

CO781 / QIC 890:

Theory of Quantum Communication

Topics 4, part 2

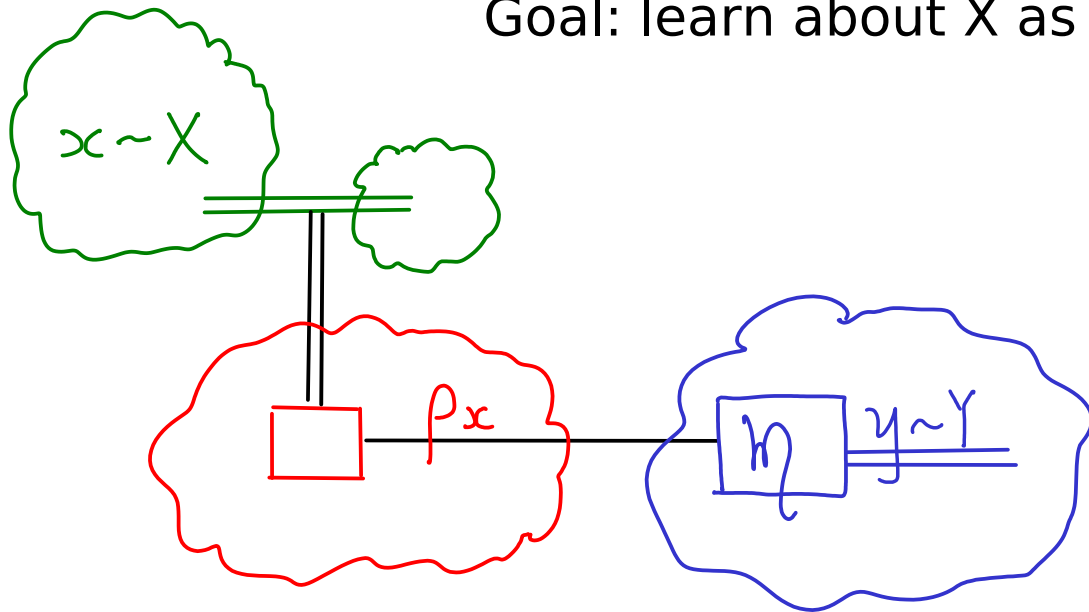
Encoding classical information in quantum states
and retrieving it

Scenario 1: accessible information

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Scenarios of encoding classical data into quantum states & retrieving it

Goal: learn about X as much as possible via rv Y .



e.g.

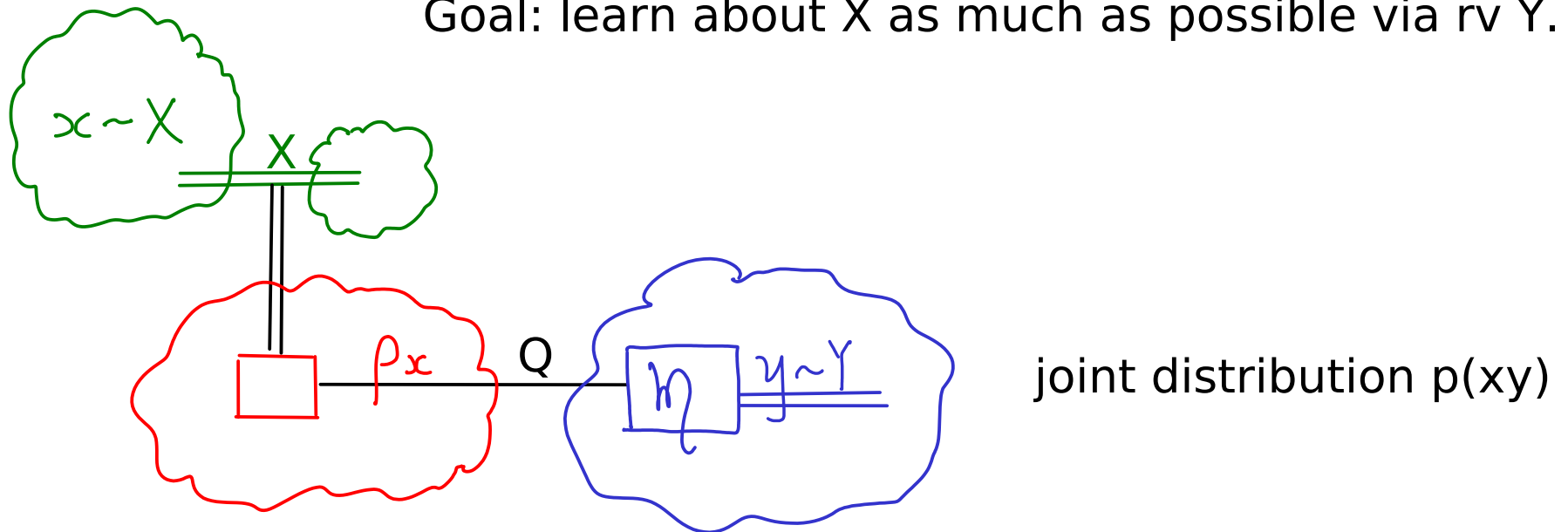
X: time elapsed	Atomic clock	Time reported
X: black hole	Telescopes generating squeezed states	Detector sees signals
X: oracles	Quantum circuit	meas giving comp answer
X: message	Alice's encoding map + noisy quantum channels	Bob's decoder giving decoded message

Scenarios: who controls each of the steps, measure of success ...

