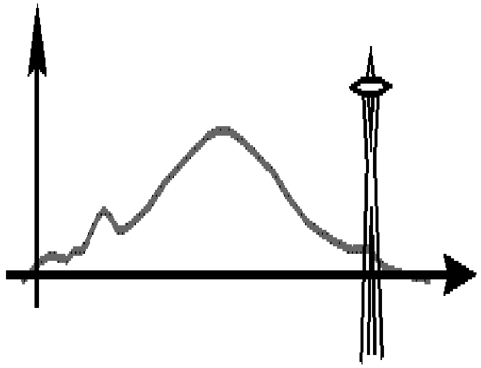
WEST COAST OPTIMIZATION MEETING: SPRING 2004



Robust Algorithms
for
Large Sparse Semidefinite Programming (SDP)

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Robust Solutions of Large Sparse Semidefinite Programming with Applications to the Nearest Euclidean Distance Matrix Problem

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OUTLINE

- Background on SDP; Notation and Motivation
- Robust, ('non-interior') path-following algorithm for SDP
  (outline of GN PCG method using LP)
- Application to Nearest Euclidean Distance Matrix Problem
- Numerics (Comparisons with a dual algorithm)

Notation and Motivation

$$
\text{(SDP)} \qquad \begin{array}{rl} \min & f(X) \\ \text{subject to} & \mathcal{A}X = b \\ & X \succeq 0, \end{array}
$$

where: $f : \mathcal{S}^n \to \mathbb{R}$ convex function

$\mathcal{S}^n$ $n \times n$ real symmetric matrices

$\mathcal{A} : \mathcal{S}^n \to \mathbb{R}^m$ linear operator,

$X(\succeq) \succ 0$ denotes positive (semi)definite

$\Big(\quad (\mathcal{A}X)_i = \langle A_i, X \rangle = \operatorname{trace} A_i X, \quad A_i = A_i^T, i = 1 \ldots n) \quad \Big)$

Linear Primal-Dual Pair of SDPs

(looks/behaves like Linear Program, LP)

$$
\text{(PSDP)} \qquad \begin{array}{rl} \min & \langle C, X\rangle = \operatorname{trace} CX \\ \text{subject to} & \mathcal{A}X = b \\ & X \succeq 0, \end{array}
$$

$$
\text{(SDP)} \qquad \begin{array}{rl} \max & b^T y \\ \text{subject to} & \mathcal{A}^* y + Z = C \\ & Z \succeq 0, \end{array}
$$

adjoint operator: $\mathcal{A}^* y = \sum_{i=1}^m y_i A_i$

(Perturbed) Optimality Conditions

For *barrier parameter* $\mu > 0$:

$$F_\mu(X, y, Z) := \begin{pmatrix} \mathcal{A}^* y + Z - C \\ \mathcal{A}X - b \\ ZX - \mu I \end{pmatrix} = 0 \qquad \begin{pmatrix} \text{dual feasibility} \\ \text{primal feasibility} \\ \text{pert. compl. slack.} \end{pmatrix}$$

For SDP:

$F_\mu : \mathcal{S}^n \times \Re^m \times \mathcal{S}^n \rightarrow \mathcal{S}^n \times \Re^m \times \mathcal{M}^n$

i.e. overdetermined nonlinear system

(Non) Interior Path-Following

Illustration/Motivation on LP Case

$$
\text{(LP)} \qquad \begin{array}{rll} p^* := & \min & c^T x \quad (\text{or } \langle c, x \rangle) \\ & \text{s.t.} & Ax = b \\ & & x \geq 0 \quad (\text{or } x \succeq 0) \end{array}
$$

$$
\text{(DLP)} \qquad \begin{array}{rll} d^* := & \max & b^T y \\ & \text{s.t.} & A^T y + z = c \\ & & z \geq 0 \quad (\text{or } z \succeq 0) \end{array}
$$

