

Matrix Completions

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Simple Completion Problem

Hermitian positive semidefinite completion

Given: $A = A^* \succeq 0$, with $\text{diag}(A) > 0$.

Consider the *completion problem*

$$\max \{ \det(B) : B \succeq 0, \text{diag}(B) = \text{diag}(A) \}.$$

(Hadamard's Inequality: $\det(B) \leq \prod_{i=1}^n B_{ii}$) implies maximum occurs when B^{-1} , and so B , is diagonal.

Proof? Optimum is interior! Differentiate log-det !!

$$0 = \nabla \left(\log \det(B) + \sum_i \lambda_i \text{trace } E_{ii}(B - A) \right) = B^{-1} + \sum_i \lambda_i E_{ii}$$

I.e., B^{-1} must be diagonal.

$2k + 1$ bands are specified in A

$a_{ij} \forall |i - j| \leq k$ are fixed; all principal submatrices within $2k + 1$ bands are positive definite.

THEOREM (Dym and Gohberg, 1981)

1 If

$$\mathcal{D}_k = \{B : B \succeq 0, b_{ij} = a_{ij}, \forall |i - j| \leq k\},$$

then $\mathcal{D}_k \neq \emptyset$.

2 $\max \{\det(B) : B \in \mathcal{D}_k\}$ occurs at the unique matrix $B \in \mathcal{D}_k$ having the property that for all $|i - j| \geq k + 1$, the (i, j) -entry of B^{-1} equals 0.

Partial Hermitian Matrix, $A = A^*$, Completion

components $A_{ij}, ij \in \mathcal{E}$ are specified (fixed) (others free)

$$A = A(\mathcal{G}), \quad \text{undirected graph } \mathcal{G} = (N, \mathcal{E})$$

positive semidefinite completion problem

find components $A_{ij}, ij \notin \mathcal{E}$, such that the resulting matrix $A \succeq 0$, is positive semidefinite.

Definitions:

- 1 chordal graph: no minimal cycles of length ≥ 4 .
- 2 A graph \mathcal{G} is completable if and only if any \mathcal{G} -partial positive definite matrix has a positive definite completion.

THEOREMS (GJSW, 1984)

- 1 \mathcal{G} is completable if and only if \mathcal{G} is chordal.
- 2 Suppose that $\text{diag}(A)$ is fixed and $A(\mathcal{G})$ has a positive definite completion. Then there is a unique such completion, B , with maximum determinant; and it is characterized by B^{-1} having 0 components in positions corresponding to all $kl \notin \mathcal{E}$.

Best Approximate Completion Problem

Let $H = H^T \succeq 0$ be matrix of weights with $\text{diag}(H) > 0$; let $A = A^*$ be given given Hermitian matrix; let \mathcal{L} be a linear transformation;

$$f(P) := \|H \circ (A - P)\|_F^2,$$

(Hadamard product, Frobenius norm)

$$\begin{array}{ll} \text{(AC)} & \mu^* := \min \\ & \text{subject to } \begin{array}{l} f(P) \\ \mathcal{L}P = b \\ P \succeq 0, \end{array} \end{array}$$

Optimal Solution \bar{P} of AC in Unconstrained Case

$$\nabla f(\bar{P}) \in (\mathcal{S}_+^n - \bar{P})^+ \quad (\text{polar cone})$$

THEOREM

The matrix $\bar{P} \succeq 0$ solves AC if and only if

$$\text{trace}(H^{(2)} \circ (\bar{P} - A))(P - \bar{P}) \geq 0, \quad \forall P \succeq 0,$$

where $H^{(2)} = H \circ H$ is the Hadamard squared term.

COROLLARIES

- 1 If $H = E$, the matrix of ones, then the (unique) optimal solution of AC is $\bar{P} = A_{\succ}$, where A_{\succ} is the positive part of A in the Loewner partial order.
- 2 If $H \succ 0$, then the (unique) optimal solution \bar{P} of AC is the solution of

$$H \circ \bar{P} = (H \circ A)_{\succ}.$$

General Constrained Case

Lagrangian

For $\Lambda \in \mathcal{H}^n$ (Hermitian) and $y \in \mathcal{C}^m$, let

$$L(P, y, \Lambda) = f(P) + \langle y, b - \mathcal{L}P \rangle - \text{trace } \Lambda P$$

denote the *Lagrangian* of AC.

primal program AC is equivalent to

$$\mu^* = \min_P \max_{\substack{y \\ \Lambda \succeq 0}} L(P, y, \Lambda).$$

Assume generalized Slater's constraint qualification

$$\exists P \succ 0 \text{ with } \mathcal{L}P = b,$$

holds for AC.

Lagrangian Dual

Then

$$\mu^* = \max_{\substack{y \\ \Lambda \succeq 0}} \min_P L(P, y, \Lambda)$$

differentiate and get the Wolfe dual

(DAC)

$$\begin{aligned} \mu^* := & \max & f(P) + \langle y, b - \mathcal{L}P \rangle - \text{trace } \Lambda P \\ & \text{subject to} & \nabla f(P) - \mathcal{L}^* y - \Lambda = 0 \\ & & \Lambda \succeq 0. \end{aligned}$$

THEOREM

Primal-Dual Framework!!