Scenario 0: no control throughout -- a draw of XY .

Scenarios of encoding classical data into quantum states & retrieving it

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Scenario 1: accessible information / states discrimination

p_x , ρ_x predetermined

Richard draws x with prob $p(x)$, prepares ρ_x , gives state to Bob
Bob picks measurement

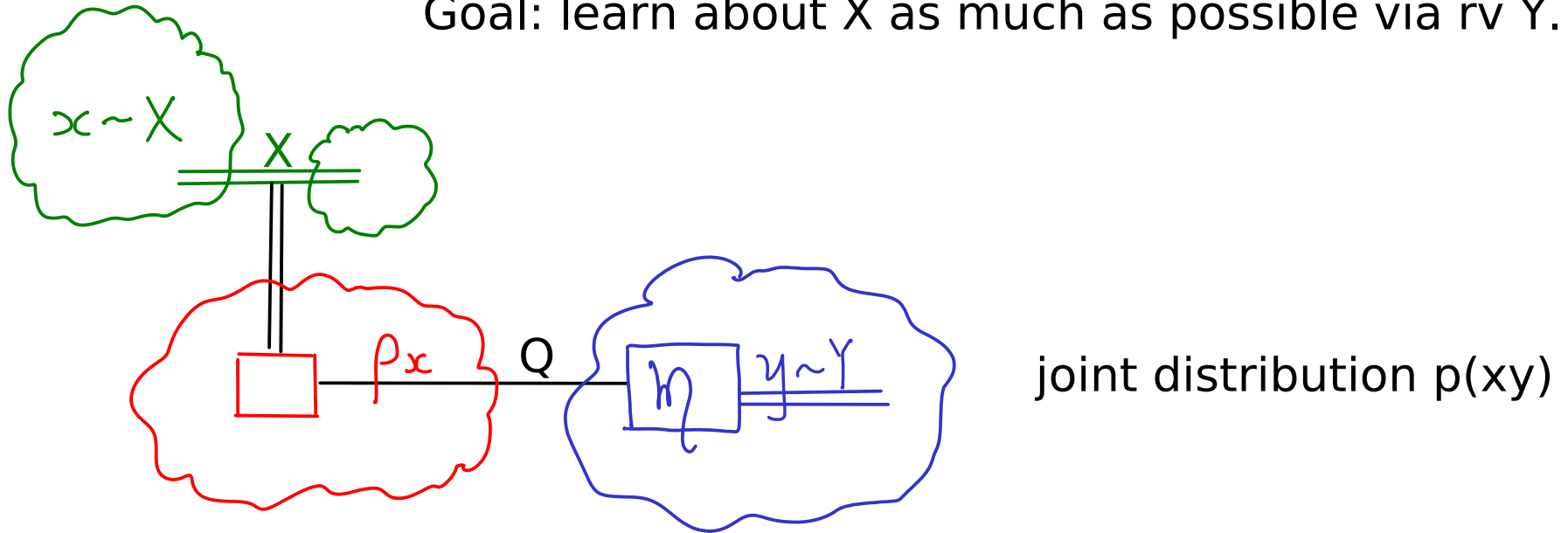
(a) max prob($X=Y$): state discrimination

(b) max $I(X:Y)$: accessible information

today

Scenarios of encoding classical data into quantum states & retrieving it

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Scenario 2: classical channel