$A \in \Re^{m \times n}$ full rank (onto); LP and DLP strictly feasible

dual log-barrier problem with parameter $\mu > 0$ is

$$\text{(Dlogbarrier)} \qquad \begin{array}{rcll} d_\mu^* := & \max & b^T y + \mu \sum_{j=1}^n \log z_j & (+\mu \log\det(z)) \\ & \text{s.t.} & A^T y + z = c & \\ & & z > 0 & (z \succ 0). \end{array}$$

stationary point of the Lagrangian / optimality conditions

$$F_\mu(x,y,z) = \begin{pmatrix} A^T y + z - c \\ Ax - b \\ X - \mu Z^{-1} \end{pmatrix} = 0, \qquad \begin{array}{c} x, z > 0, \quad (\succ 0) \\ X = \mathrm{Diag}\,(x), \\ Z = \mathrm{Diag}\,(z) \end{array}$$

central path: set of these solutions $(x_\mu, y_\mu, z_\mu), \mu > 0$

As $\mu \to 0$, Jacobian $F'_\mu(x,y,z)$ grows ill-conditioned near central path

Cure/Fix: Make nonlinear equations *less nonlinear*, i.e. preconditioning for Newton type methods; premultiply by block-diag matrix with blocks (I, I, Z):

$$
\begin{aligned}
F_\mu(x,y,z) \leftarrow \begin{pmatrix} I & 0 & 0 \\ 0 & I & 0 \\ 0 & 0 & Z \end{pmatrix} F_\mu(x,y,z) \quad &= \quad \begin{pmatrix} A^T y + z - c \\ Ax - b \\ ZX - \mu I \end{pmatrix} \\
&=: \quad \begin{pmatrix} R_d \\ r_p \\ R_{ZX} \end{pmatrix}
\end{aligned}
$$

Special structure of linearized system can be exploited;

linearization for the Newton direction $\Delta s = \begin{pmatrix} \Delta x \\ \Delta y \\ \Delta z \end{pmatrix}$ is

$$F'_\mu(x,y,z)\Delta s = \begin{pmatrix} 0 & A^T & I \\ A & 0 & 0 \\ Z & 0 & X \end{pmatrix} \Delta s = -F_\mu(x,y,z).$$

overdetermined system in SDP case:

$$\mathcal{S}^n \times \Re^m \times \mathcal{S}^n \to \mathcal{S}^n \times \Re^m \times \mathcal{M}^n$$

apply symmetrization 'undoes preconditioning'

$$\begin{pmatrix} I & 0 & 0 \\ 0 & I & 0 \\ 0 & 0 & \mathcal{S} \end{pmatrix} \begin{pmatrix} 0 & A^T & I \\ A & 0 & 0 \\ Z & 0 & X \end{pmatrix}$$

e.g. last equation is linearization of:
$ZX + XZ - 2\mu I = 0$ (AHO search direction)

Reduction/Block Elimination for the Normal Equations

Step 1 (Eliminate Δz):

$$\begin{pmatrix} I & 0 & 0 \\ 0 & I & 0 \\ -X & 0 & I \end{pmatrix} \begin{pmatrix} 0 & A^T & I \\ A & 0 & 0 \\ Z & 0 & X \end{pmatrix} = \begin{pmatrix} 0 & A^T & I \\ A & 0 & 0 \\ Z & -XA^T & 0 \end{pmatrix}.$$

We let

$$P_Z = \begin{pmatrix} I & 0 & 0 \\ 0 & I & 0 \\ -X & 0 & I \end{pmatrix}, \quad K = \begin{pmatrix} 0 & A^T & I \\ A & 0 & 0 \\ Z & -XA^T & 0 \end{pmatrix}.$$

with right-hand side

$$
-\begin{pmatrix} I & 0 & 0 \\ 0 & I & 0 \\ -X & 0 & I \end{pmatrix} \begin{pmatrix} R_d \\ r_p \\ R_{ZX} - \mu e \end{pmatrix} = \begin{pmatrix} -R_d \\ -r_p \\ XR_d - R_{ZX} \end{pmatrix}
$$

Step 2 (Eliminate Δx):

$$F_n := P_n K \quad := \quad \begin{pmatrix} I & 0 & 0 \\ 0 & I & -AZ^{-1} \\ 0 & 0 & Z^{-1} \end{pmatrix} \begin{pmatrix} 0 & A^T & I \\ A & 0 & 0 \\ Z & -XA^T & 0 \end{pmatrix}$$

$$= \quad \begin{pmatrix} 0 & A^T & I_n \\ 0 & AZ^{-1}XA^T & 0 \\ I_n & -Z^{-1}XA^T & 0 \end{pmatrix}$$

$AZ^{-1}XA^T$ can have:

- uniformly bounded condition number, e.g. Güler et al 1993
- structured singularity, e.g. M. Wright 1997

But $\mathrm{cond}(F_n) \to \infty$.

