# CO 602/CM 740: Fundamentals of Optimization Problem Set 2

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## 1 Basic and Basic Feasible Solutions

- 1. Suppose that  $P = \{x \in \mathbb{R}^n : Ax = a, Bx \ge b\}$  is a given polyhedron, where A, B are  $m_A \times n$  and  $m_B \times n$  matrices, respectively.
  - (a) What conditions on the data guarantees that P has a nonempty set of extreme points?
  - (b) If P has a nonempty set of extreme points, prove that the number of extreme points is finite.
  - (c) What is the maximum number of extreme points that *P* can have? (An upper bound, not necessarily the best upper bound, is fine.)
- 2. Let

$$A = \begin{bmatrix} 1 & 1 & 1 & 10 & 2 & 2 & 1 \\ 1 & 1 & -1 & 0 & 4 & 2 & 1 \\ 2 & 3 & -2 & 3 & 10 & 5 & 3 \end{bmatrix}; b = \begin{bmatrix} 10 \\ 6 \\ 17 \end{bmatrix}; c = \begin{bmatrix} 1 & 1 & 1 & 1 & 1 & 1 & 1 \end{bmatrix}^{T}.$$

Consider the standard form polyhedron  $P = \{x \in \mathbb{R}^7 : Ax = b, x \ge 0\}$ . Write a MATLAB program that takes A, b, with A full row rank, as input, and then it outputs the following:

- (a) verification that A is full row rank (or not);
- (b) the maximum number of possible basic solutions for a polyhedron of type P dependent only on the size of A, call it nCm; (see Item (1c) above)

- (c) the minimum number of 0 elements/components in a basic solution, call it  $\zeta$ .
- (d) an  $nCm \times m$  matrix, call it RowsnCk, where each row of the matrix RowsnCk corresponds to the possible indices of columns of A (of nonzero components of basic solution x) corresponding to a basic solution; (Hint: use the MATLAB command: nchoosek)
- (e) an  $n \times k$  matrix X where each column corresponds to a basic solution;
- (f) a vector with the indices of the columns of X that correspond to basic feasible solutions and a corresponding vector with the values of  $c^T x$  and the basic feasible solutions for the maximum value and the minimum value for  $c^T x$ ;
- (g) a submatrix formed from the rows of the matrix RowsnCk where each row corresponds to a basic feasible solution, i.e. this new matrix provides the indices of columns that form feasible bases.

### 2 Isomorphic Polyhedra

The mapping of type f(x) = Ax + b, where A is a matrix and b is a vector, is called an *affine map*. Let P, Q be polyhedra in  $\mathbb{R}^n$  and  $\mathbb{R}^m$ , respectively. The polyhedra P, Q are called *isomorphic* if there exist affine maps  $f: P \to Q$  and  $g: Q \to P$  such that  $g(f(x)) = x, \forall x \in P$  and  $f(g(y)) = y, \forall y \in Q$ . Show the following:

- 1. If P, Q are isomorphic polyhedra, show that there is one-one correspondence between their extreme points. In particular, if f, g are as above, then show that x is an extreme point of P if and only if y = f(x) is an extreme point of Q.
- 2. (slack/surplus variables) Let  $P = \{x \in \mathbb{R}^n : Ax \ge b, x \ge 0\}$ , where A is  $m \times k$ . Let  $Q = \{(x, z) \in \mathbb{R}^{n+k} : Ax z = b, x \ge 0, z \ge 0\}$ . Show that P and Q are isomorphic.