ρ_x , \mathcal{M} predetermined POVM $\{M_y\}$, $M_y \geq 0$, $\sum_y M_y = I$

Alice chooses x ,

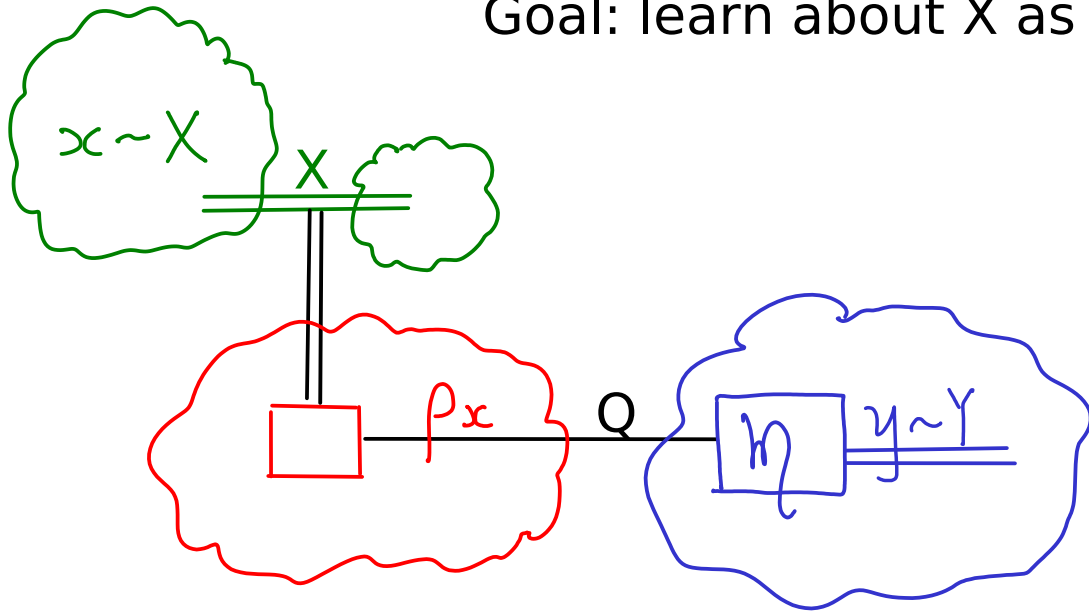
corresponding state ρ_x generated, and measured (with fixed meas),
outcome is given to Bob.

For each x , Bob receives y with prob $p(y|x) = \text{tr } M_y \rho_x$

Last week: for large number of uses,
can create $\max_x I(X:Y)$ cbits per use

Scenarios of encoding classical data into quantum states & retrieving it

Goal: learn about X as much as possible via rv Y .



Q box \xrightarrow{x} \square ρ_x

as if Alice presses a button "x" and Q box spits out ρ_x to Bob

Scenario 3: Q box

ρ_x predetermined

Alice chooses x ,

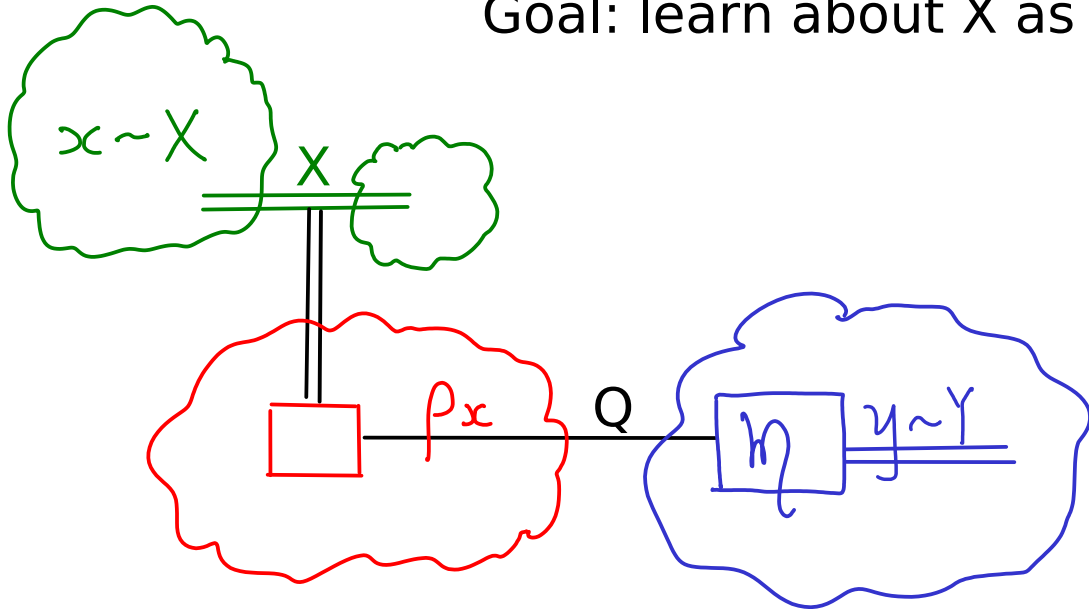
corresponding state ρ_x generated and available to Bob.

Bob picks measurement and obtains y .

If Bob sticks to optimal meas for $I(X:Y)$ for each system, this reduces to scenario 2.