The right-hand side becomes

$$-P_n P_Z \begin{pmatrix} R_d \\ r_p \\ R_{ZX} \end{pmatrix} =$$

$$\begin{pmatrix} -R_d \\ -r_p + A(x - Z^{-1} X R_d - \mu Z^{-1} e) \\ Z^{-1} X R_d - x + \mu Z^{-1} e \end{pmatrix}$$

Proposition The condition number of $F_n^T F_n$ diverges to infinity if $x(\mu)_i/z(\mu)_i$ diverges to infinity, for some i, as μ converges to 0. The condition number of $(F'_\mu)^T F'_\mu$ is uniformly bounded if there exists a unique primal-dual solution.

PROOF: Note that

$$F_n^T F_n = \begin{pmatrix} I_n & -Z^{-1}XA^T & 0 \\ -AXZ^{-1} & (AA^T + (AZ^{-1}XA^T)^2 + AZ^{-2}X^2A^T) & A \\ 0 & A^T & I_n \end{pmatrix}.$$

By interlacing of eigenvalues, ... ■

Corollary The condition number of F_n is at least $O(1/\mu)$. ■

EXAMPLE: $A = \begin{pmatrix} 1 & 1 \end{pmatrix}, c = \begin{pmatrix} -1 \\ 1 \end{pmatrix}, b = 1.$

$x^* = \begin{pmatrix} 1 \\ 0 \end{pmatrix}, y^* = -1, z^* = \begin{pmatrix} 0 \\ 2 \end{pmatrix};$

initial points: $x = \begin{pmatrix} 9.183012e-001 \\ 1.356397e-008 \end{pmatrix}, z = \begin{pmatrix} 2.193642e-008 \\ 1.836603e+000 \end{pmatrix},$

$y = -1.163398e+000.$

residuals and duality gap:

$\|r_b\| = 0.081699, \quad \|R_d\| = 0.36537, \quad \mu = x^T z/n = 2.2528e-008$

5 decimals rounding before/after arithmetic

centering with $\sigma = .1$

BUT: residuals are NOT order μ.

search directions found using full matrix F'_μ and backsolve matrix F_n:

$$\begin{pmatrix} \Delta x \\ \Delta y \\ \Delta z \end{pmatrix} = \begin{pmatrix} 8.17000e-02 \\ -1.35440e-08 \\ 1.63400e-01 \\ -2.14340e-08 \\ 1.63400e-01 \end{pmatrix}; \quad = \begin{pmatrix} -6.06210e+01 \\ -1.35440e-08 \\ 1.63400e-01 \\ 0.00000e+00 \\ 1.63400e-01 \end{pmatrix}$$

error in Δy is small; error after backsubstitution for $(\Delta x)_1$ is large.

$$\begin{pmatrix} AZ^{-1}XA^T \\ -Z^{-1}XA^T \end{pmatrix} = \begin{pmatrix} 4.18630e+07 \\ -4.18630e+07 \\ -7.38540e-09 \end{pmatrix}$$

Alternate Second Step; Stable Reduction

Assuming! $A = [I_m \ E]$.

