- **unconstrained problem**: x is optimal if and only if

$$x \in \mathbf{dom}\, f_0, \qquad \nabla f_0(x) = 0$$

- **equality constrained problem**

$$\text{minimize} \quad f_0(x) \quad \text{subject to} \quad Ax = b$$

  x is optimal if and only if there exists a ν such that

$$x \in \mathbf{dom}\, f_0, \qquad Ax = b, \qquad \nabla f_0(x) + A^T \nu = 0$$

- **minimization over nonnegative orthant**

$$\text{minimize} \quad f_0(x) \quad \text{subject to} \quad x \succeq 0$$

  x is optimal if and only if

$$x \in \mathbf{dom}\, f_0, \qquad x \succeq 0, \qquad \begin{cases} \nabla f_0(x)_i \geq 0 & x_i = 0 \\ \nabla f_0(x)_i = 0 & x_i > 0 \end{cases}$$

Equivalent convex problems

two problems are (informally) **equivalent** if the solution of one is readily obtained from the solution of the other, and vice-versa

some common transformations that preserve convexity:

- **eliminating equality constraints**

$$\begin{array}{ll} \text{minimize} & f_0(x) \\ \text{subject to} & f_i(x) \leq 0, \quad i = 1, \ldots, m \\ & Ax = b \end{array}$$

  is equivalent to

$$\begin{array}{ll} \text{minimize (over } z\text{)} & f_0(Fz + x_0) \\ \text{subject to} & f_i(Fz + x_0) \leq 0, \quad i = 1, \ldots, m \end{array}$$

  where F and x_0 are such that

$$Ax = b \quad \Longleftrightarrow \quad x = Fz + x_0 \text{ for some } z$$

- **introducing equality constraints**

$$\begin{array}{ll} \text{minimize} & f_0(A_0x + b_0) \\ \text{subject to} & f_i(A_ix + b_i) \leq 0, \quad i = 1, \ldots, m \end{array}$$

is equivalent to

$$\begin{array}{ll} \text{minimize (over } x\text{, } y_i\text{)} & f_0(y_0) \\ \text{subject to} & f_i(y_i) \leq 0, \quad i = 1, \ldots, m \\ & y_i = A_ix + b_i, \quad i = 0, 1, \ldots, m \end{array}$$

- **introducing slack variables for linear inequalities**

$$\begin{array}{ll} \text{minimize} & f_0(x) \\ \text{subject to} & a_i^T x \leq b_i, \quad i = 1, \ldots, m \end{array}$$

is equivalent to

$$\begin{array}{ll} \text{minimize (over } x\text{, } s\text{)} & f_0(x) \\ \text{subject to} & a_i^T x + s_i = b_i, \quad i = 1, \ldots, m \\ & s_i \geq 0, \quad i = 1, \ldots m \end{array}$$

- **epigraph form**: standard form convex problem is equivalent to

$$\begin{array}{ll} \text{minimize (over } x, t) & t \\ \text{subject to} & f_0(x) - t \leq 0 \\ & f_i(x) \leq 0, \quad i = 1, \ldots, m \\ & Ax = b \end{array}$$

- **minimizing over some variables**

$$\begin{array}{ll} \text{minimize} & f_0(x_1, x_2) \\ \text{subject to} & f_i(x_1) \leq 0, \quad i = 1, \ldots, m \end{array}$$

is equivalent to

$$\begin{array}{ll} \text{minimize} & \tilde{f}_0(x_1) \\ \text{subject to} & f_i(x_1) \leq 0, \quad i = 1, \ldots, m \end{array}$$

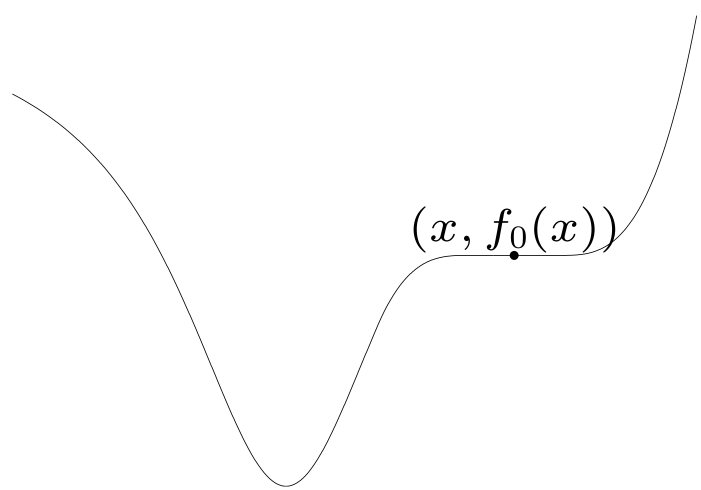
where $\tilde{f}_0(x_1) = \inf_{x_2} f_0(x_1, x_2)$