Scenarios of encoding classical data into quantum states & retrieving it

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Q box \xrightarrow{x} \square ρ_x

as if Alice presses a button "x" and Q box spits out ρ_x to Bob

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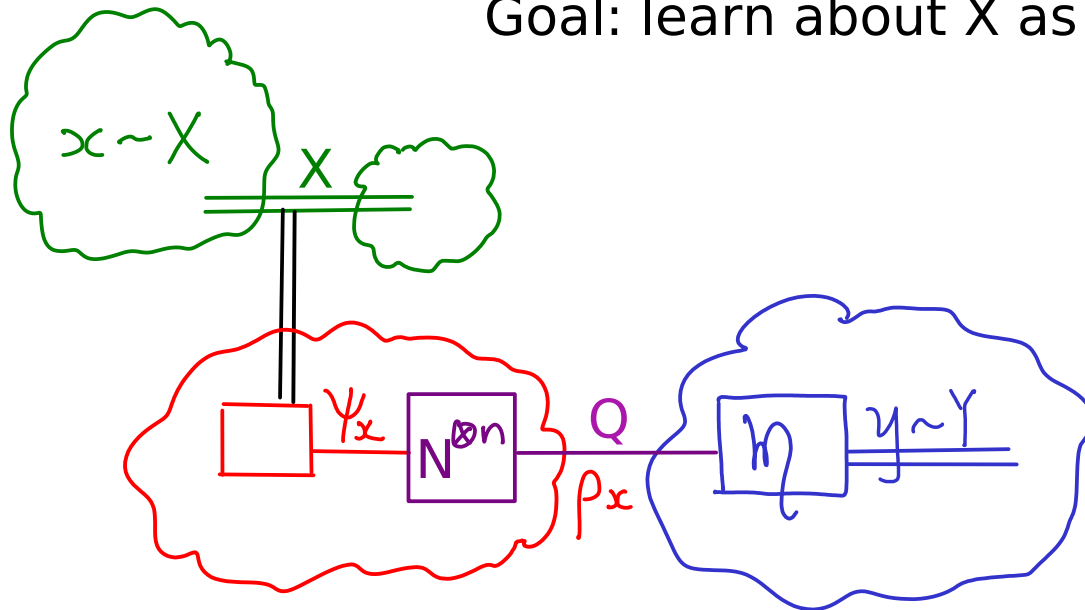
Scenario 3: for multiple uses, Bob can choose JOINT measurement.

Next Tue: for large number of uses of Q boxes, can create $S(X:Q)$

cbits per use, for $\Lambda = \sum_x p_x |x\rangle\langle x|_X \otimes \rho_{xQ}$.

Scenarios of encoding classical data into quantum states & retrieving it

Goal: learn about X as much as possible via rv Y .



Scenario 4: classical capacity of quantum channel
given N

Alice chooses x , and Ψ_x (the input to n uses of N)

ρ_x is the channel output available to Bob.

Bob picks measurement and obtains y .

Scenario 4: for multiple uses, Bob can choose JOINT measurement.

Optimized: $C(N)$ classical capacity of quantum channel N (next Thur).

Definition:

Let $\Lambda = \sum_x p_x |x\rangle\langle x|_X \otimes \rho_{xQ}$.

\mathcal{M} measurement on Q with output space Y

The accessible information for ensemble $\mathcal{E} = \{p_x, \rho_{xQ}\}$ is

$$I_{\text{acc}}(\mathcal{E}) := \max_{\mathcal{M}} I(X:Y)_{\mathcal{I} \otimes \mathcal{M}(\Lambda)}$$

Example 1. $x = 0, 1, p(0) = p(1) = 1/2,$

$$\rho_x = |\Psi_x\rangle\langle\Psi_x|, \quad |\Psi_0\rangle = a|0\rangle + b|1\rangle$$

$$|\Psi_1\rangle = a|0\rangle - b|1\rangle$$

$$a, b \geq 0, \quad a^2 + b^2 = 1$$

(most general form of 2 arbitrary pure states)

Optimal measurement:

projective, along basis $\{|+\rangle, |-\rangle\}$

Levitin 95, or Fuchs PhD thesis 96 (Ch3.5)

$$p(x=0 | y=+) = p(x=0) p(y=+ | x=0)$$

$$\frac{1}{2} \quad \text{tr} |+\rangle\langle+| \rho_0 |+\rangle\langle+| = \left(\frac{a}{\sqrt{2}} + \frac{b}{\sqrt{2}} \right)^2 = \frac{1}{2} (a^2 + b^2 + 2ab) = \frac{1}{2} + ab$$

$$p(x=1 | y=+) = \frac{1}{2} (\frac{1}{2} - ab)$$

$$p(y=+) = 1/2,$$

$$p(x=0 | y=+) = 1/2 + ab$$

$$p(x=1 | y=+) = 1/2 - ab$$

$$H(X | y=+) = h(1/2 + ab)$$

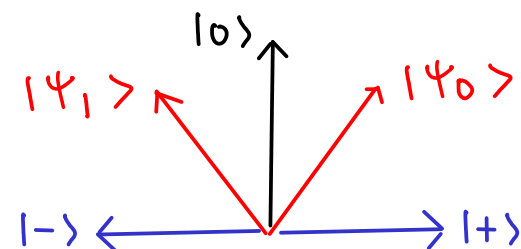
Similarly,

$$p(y=-) = 1/2,$$

$$H(X | y=-) = h(1/2 - ab) = h(1/2 + ab)$$

$$\therefore H(X|Y) = p(y=+) H(X|y=+) + p(y=-) H(X|y=-) = h(1/2 + ab)$$

$$I_{acc} = I(X:Y) = H(X) - H(X|Y) = 1 - h(1/2 + ab)$$



How to optimize measurement for lacc?

