# On the Parameterized Complexity of Deletion to *H*-free Strong Components

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MFCS 2020

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#### 2 Preliminaries

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DIRECTED FEEDBACK VERTEX SET **Input:** Directed graph D, integer k**Output:** Does there exist a set S of size at most k such that D - S is acyclic?

Best known FPT algorithm:  $O^*(k!4^k)$  (here  $O^*$  notation suppresses polynomial factors)

Improving this is a big open problem in parameterized complexity.

Recent work by Göke et al. [CIAC 2019] designs FPT algorithms for related problems.

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BOUNDED SIZE STRONG COMPONENT VERTEX DELETION **Input:** Directed graph D, integers k, s **Output:** Does there exist a set S of size at most k such that every strong component of D - S contains at most s vertices?

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Göke et al. gave a  $2^{O(k^3)}n^{O(1)}$  algorithm for the first problem and a  $4^k(ks + k + s)!n^{O(1)}$  algorithm for the second one.

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We generalize these problems to a more unified framework.

 $\mathcal{H}$ -FREE STRONG CONNECTED COMPONENT DELETION **Input:** Directed graph D, integer k, finite family of graphs  $\mathcal{H}$  **Output:** Does there exist a set S of at most k vertices such that every strong component of D-S does not have a subgraph isomorphic to any graph  $\mathcal{H}$ 

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BOUNDED SIZE STRONG COMPONENT VERTEX DELETION. Here  $\mathcal{H}$  is an independent set on s + 1 vertices.

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• A 2<sup>O(k<sup>3</sup> log k)</sup> n<sup>O(h)</sup> algorithm for when each graph in H has a 'rooted' property. Here h is the maximum size amognst all graphs in H.

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- A 2<sup>O(k log k)</sup> n<sup>O(1)</sup> algorithm for 1-OUT REGULAR VERTEX DELETION.

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Last two results improve on the bounds given by Göke et al.

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## This talk

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The  $2^{O(k^3 \log k)} n^{O(1)}$  algorithm for when  $\mathcal{H}$  contains a path is based upon a reduction to the rooted case.

Algorithms for 1-OUT REGULAR VERTEX DELETION and BOUNDED SIZE STRONG COMPONENT VERTEX DELETION are based upon similar ideas.

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3 Reducing to the partioned problem



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For an S-T separator C, we define R(S, C) to be the set of vertices reachable from S after the deletion of C.

Important property. There is a unique minimum 'closest' separator i.e. there is a unique minimum S-T separator C such that  $R(S, C) \subseteq R(S, C')$  for all other minimum S-T separators C'.

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Symmetrically, there is a unique minimum 'furthest' separator i.e. separator C such that  $R(S, C) \supseteq R(S, C')$  for all other minimum S-T separators C'.

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A minimum S-T separator C is said to *cover* another minimum S-T separator C' if  $R(S, C) \supseteq R(S, C')$ .

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A minimum S-T separator C is said to *tightly cover* another minimum S-T separator C' if  $R(S, C) \supseteq R(S, C')$  and there is no other minimum S-T separator C'' such that  $R(S, C) \supseteq R(S, C'') \supseteq R(S, C')$ .

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#### Lemma (Pushing Routine)

Given a minimum S-T separator C, in polynomial one can either

- Compute a minimum S-T separator C' that tightly covers C
- Conclude that there is no such C', i.e. C is the unique furthest minimum separator.

Neogi, Ramanujan, Saurabh, Sharma

 $\mathcal{H}$ -free SCC Deletion

#### Important Separators

For a graph *D* and subsets  $S, T \subseteq V(G)$ , an *S*-*T* separator *C* is said to be *important* if there is no other *S*-*T* separator *C'* such that  $|C'| \leq |C|$  and  $R(S, C') \supseteq R(S, C)$ .

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#### Lemma

There are at most  $4^k$  important separators of size at most k, and they can be enumerated in  $O^*(4^k)$  time.

Fundamental lemma for designing FPT algorithms for cut problems.

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#### Lemma

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Fundamental lemma for designing FPT algorithms for cut problems.

Prove something of the form "If there exists a solution, then there is a solution that contains an important separator", then branch on the  $4^k$  important separators.

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Turns out that this property is very helpful in designing algorithms for the  $\mathcal{H}$ -FREE SCC DELETION problem.

We will look at the special case when each graph in  $\mathcal{H}$  is rooted.

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 $\mathcal{H}$ -free SCC Deletion

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Using the technique of Iterative Compression, it suffices to solve the disjoint version of the problem.

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Using the technique of Iterative Compression, it suffices to solve the disjoint version of the problem.

DISJOINT ROOTED  $\mathcal{H}$ -FREE SCC DELETION **Input:** Graph D, integer k, finite family of graphs  $\mathcal{H}$  where every graph is *rooted*, and solution  $W \subseteq V(D)$  of size k + 1**Output:** Does there exist a solution of size k that is disjoint from W

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I.e. Vertices of W in the same strongly connected components D - X correspond to vertices in the same partition, and a partition come before another partition in the ordering if that strong component comes before the other in the topological ordering of D - X.

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We start by guessing this ordered partition on W!

Now the problem reduces to the following: Given an ordered partition on  $W = (W_1, \ldots, W_q)$ , find a solution X that is disjoint from W and of size k such that the aforementioned topological ordering of D - X induces same ordered partition on W.

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Now the problem reduces to the following: Given an ordered partition on  $W = (W_1, \ldots, W_q)$ , find a solution X that is disjoint from W and of size k such that the aforementioned topological ordering of D - X induces same ordered partition on W.

That is, if  $W_i$  and  $W_j$  are sets in the partition with i > j then we want to kill all paths from  $W_i$  to  $W_j$  and deal with subgraphs isomorphic to a graph in  $\mathcal{H}$  that we encounter.

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- 4 Solving the partitioned problem

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Eventually when  $\lambda = k$ , either k must drop or we can conclude that is a NO-instance once  $\lambda > k$ , since every solution must contain an S-T separator.

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In the second case, the minimum S-T separator size  $\lambda$  increases because we add a vertex to T

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However any S- $(T \cup \{r\})$  separator *cannot* cover C since  $r \in R(S, C)$ . Thus the minimum S- $(T \cup \{r\})$  separator size must be greater than  $\lambda$ .

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- Conclude that there is no such C', i.e. C is the unique furthest minimum separator.

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- Picking a vertex  $v \in F$  into our solution
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Turns out by guessing which vertices of C that are reachable or unreachable in the final solution, we gain enough information to make progress in case 2 also.

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- What about algorithms for other families  $\mathcal{H}$ ? Is it possible to design an FPT algorithm for every such  $\mathcal{H}$ ?
- What about infinite families?
- Recent result by Göke, Marx and Mnich [ICALP 2020] shows that one can design an FPT algorithm for when H is the set of cycles of length greater than some integer s.

## Thank You

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