Partition diagonal matrix Z, X using vectors

$z = \begin{pmatrix} z_m \\ z_v \end{pmatrix}, x = \begin{pmatrix} x_m \\ x_v \end{pmatrix}$, $XA^T = \begin{pmatrix} X_m \\ X_v E^T \end{pmatrix}$

$$
\begin{aligned}
F_s : \quad &= \quad P_s K = \begin{pmatrix} I_n & 0 & 0 & 0 \\ 0 & I_m & 0 & 0 \\ 0 & -Z_m & I_m & 0 \\ 0 & 0 & 0 & I_v \end{pmatrix} \begin{pmatrix} 0 & 0 & A^T & I_n \\ I_m & E & 0 & 0 \\ Z_m & 0 & -X_m & 0 \\ 0 & Z_v & -X_v E^T & 0 \end{pmatrix} \\
&= \quad \begin{pmatrix} 0 & 0 & A^T & I_n \\ I_m & E & 0 & 0 \\ 0 & -Z_m E & -X_m & 0 \\ 0 & Z_v & -X_v E^T & 0 \end{pmatrix}.
\end{aligned}
$$

The right-hand side becomes

$$
\begin{aligned}
-P_s P_Z \begin{pmatrix} A^T y + z - c \\ Ax - b \\ ZXe - \mu e \end{pmatrix} &= -P_s \begin{pmatrix} R_d \\ r_p \\ -XR_d + ZXe - \mu e \end{pmatrix} \\
&= \begin{pmatrix} -R_d \\ -r_p \\ -Z_m r_p - X_m (R_d)_m + Z_m X_m e - \mu e \\ -X_v (R_d)_v + Z_v X_v e - \mu e \end{pmatrix}
\end{aligned}
$$

Summary: Path-following and NOT Interior-point

• staying interior is a heuristic for staying within a neighbourhood of the central path

• staying interior is required for numerical accuracy when solving the *current* ill-conditioned reduced systems

(Nearest) Euclidean Distance Matrix Completion using SDP

Given:
pre-distance matrix $A \in \mathcal{S}^n$ (nonnegative with zero diagonal)
weight matrix $H \in \mathcal{S}^n$:

$$\text{(NEDM)} \quad \mu^* = \min \frac{1}{2} \|H \circ (A - D)\|_F^2 \text{ subject to: } D \in \text{EDM}$$

$\text{EDM} = \{D = (d_{ij}) \in \mathcal{S}^n : d_{ij} = \|x_i - x_j\|^2, \text{ for some } x_i \in \Re^k\}$, k is *embedding dimension*

Applications e.g. molecular conformation problems in chemistry; multidimensional scaling and multivariate analysis problems in statistics; genetics, geography, ...

Mixed-Cone Formulation

direct approach using a mixed SDP and second-order (or Lorentz) cone problem:

$$
\begin{array}{ll}
\min & \alpha \\
\text{s.t.} & Y = H \circ (\mathcal{L}(X) - A), \;\; \|Y\|_F \leq \alpha \\
& X \in \mathcal{S}^{n-1}, Y \in \mathcal{S}^{n}, X \in \mathrm{SDP}
\end{array}
$$

where $X \in SDP \Rightarrow \mathcal{L}(X) \in \mathrm{EDM}$
(Public domain software packages are available)

$$B = [x_1 \ x_2 \ \ldots \ x_n], \quad k \times n$$

$$D_{ij} = \|x_i - x_j\|^2 = -2x_i^T x_j + \|x_i\|^2 + \|x_j\|^2$$

$$D = -2B^T B + e\left(\operatorname{diag}\left(B^T B\right)\right)^T + \left(\operatorname{diag}\left(B^T B\right)\right) e^T$$

With $X = B^T B \succeq 0$
connection between SDP and EDM .

Operator Notation:

us2vec , us2Mat , svec , sMat

$$x = \operatorname{svec}(X) \in \mathbb{R}^{\binom{n+1}{2}}, \quad X = \operatorname{sMat}(x)$$

$\sqrt{2}$ times vector (columnwise) from upper-triang of X.