1. Unknown for most ensembles

For the few ensembles (highly symmetric) with known optimal measurements, there is no simple proof of optimality :(

How to optimize measurement for lacc?

2. EB Davies, IEEE Trans Info Th, 24, p596, 1978

For any ensemble of states in d dimensions, $\mathcal{E} = \{\rho_x, p_x\}$
optimal measurement has POVM $\mathcal{M} = \{M_y\}_{y=1}^n$ with

(a) $\text{rank}(M_y) = 1$ and

(b) $d \leq n \leq d^2$

Proof (a): If $M_y = \sum_k M_{y,k}$ is a decomp into rank 1 matrices

replace measurement \mathcal{M} with POVM $\{M_y\}$

by new measurement \mathcal{M}' with POVM $\{M_{y,k}\}$. outcome has 2 parts

eg \mathcal{M} : $M_0 = \frac{1}{2}|0\rangle\langle 0| + \frac{1}{3}|+\rangle\langle +|$ ($y=0$)

$$M_1 = \frac{1}{5}|1\rangle\langle 1| + \frac{1}{2}|-\rangle\langle -|$$
 ($y=1$)

$$M_2 = \frac{4}{5}|1\rangle\langle 1| + \frac{1}{6}|+\rangle\langle +|$$
 ($y=2$)

$$\mathcal{M}': M_{0,0} = \frac{1}{2}|0\rangle\langle 0| \quad (y=0, k=0) \quad M_{0,1} = \frac{1}{3}|+\rangle\langle +| \quad (y=0, k=1)$$

$$M_{1,0} = \frac{1}{5}|1\rangle\langle 1| \quad (y=1, k=0) \quad M_{1,1} = \frac{1}{2}|-\rangle\langle -| \quad (y=1, k=1)$$

$$M_{2,0} = \frac{4}{5}|1\rangle\langle 1| \quad (y=2, k=0) \quad M_{2,1} = \frac{1}{6}|+\rangle\langle +| \quad (y=2, k=1)$$

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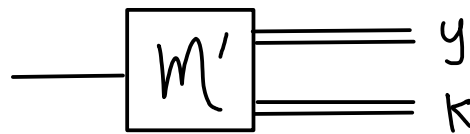
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if we discard k ,
 we perform \mathcal{M}

$$\therefore \text{lacc}(\mathcal{E}) \underset{\substack{\uparrow \\ \text{given} \\ \mathcal{M} \text{ optimal}}}{=} I(X:Y)_{\mathcal{I} \otimes \mathcal{M}(\Lambda)} = I(X:Y)_{\mathcal{I} \otimes \mathcal{M}'(\Lambda)} \left(\leq \right) I(X:YK)_{\mathcal{I} \otimes \mathcal{M}'(\Lambda)} \left(\leq \right) \text{lacc}$$

$\sum_x p_x |x\rangle\langle x| \otimes \rho_x$

q info proc-
 essing ineq

equal and \mathcal{M}'
 also optimal

How to optimize measurement for lacc?

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For any ensemble of states in d dimensions, $\mathcal{E} = \{p_x, \rho_x\}$
optimal measurement has POVM $\mathcal{M} = \{M_y\}_{y=1}^n$ with

(a) $\text{rank}(M_y) = 1$ and

(b) $d \leq n \leq d^2$

Proof (b): see e.g., Watrous book, or 1904.10985 Corollary 5.

Based on:

Caratheodory's Theorem:

Let $S \subseteq \mathbb{R}^t$, $\text{conv}(S)$ convex hull of S .

Then, any $x \in \text{conv}(S)$ is a convex combination of at most $t+1$ elements of S .

How to optimize measurement for lacc?

3. EB Davies, IEEE Trans Info Th, 24, p596, 1978
Sasaki, Barnett, Jozsa, Osaki, Hirota 9812062
Decker 0509122

Informally: many equiprobable ensembles of states with symmetry have optimal measurement with the same symmetry.

How to optimize measurement for lacc?