Quasiconvex optimization

$$\begin{array}{ll} \text{minimize} & f_0(x) \\ \text{subject to} & f_i(x) \leq 0, \quad i = 1, \ldots, m \\ & Ax = b \end{array}$$

with $f_0 : \mathbf{R}^n \to \mathbf{R}$ quasiconvex, f_1, . . . , f_m convex

can have locally optimal points that are not (globally) optimal



convex representation of sublevel sets of f_0

if f_0 is quasiconvex, there exists a family of functions ϕ_t such that:

- $\phi_t(x)$ is convex in x for fixed t
- t-sublevel set of f_0 is 0-sublevel set of ϕ_t, *i.e.*,

$$f_0(x) \le t \quad \Longleftrightarrow \quad \phi_t(x) \le 0$$

example

$$f_0(x) = \frac{p(x)}{q(x)}$$

with p convex, q concave, and $p(x) \ge 0$, $q(x) > 0$ on $\mathbf{dom}\, f_0$

can take $\phi_t(x) = p(x) - tq(x)$:

- for $t \ge 0$, ϕ_t convex in x
- $p(x)/q(x) \le t$ if and only if $\phi_t(x) \le 0$

quasiconvex optimization via convex feasibility problems

$$\phi_t(x) \le 0, \qquad f_i(x) \le 0, \quad i = 1, \ldots, m, \qquad Ax = b \tag{1}$$

- for fixed t, a convex feasibility problem in x
- if feasible, we can conclude that $t \ge p^\star$; if infeasible, $t \le p^\star$

Bisection method for quasiconvex optimization

given $l \le p^\star$, $u \ge p^\star$, tolerance $\epsilon > 0$.
repeat
1. $t := (l + u)/2$.
2. Solve the convex feasibility problem (1).
3. **if** (1) is feasible, $u := t$; **else** $l := t$.

until $u - l \le \epsilon$.

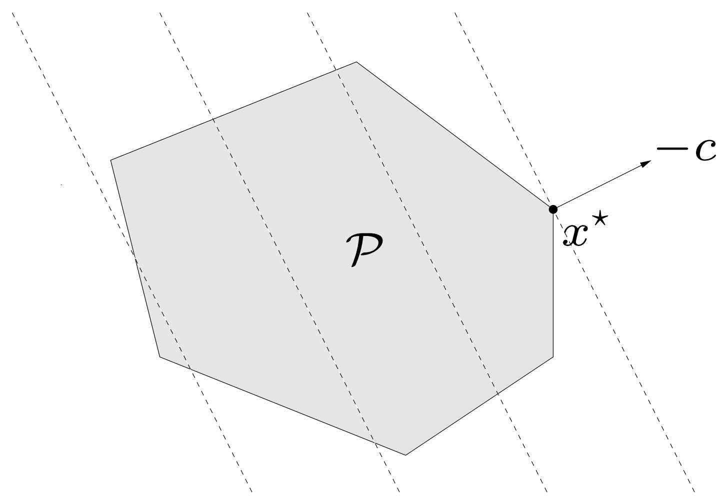
---

requires exactly $\lceil \log_2((u - l)/\epsilon) \rceil$ iterations (where u, l are initial values)

Linear program (LP)

$$\begin{array}{ll} \text{minimize} & c^T x + d \\ \text{subject to} & Gx \preceq h \\ & Ax = b \end{array}$$

- convex problem with affine objective and constraint functions
- feasible set is a polyhedron