$\binom{n+1}{2} = n(n+1)/2$; $\sqrt{2}$ guarantees isometry.

sMat $:=$ svec $^{-1}$ mapping into $\mathcal{S}^n$

adjoint transformation sMat $^* =$ svec :

$$\begin{aligned} \langle \operatorname{sMat}(v), S \rangle &= \operatorname{trace} \operatorname{sMat}(v) S \\ &= v^T \operatorname{svec}(S) = \langle v, \operatorname{svec}(S) \rangle \end{aligned}$$

$$D \text{ is EDM} \quad (\subset \mathcal{S}^n)$$

$$\boxed{\textit{iff}}$$

$$D = \mathcal{L}(X) := \begin{pmatrix} 0 & \operatorname{diag}(X)^T \\ \operatorname{diag}(X) & \operatorname{diag}(X)e^T + e\operatorname{diag}(X)^T - 2X \end{pmatrix},$$

$$\text{for some } X \succeq 0, X \in \mathcal{S}^{n-1}$$

(e is vector of ones)

$$\mathcal{L} : \mathcal{S}^{n-1} \to \mathcal{S}^n, \quad \mathcal{L}(\mathcal{S}_+^{n-1}) = \text{EDM}$$

with partition:

$$D = \begin{bmatrix} \alpha & d^T \\ d & \bar{D} \end{bmatrix},$$

where $\alpha \in \mathbb{R}$

$$\mathcal{L}^*(D) = 2\left(\mathrm{Diag}\,(d) + \mathrm{Diag}\,(\bar{D}e) - \bar{D}\right)$$

$$\mathcal{L}^\dagger(D) = \frac{1}{2}\left(de^T + ed^T - \bar{D}\right)$$

$$\mathcal{L}^*, \mathcal{L}^\dagger : \mathcal{S}^n \to \mathcal{S}^{n-1}, \quad \mathcal{L}^\dagger(EDM) = \mathcal{S}_+^{n-1}$$

Duality and Optimality Conditions

(using $X = \mathrm{sMat}\,(x) + I$) an equivalent problem is:

$$\mu^* := \min \frac{1}{2}\|H \circ (A - \mathcal{L}(X))\|_F^2 \quad \text{subject to} \quad X \succeq 0$$

strong (Lagrangian) duality holds (Slater's holds for primal and holds for dual if the graph is complete)

$$\mu^* = \nu^* := \max_{\Lambda \succeq 0} \min_{X} \frac{1}{2}\|H \circ (A - \mathcal{L}(X))\|_F^2 - \operatorname{trace} \Lambda X$$

change to **Wolfe dual** and obtain optimality conditions:

$$\begin{array}{rcll} X & := & \mathrm{sMat}\,(x) \succeq 0 & \text{(primal feasibility)} \\ \Lambda & := & \mathcal{L}^* \left\{ H^{(2)} \circ (\mathcal{L}(X)) \right\} - C, \quad \Lambda \succeq 0 & \text{(dual feasibility)} \\ \Lambda X & := & 0 & \text{(complementary slack.)} \end{array}$$

eliminate Λ

exact primal-dual feasibility during iterations

full rank Jacobian at optimality.

single bilinear (perturbed) equation in x; $\quad F_\mu(x) : \mathbb{R}^{\binom{n}{2}} \to \mathcal{M}^{n-1}$

$$\boxed{F_\mu(x) := \left[\mathcal{L}^* \left\{H^{(2)} \circ (\mathcal{L}(X))\right\} - C\right] X - \mu I = 0}$$

typical SDP - overdetermined system of bilinear equations

current approach is to symmetrize - which results in ill-conditioning!

from rank deficient Jacobian at optimality.

BUT, here, no symmetrization used;

solve using (an inexact) Gauss-Newton method - with PCG

Let $\mathcal{W}(x) := \mathcal{L}^* \left\{ H^{(2)} \circ (\mathcal{L}(x)) \right\}$

Linearization for search direction Δx at current $x = \operatorname{svec}(X)$:

$$\boxed{F'_\mu(x)\Delta x = \left[\mathcal{W}(x) - C\right]\Delta x + \left[\mathcal{W}(\Delta x)\right]X}$$

This is a linear, full rank, overdetermined system.

Our search direction Δx is its (approx.) least squares solution.