3. Ensembles with symmetry

Example 2. Define the ensemble ξ , with

$$p(0) = p(1) = p(2) = 1/3, \quad \rho_x = |\psi_x\rangle\langle\psi_x|, \quad |\psi_0\rangle = |0\rangle$$

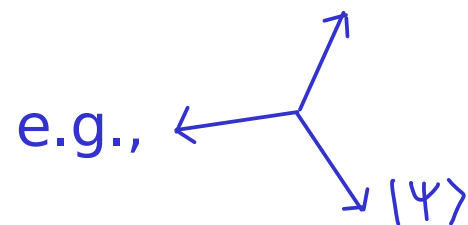
$$|\psi_1\rangle = \cos\frac{\pi}{3}|0\rangle + \sin\frac{\pi}{3}|1\rangle$$

$$|\psi_2\rangle = \cos\frac{\pi}{3}|0\rangle - \sin\frac{\pi}{3}|1\rangle$$

9812062: optimal meas has POVM

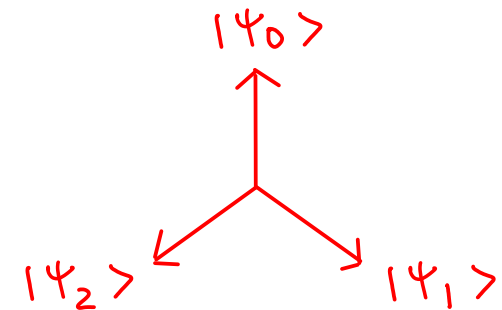
$$M_i = \left\{ M_k = \frac{2}{3} R^k |\psi\rangle\langle\psi| R^{k\dagger} \right\}_{k=0,1,2}$$

where $R = e^{i\sigma_y \frac{2}{3}\pi}$ (note $R^k |\psi_0\rangle = |\psi_k\rangle$)



Ex: optimal

$$|\psi\rangle = |\psi_0^\perp\rangle = |1\rangle.$$



(the trine or "Mercedes" states)

So, $M_0 = |\psi_0^\perp\rangle\langle\psi_0^\perp| = |1\rangle\langle 1|$

$$M_1 = |\psi_1^\perp\rangle\langle\psi_1^\perp|, \quad |\psi_1^\perp\rangle = \sin\frac{\pi}{3}|0\rangle - \cos\frac{\pi}{3}|1\rangle$$

$$M_2 = |\psi_2^\perp\rangle\langle\psi_2^\perp|, \quad |\psi_2^\perp\rangle = \sin\frac{\pi}{3}|0\rangle + \cos\frac{\pi}{3}|1\rangle$$

How to optimize measurement for lacc?

3. Ensembles with symmetry

Example 2. Define the ensemble \mathcal{E}_1 with

$$p(0) = p(1) = p(2) = 1/3, \quad \rho_x = |\psi_x\rangle\langle\psi_x|, \quad |\psi_0\rangle = |0\rangle$$

$$M_1 = \{M_k\}_{k=0,1,2}$$

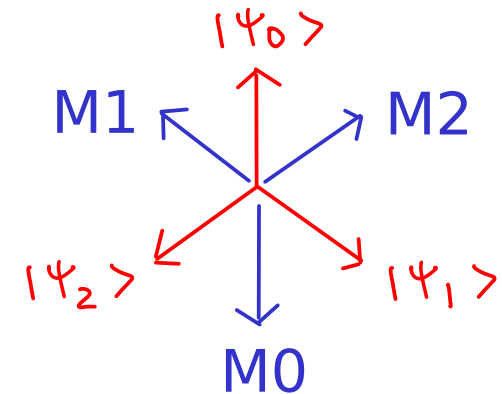
$$M_0 = |\psi_0^\perp\rangle\langle\psi_0^\perp| = |1\rangle\langle 1|$$

$$M_1 = |\psi_1^\perp\rangle\langle\psi_1^\perp|, \quad |\psi_1^\perp\rangle = \sin\frac{\pi}{3}|0\rangle - \cos\frac{\pi}{3}|1\rangle$$

$$M_2 = |\psi_2^\perp\rangle\langle\psi_2^\perp|, \quad |\psi_2^\perp\rangle = \sin\frac{\pi}{3}|0\rangle + \cos\frac{\pi}{3}|1\rangle$$

$$|\psi_1\rangle = \cos\frac{\pi}{3}|0\rangle + \sin\frac{\pi}{3}|1\rangle$$

$$|\psi_2\rangle = \cos\frac{\pi}{3}|0\rangle - \sin\frac{\pi}{3}|1\rangle$$



Ex: find $\text{pr}(y|x)$ for all x,y .

$$\text{If } y=0, \quad \text{pr}(x=0|y=0) = 0$$

$$\text{pr}(x=1|y=0) = \text{pr}(x=2|y=0) = 1/2, \quad \text{so } H(X|y=0) = 1.$$

$$H(X|Y) = p(y=0) H(X|y=0) + p(y=1) H(X|y=1) + p(y=2) H(X|y=2) = 1$$
$$\frac{1}{3} \cdot 1 \quad \frac{1}{3} \cdot 1 \quad \frac{1}{3} \cdot 1$$

$$\text{lacc} = H(X) - H(X|Y) = (\log 3) - 1 = 0.5850.$$

How to optimize measurement for Iacc?

