\kappa := - \sum_{j \in T^s} \ln(w_j^s) / |\{j : w_j^s \leq T\}|. \quad (1)$$

[small (large) for str. compl holds (fails)]

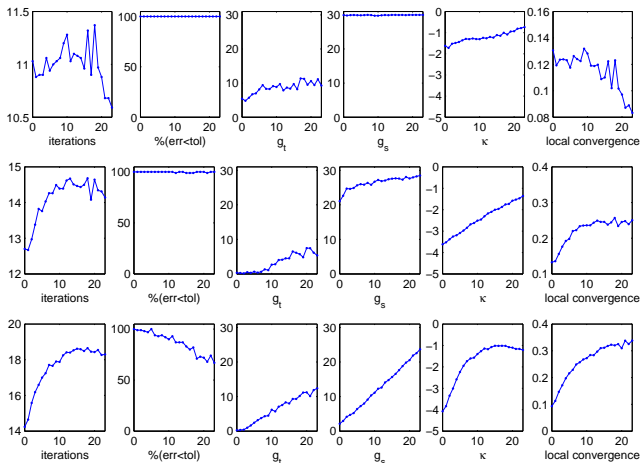
Randomly Generated Instances

Random Instances

- We generate 100 instances for each nullity value 0:23.
- The Slater conditions hold for both primal and dual.
- The x-axis of each figure represents the complementarity nullity ranging from 0 to 23.
- On y-axes from left to right:

iteration numbers; number of instances that satisfy the desired accuracy; measure g_t ; measure g_s ; measure κ ; local convergence rate.

Plots



Slater conditions hold; stop tolerances: 10^{-8} , 10^{-10} , 10^{-12}
 (using average of instances that attained desired accuracy)

Observations

Observations

- There is a *strong correlation* between the iteration number to achieve the desired stopping tolerance and the size of the complementarity nullity, when the accuracy requirement is high.
- Large nullity instances cause problems for SDPT3 solver.
- The measures g_t , g_s and κ all improve as the accuracy increases. Measure κ correlates well with the iteration number.
- Local asymptotic convergence rate is slower when nullity is larger.

Correlation Matrix

The local convergence rate is for stop tolerance is 10^{-12} .

| | Nullity | Iterations | g_t | g_s | κ | Cvg. Rate |
|------------|---------|------------|--------|--------|----------|-----------|
| Nullity | 1.0000 | 0.8341 | 0.9921 | 0.9993 | 0.8430 | 0.9263 |
| Iterations | 0.8341 | 1.0000 | 0.8417 | 0.8191 | 0.9958 | 0.9763 |
| g_t | 0.9921 | 0.8417 | 1.0000 | 0.9897 | 0.8567 | 0.9274 |
| g_s | 0.9993 | 0.8191 | 0.9897 | 1.0000 | 0.8280 | 0.9164 |
| κ | 0.8430 | 0.9958 | 0.8567 | 0.8280 | 1.0000 | 0.9785 |
| Cvg. Rate | 0.9263 | 0.9763 | 0.9274 | 0.9164 | 0.9785 | 1.0000 |

- nullity correlates well with iterations as well as local convergence rate.
- The measure κ has highest correlation with iterations.

SDPT3 Iteration Numbers on SDPLIB Instances

- Measures g_t , g_s and κ are applied on the SDPLIB instances.
- We only consider those SDP instances (47 such instances), where the error obtained was less than 10^{-7} . The correlation between the measures and the iteration numbers are:

$$\text{corr}(g_t, \text{its}) = 0.1472, \text{corr}(g_s, \text{its}) = 0.4509,$$

$$\text{and } \text{corr}(\kappa, \text{its}) = 0.4371.$$

- Low accuracy in solutions yield low correlations.

SDPLIB Instances

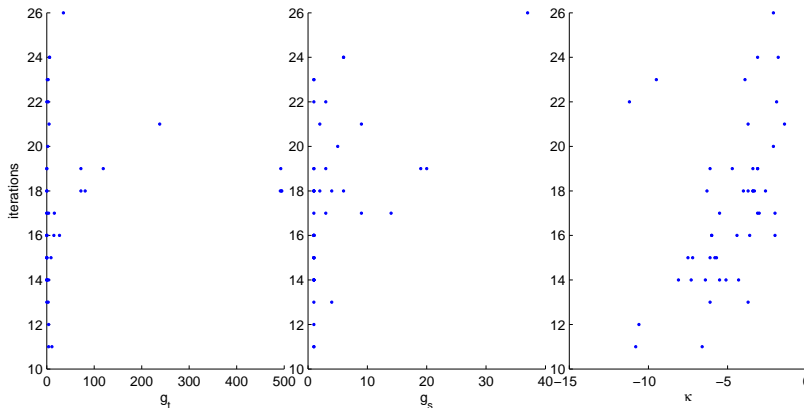


Figure: Scatter plots of g_t , g_s , κ versus # iterations for SDPLIB instances with attained tolerance $< 10^{-7}$.

Conclusion

Generating Hard Instances

We have presented an algorithm for generating hard SDP instances, i.e. problem instances where we can control the complementarity nullity, g .

Two Empirical Measures for g

We introduced two empirical measures g_t and g_s for g . These two measures provide accurate measurement of g if high accuracy solutions are used.

Measures: Positive Correlation with Numerical Difficulties

The numerical tests show: number of iterations and the numerical accuracy are positively correlated to g .

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