Algorithm: p-d i-e-p framework

- **Initialization:**
  - •• **Input data:** a pre-distance $n \times n$ matrix A
  - •• **Positive tolerances:**

$$\epsilon_1 \text{ (stopping)}, \; \epsilon_2 \text{ (lss accuracy)}, \; \epsilon_3 \text{ (crossover)},$$

  - •• **Find initial strictly feasible points:** both $X^0, \Lambda^0 := (\mathcal{W}(X) - C) \;\succ\; 0; \mu > 0$
  - •• **Set initial parameters:**

$$\text{gap} = \operatorname{trace} \Lambda^0 X^0; \quad \mu = \text{gap}/n; \quad \text{objval} = f(X^0); \quad k = 0.$$

- **while** $\min\{\frac{\text{gap}}{\text{objval}+1}, \text{objval}\} > \epsilon_1$

•• **solve lss for search direction** (accuracy $\epsilon_2 \min\{\mu, 1\}$)

$$F'_{\sigma\mu}(x^k)\left(\Delta x^k\right) = -F_{\sigma\mu}(x^k),$$

where σ_k centering, $\mu_k = \frac{1}{n}\mathrm{trace}\,(\mathcal{W}(X^k) - C)X^k$

$$X^{k+1} = X^k + \alpha_k \Delta X^k, \quad \alpha_k > 0,$$

so that both $X^{k+1}, (\mathcal{W}(X^{k+1}) - C) \succeq 0$

($\alpha_k = 1$ after the crossover.)

•• **update**

$$k \leftarrow k+1 \quad \text{and then}$$

$$\sigma_k \quad \left(\text{set } \sigma_k = 0 \text{ if } \min\{\frac{\text{gap}}{\text{objval}+1}, \text{objval}\} < \epsilon_3\right)$$

• **end (while)**.

• **Conclusion:** $D = \mathcal{L}(X) \in \mathrm{EDM}$ is approx. to A

After the **crossover**, centering $\sigma = 0$ and steplength $\alpha = 1$, we get q-quadratic convergence; allows for *warm starts*.

Long steps can be taken *beyond* the positivity boundary. (tests show improved convergence rates)

Preconditioning

$$(\Lambda + \mathcal{X}\mathcal{W})\, P^{-1}(\widehat{\Delta x}) = -F_\mu(x),$$

where

$$\widehat{\Delta x} = P(\Delta x)$$

Diagonal Preconditioning

Optimal scaling Dennis and W. (1993) full rank matrix $A \in \mathbb{R}^{m \times n}$, $m \geq n$, with condition number $\omega(K) := n^{-1}\mathrm{trace}\,(K)/\det(K)^{1/n}$, the optimal scaling

$$\min \omega((AD)^T(AD)) \quad \text{subject to: } D \text{ positive and diagonal}$$

solution: $d_{ii} = 1/\|A_{:i}\|_2, i = 1, \ldots, n$

explicit expressions for preconditioner
inexpensive

diagonal operator P; evaluate using columns of $F'_\mu(v)$.
$k \cong (i,j),\ 1 \le i < j \le n$, strictly upper triangular part

$$
\begin{aligned}
\|(\Lambda + \mathcal{X}\mathcal{W})(e_k)\|_F^2 &= \|\Lambda(e_k)\|_F^2 + \|(\mathcal{W}(e_k))X\|_F^2 \\
&\quad + \langle \Lambda(E_{ij}), (\mathcal{W}(E_{ij}))X \rangle \,,
\end{aligned}
$$

where

$$
\Lambda(e_k) = \begin{cases} \frac{1}{\sqrt{2}} \left(\Lambda_{:i} e_j^T + \Lambda_{:j} e_i^T \right), & \text{if } i < j \\ \left(\Lambda_{:i} e_i^T \right), & \text{if } i = j. \end{cases}
$$

and $\mathcal{X}\mathcal{W}$ ..... inexpensive - 50% reduction in LSQR iterations

Numerical Tests

Pentium 4; MATLAB 6.5; 1 GIG RAM.

crossover heuristic: relative duality gap $< .1$.

Stopping criteria (relative duality gap) $< \epsilon_1 = 1e - 10$.
(But - average accuracy attained $1e - 13$, q-quadratic convergence.)