Examples

diet problem: choose quantities $x_1, \ldots, x_n$ of n foods

- one unit of food j costs c_j, contains amount a_{ij} of nutrient i
- healthy diet requires nutrient i in quantity at least b_i

to find cheapest healthy diet,

$$\begin{array}{ll} \text{minimize} & c^T x \\ \text{subject to} & Ax \succeq b, \quad x \succeq 0 \end{array}$$

piecewise-linear minimization

$$\text{minimize} \quad \max_{i=1,\ldots,m}(a_i^T x + b_i)$$

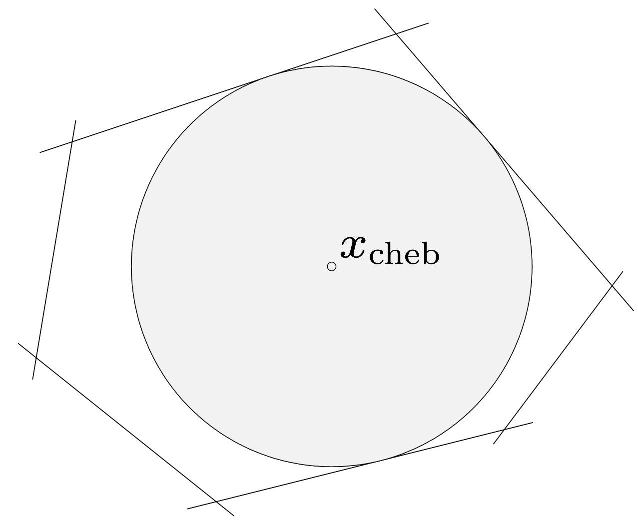
equivalent to an LP

$$\begin{array}{ll} \text{minimize} & t \\ \text{subject to} & a_i^T x + b_i \leq t, \quad i = 1, \ldots, m \end{array}$$

Chebyshev center of a polyhedron

Chebyshev center of

$$\mathcal{P} = \{x \mid a_i^T x \leq b_i,\ i = 1, \ldots, m\}$$



is center of largest inscribed ball

$$\mathcal{B} = \{x_c + u \mid \|u\|_2 \leq r\}$$

- $a_i^T x \leq b_i$ for all $x \in \mathcal{B}$ if and only if

$$\sup\{a_i^T(x_c + u) \mid \|u\|_2 \leq r\} = a_i^T x_c + r\|a_i\|_2 \leq b_i$$

- hence, x_c, r can be determined by solving the LP

$$\begin{array}{ll} \text{maximize} & r \\ \text{subject to} & a_i^T x_c + r\|a_i\|_2 \leq b_i, \quad i = 1, \ldots, m \end{array}$$

(Generalized) linear-fractional program

$$\begin{array}{ll} \text{minimize} & f_0(x) \\ \text{subject to} & Gx \preceq h \\ & Ax = b \end{array}$$

linear-fractional program

$$f_0(x) = \frac{c^T x + d}{e^T x + f}, \qquad \mathbf{dom}\, f_0(x) = \{x \mid e^T x + f > 0\}$$

- a quasiconvex optimization problem; can be solved by bisection
- also equivalent to the LP (variables y, z)

$$\begin{array}{ll} \text{minimize} & c^T y + dz \\ \text{subject to} & Gy \preceq hz \\ & Ay = bz \\ & e^T y + fz = 1 \\ & z \geq 0 \end{array}$$

generalized linear-fractional program

$$f_0(x) = \max_{i=1,\ldots,r} \frac{c_i^T x + d_i}{e_i^T x + f_i}, \qquad \mathbf{dom}\, f_0(x) = \{x \mid e_i^T x + f_i > 0,\ i = 1, \ldots, r\}$$

a quasiconvex optimization problem; can be solved by bisection

example: Von Neumann model of a growing economy

$$\begin{array}{ll} \text{maximize (over } x,\ x^+) & \min_{i=1,\ldots,n} x_i^+/x_i \\ \text{subject to} & x^+ \succeq 0, \quad Bx^+ \preceq Ax \end{array}$$

- $x, x^+ \in \mathbf{R}^n$: activity levels of n sectors, in current and next period
- $(Ax)_i$, $(Bx^+)_i$: produced, resp. consumed, amounts of good i
- x_i^+/x_i: growth rate of sector i

allocate activity to maximize growth rate of slowest growing sector