The matrix $\bar{P} \succeq 0$ and vector-matrix $\bar{y}, \bar{\lambda} \succeq 0$ solve AC and DAC if and only if

$$\begin{array}{ll} \mathcal{L}\bar{P} = b & \text{primal feas} \\ 2H^{(2)} \circ (\bar{P} - A) - \mathcal{L}^*\bar{y} - \bar{\lambda} = 0 & \text{dual feas} \\ \text{trace } \bar{\lambda}\bar{P} = 0 & \text{compl slack} \end{array}$$

compl slack value = duality gap value

Optimal solution of AC

Solve the two equations

$$\bar{P} - (\bar{P} - 2H^{(2)} \circ (\bar{P} - A) + \mathcal{L}^*y)_{\gamma} = 0$$

and

$$\mathcal{L} \left(\bar{P} - 2H^{(2)} \circ (\bar{P} - A) + \mathcal{L}^*y \right)_{\gamma} = b.$$

Suppose $A = 0$ and $H = \frac{1}{\sqrt{2}}E$.

the optimal solution of AC is:

$$\bar{P} = (\mathcal{L}^*y)_{\gamma},$$

where

$$\mathcal{L} (\mathcal{L}^*y)_{\gamma} = b.$$

Unconstrained - Using only Weights

$$2H^{(2)} \circ (P - A) - \Lambda = 0$$

dual feas

$$-P + \mu\Lambda^{-1} = 0$$

perturbed compl slack

Note

$$H_{ij} = 0 \text{ (} P_{ij} \text{ free)} \Rightarrow \Lambda_{ij} = 0$$

(dual variable Λ takes role of P^{-1})

Linearization of the second equation

$$-(P + h) + \mu\Lambda^{-1} - \mu\Lambda^{-1}I\Lambda^{-1} = 0$$

We get

$$h = \mu\Lambda^{-1} - \mu\Lambda^{-1}I\Lambda^{-1} - P.$$

and

$$I = \frac{1}{\mu} \{-\Lambda(P + h)\Lambda\} + \Lambda$$

Linearization of the dual feasibility equation

$$2H^{(2)} \circ h - I = -(2H^{(2)} \circ (P - A) - \Lambda).$$

Eliminate the primal step h and solve for the dual step l

$$\begin{aligned}l &= 2H^{(2)} \circ h + (2H^{(2)} \circ (P - A) - \Lambda) \\ &= 2H^{(2)} \circ (\mu\Lambda^{-1} - \mu\Lambda^{-1}l\Lambda^{-1} - P) \\ &\quad + (2H^{(2)} \circ (P - A) - \Lambda).\end{aligned}$$

Newton equation

$$2H^{(2)} \circ (\mu\Lambda^{-1}l\Lambda^{-1}) + l = 2H^{(2)} \circ (\mu\Lambda^{-1} - A) - \Lambda.$$

or equivalently

$$\begin{aligned}&[2 \text{Diag}(\text{vec}(H^{(2)}))\mu(\Lambda^{-1} \otimes \Lambda^{-1}) + I] \text{vec}(l) \\ &= \text{vec}(2H^{(2)} \circ (\mu\Lambda^{-1} - A) - \Lambda).\end{aligned}$$

Matrix Representations

F denotes $k \times 2$ matrix with row s denoting the s -th nonzero element of H

for $s = 1, \dots, k$: $(F_{s1}, F_{s2})_{s=1, \dots, k} = \{ij : H_{ij} \neq 0\}$.

(kl, ij) component of the Hadamard-Kronecker product of $2H^{(2)} \circ (\mu\Lambda^{-1}I\Lambda^{-1})$

$$\begin{aligned} & 2\mu \text{trace } E_{kl} (H^{(2)} \circ \Lambda^{-1} E_{ij} \Lambda^{-1}) \\ &= 2\mu \text{trace } e_k e_j^t (H^{(2)} \circ \Lambda^{-1} e_i e_i^t \Lambda^{-1}) \\ &= 2\mu \text{trace } e_j^t (H^{(2)} \circ \Lambda_{:,i}^{-1} \Lambda_{j,:}^{-1}) e_k \\ &= 2\mu H_{lk}^{(2)} \Lambda_{li}^{-1} \Lambda_{jk}^{-1}. \end{aligned}$$

This can be “vectorized” in MATLAB. The “sparsity” (free variables of A) of H can be exploited.

Many elements of H are sufficiently large

eliminate l and solve for h first.

$$2H^{(2)} \circ h + \frac{1}{\mu} \Lambda h \Lambda = \Lambda - \frac{1}{\mu} \Lambda P \Lambda - \left(2H^{(2)} \circ (P - A) - \Lambda \right)$$

or equivalently
$$\left[2 \text{Diag}(\text{vec}(H^{(2)})) + \frac{1}{\mu} (\Lambda \otimes \Lambda) \right] \text{vec}(h) = \text{vec} \left(\Lambda - \frac{1}{\mu} \Lambda P \Lambda - (2H^{(2)} \circ (P - A) - \Lambda) \right).$$

The (kl, ij) component of the Kronecker product $\Lambda \otimes \Lambda$ is found from

$$\text{trace } E_{kl} \Lambda E_{ij} \Lambda = \text{trace } e_k e_j^t \Lambda e_i e_l^t \Lambda = \Lambda_{li} \Lambda_{jk}.$$

This can be “vectorized” in MATLAB. The “infinities” (fixed variables of A) of H can be exploited.

dual feasibility

$$2H^{(2)} \circ (P - A) - \Lambda = 0$$

For $\Lambda \succ 0$, we cannot fix ($P_{ii} = A_{ii}$) or free ($H_{ii} = 0$) the diagonal of A



Thanks for your attention!

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