4. Additivity of accessible info on product ensembles

$$\text{Let } \tilde{\mathcal{F}}_1 = \{ \rho(x_1), \rho_{x_1} \}, \tilde{\mathcal{F}}_2 = \{ \rho(x_2), \rho_{x_2} \}$$

The product ensemble of $\tilde{\mathcal{F}}_1, \tilde{\mathcal{F}}_2$ is

$$\tilde{\mathcal{F}}_1 \otimes \tilde{\mathcal{F}}_2 = \{ \rho(x_1) \rho(x_2), \rho_{x_1} \otimes \rho_{x_2} \}$$

$$\text{Represent } \tilde{\mathcal{F}}_1 \text{ by } \Lambda_1 = \sum_{x_1} \rho(x_1) |x_1\rangle\langle x_1| \otimes \rho_{x_1}$$

$$\tilde{\mathcal{F}}_2 \text{ by } \Lambda_2 = \sum_{x_2} \rho(x_2) |x_2\rangle\langle x_2| \otimes \rho_{x_2}$$

$$\tilde{\mathcal{F}}_1 \otimes \tilde{\mathcal{F}}_2 \text{ by } \sum_{x_1, x_2} \rho(x_1) \rho(x_2) |x_1\rangle\langle x_1| \otimes |x_2\rangle\langle x_2| \otimes \rho_{x_1} \otimes \rho_{x_2} = \Lambda_1 \otimes \Lambda_2$$

$X_1 \quad X_2 \quad Q_1 \quad Q_2$

$$\text{Thm. } \mathcal{I}_{\text{acc}}(\tilde{\mathcal{F}}_1 \otimes \tilde{\mathcal{F}}_2) = \mathcal{I}_{\text{acc}}(\tilde{\mathcal{F}}_1) + \mathcal{I}_{\text{acc}}(\tilde{\mathcal{F}}_2)$$

joint meas
allowed but
not needed

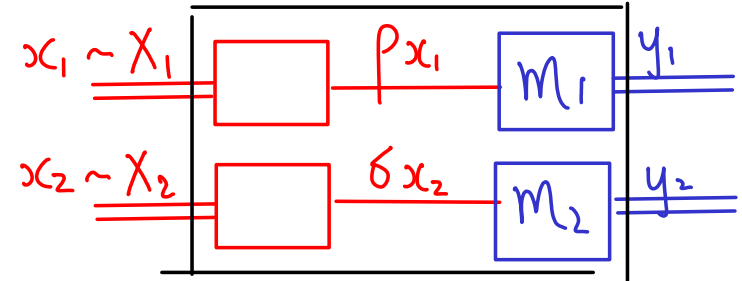
Idea: applying the optimal measurement of $\tilde{\mathcal{F}}_1$ on Q_1 ,
and the optimal measurement of $\tilde{\mathcal{F}}_2$ on Q_2 ,
is optimal for $\tilde{\mathcal{F}}_1 \otimes \tilde{\mathcal{F}}_2$

Thm. $I_{acc}(\tilde{F}_1 \otimes \tilde{F}_2) = I_{acc}(\tilde{F}_1) + I_{acc}(\tilde{F}_2)$

Proof: $\lceil \geq \rceil$ suffices to find a measurement for $\tilde{F}_1 \otimes \tilde{F}_2$ achieving mutual information given by RHS.

Let $\mathcal{M}_1, \mathcal{M}_2$ be optimal meas for \tilde{F}_1, \tilde{F}_2 with outputs Y_1, Y_2 .

We now analyse the mutual info between $X_1 X_2$ and $Y_1 Y_2$ if $\mathcal{M}_1 \otimes \mathcal{M}_2$ is applied to Q1Q2 of ensemble $\tilde{F}_1 \otimes \tilde{F}_2$



$I_{acc}(\tilde{F}_1 \otimes \tilde{F}_2) \geq I(X_1 X_2 : Y_1 Y_2)$

$I_{\otimes} I_{\otimes} \mathcal{M}_1 \otimes \mathcal{M}_2 (\Lambda)$

X1 independent of X2
 Y1 independent of Y2
 X1Y1 independent of X2Y2

$= H(X_1 X_2) + H(Y_1 Y_2) - H(X_1 X_2 Y_1 Y_2)$

$= H(X_1) + H(X_2) + H(Y_1) + H(Y_2) - H(X_1 Y_1) - H(Y_1 Y_2)$

$= [H(X_1) + H(Y_1) - H(X_1 Y_1)]_{I_{\otimes} \mathcal{M}_1(\lambda_1)} + [H(X_2) + H(Y_2) - H(Y_1 Y_2)]_{I_{\otimes} \mathcal{M}_2(\lambda_2)}$

reduced states of $I_{\otimes} I_{\otimes} \mathcal{M}_1 \otimes \mathcal{M}_2 (\Lambda = \Lambda_1 \otimes \Lambda_2)$