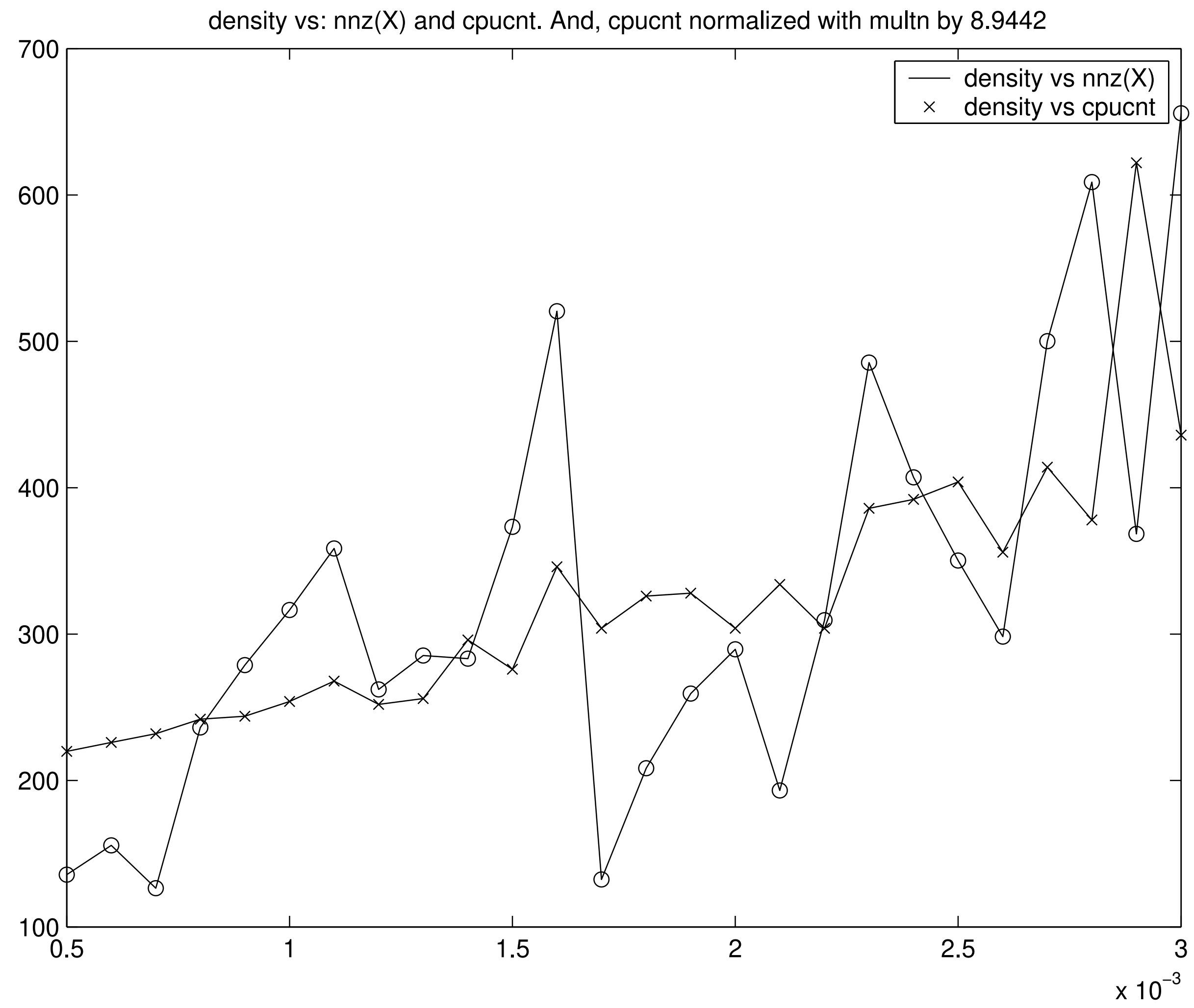

Figure 0.1: density .0005:.001:.003, CPU times and nnz(Λ), n=200

Conclusion

Gauss-Newton direction:

Advantages/Disadvantages:

- Robust, warm starts are simple, longer steps
- exact primal and dual feasibility at each iteration
- Can apply CG-type approaches
- q-quadratic convergence
- scale-invariant on the right

Future:

- Need large sparse QR efficient as Cholesky
- predictor-corrector