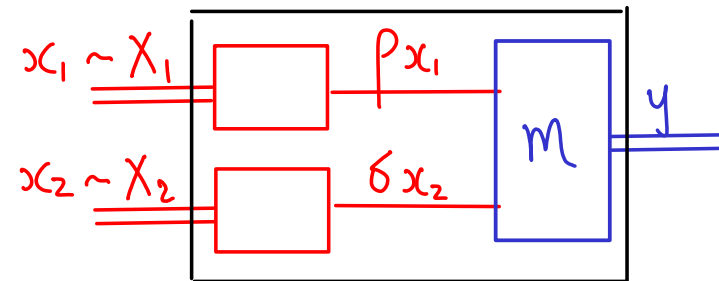
$= I(X_1:Y_1)_{I_{\otimes} \mathcal{M}_1(\lambda_1)} + I(X_2:Y_2)_{I_{\otimes} \mathcal{M}_2(\lambda_2)}$

$= I_{acc}(\tilde{F}_1) + I_{acc}(\tilde{F}_2)$ (by optimality of $\mathcal{M}_1, \mathcal{M}_2$)

Thm. $I_{acc}(\mathcal{F}_1 \otimes \mathcal{F}_2) = I_{acc}(\mathcal{F}_1) + I_{acc}(\mathcal{F}_2)$

Proof: $[\leq]$

Let \mathcal{M} be any meas on $Q_1 \times Q_2$ with output space Y



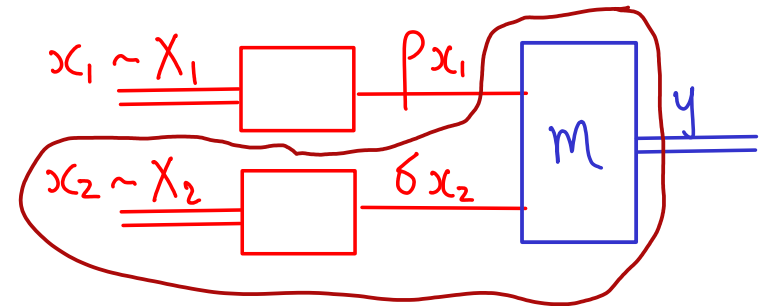
$$I(X_1 X_2 : Y) = I(X_1 : Y) + I(X_2 : Y | X_1)$$

$$\begin{aligned}
 & H(X_1 X_2) + H(Y) - H(X_1 X_2 Y) \\
 & \quad - H(X_1 Y) \\
 & \quad + H(Y) \\
 & \quad - H(X_1 Y) \\
 & \quad H(X_2 | X_1) - H(X_2 | X_1 Y) \\
 & = H(X_1 X_2) - H(X_1) - H(X_2 | X_1 Y) + H(X_1 Y)
 \end{aligned}$$

Thm. $I_{acc}(\tilde{\mathcal{F}}_1 \otimes \tilde{\mathcal{F}}_2) = I_{acc}(\tilde{\mathcal{F}}_1) + I_{acc}(\tilde{\mathcal{F}}_2)$

Proof: $[\leq]$


Let \mathcal{M} be any meas on $Q_1 Q_2$ with output space Y



$I(X_1 X_2 : Y) = I(X_1:Y) + I(X_2:Y|X_1)$

$H(X_1 X_2) + H(Y) - H(X_1 X_2 Y) = H(X_1) + H(Y) - H(X_1 Y) + H(X_2|X_1) - H(X_2|X_1 Y) = H(X_1 X_2) - H(X_1) - H(X_2 X_1 Y) + H(X_1 Y)$

(1) if X_1, X_2 independent, drawing state from $\tilde{\mathcal{F}}_2$ is part of meas of Q_1

 is a measurement on Q_1 prepared in the ensemble $\tilde{\mathcal{F}}_1$

$\therefore I(X_1:Y) \leq I_{acc}(\tilde{\mathcal{F}}_1)$

(2) 2nd term $\sum_{x_1} p(x_1) I(X_2:Y | X_1=x_1) \leq \max_{x_1} I(X_2:Y | X_1=x_1) \leq I_{acc}(\tilde{\mathcal{F}}_2)$

$\therefore \forall \mathcal{M}. I(X_1 X_2 : Y) \leq I_{acc}(\tilde{\mathcal{F}}_1) + I_{acc}(\tilde{\mathcal{F}}_2)$ prepare best ρ_{x_1} as part of meas of Q_2

$\therefore I_{acc}(\tilde{\mathcal{F}}_1 \otimes \tilde{\mathcal{F}}_2) \leq I_{acc}(\tilde{\mathcal{F}}_1) + I_{acc}(\tilde{\mathcal{F}}_2)$

Tue

adaptive, vs joint A3

locking A3

upper bound by holevo info

holevo bound

araki lieb two-way holevo bound