In Progress: Summary of Notation and Basic Results Convex Analysis C&O 663, Fall 2009

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Abstract

This contains a list of definitions/hyperlinks and basic results in Convex Analysis. Please notify the instructor about any errors and/or missing content.

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1 Euclidean Spaces, Linear Manifolds, Hyperplanes

Definition 1.1 A Euclidean space \mathbb{E} is a finite dimensional vector space over the reals, \mathbb{R} , equipped with an inner product, $\langle \cdot, \cdot \rangle$.

Definitions and basic results on the following well know results are available at e.g. wikipedia. Hyperlinks are provided for several of them here: linear manifold, polyhedral set/polyhedron, Minkowski-Weyl Theorem, hyperplanes and halfspaces, affine hull, span, linear transformation, adjoint, relative interior, closure, boundary, Bolzano-Weierstrass Theorem.

1.1 Basics for Background

- Unit ball in \mathbb{E} . $B = \{x \in \mathbb{E} : ||x|| \le 1\}$
- Open set $S \subseteq \mathbb{E}$. $\forall x \in S, \exists \delta > 0, \{x\} + \delta B \subseteq S$
- Interior of $S \subseteq \mathbb{E}$. $int(S) = \{x \in \mathbb{E} : \{x\} + \delta B \subseteq S \text{ for some } \delta > 0\} = union of all open sets contained in S is a set of the set$
- Closed set $S \subseteq \mathbb{E}$. $\forall x \notin S, \exists \delta > 0, (\{x\} + \delta B) \cap S = \emptyset$
- Closure of $S \subseteq \mathbb{E}$. $cl(S) = \{x \in \mathbb{E} : \forall \delta > 0, (\{x\} + \delta B) \cap S \neq \emptyset\}$ = intersection of all closed sets containing S
- Linear subspace $S \subseteq \mathbb{E}$. $\forall x, y \in S, \forall \lambda, \mu \in \mathbb{R}, \lambda x + \mu y \in S$
- Linear function $f : \mathbb{E} \to (-\infty, +\infty]$. $\forall x, y \in dom(f), \forall \lambda, \mu \in \mathbb{R}, f(\lambda x + \mu y) = \lambda f(x) + \mu f(y)$
- Lower semicontinuous function $f : \mathbb{E} \to (-\infty, +\infty]$ at x. $\liminf_{y \to x} f(y) \ge f(x)$
- Linear map $L : \mathbb{E} \to \mathbb{Y}$. $\forall x, y \in \mathbb{E}, \forall \lambda, \mu \in \mathbb{R}, L(\lambda x + \mu y) = \lambda L(x) + \mu L(y)$
- Adjoint of linear map $A : \mathbb{E} \to \mathbb{Y}$. Linear map $A^{adj} : \mathbb{Y} \to \mathbb{E}$ satisfying $\forall x \in \mathbb{E}, \forall y \in \mathbb{Y}, \langle A^{adj}y, x \rangle_{\mathbb{E}} = \langle y, Ax \rangle_{\mathbb{Y}}$
- Affine subspace $S \subseteq \mathbb{E}$. (1) $\forall x, y \in S, \forall \lambda \in \mathbb{R}, \lambda x + (1 \lambda)y \in S$ (2) $S = V + \{x\}$ for some linear subspace V and vector x

- Affine function $a : \mathbb{E} \to (-\infty, +\infty]$. (1) $\forall x, y \in dom(a), \forall \lambda \in \mathbb{R}, a(\lambda x + (1 \lambda)y) = \lambda a(x) + (1 \lambda)a(y)$ (2) $a : x \mapsto f(x) + r$ for some linear function f and real number r
- Affine map $A : \mathbb{E} \to \mathbb{Y}$. (1) $\forall x, y \in \mathbb{E}, \forall \lambda \in \mathbb{R}, A(\lambda x + (1 \lambda)y) = \lambda A(x) + (1 \lambda)A(y)$ (2) $A : x \mapsto L(x) + b$ for some linear map L and vector b
- Affine hull of $S \subseteq \mathbb{E}$. Af $(S) = \{\lambda x + (1 \lambda)y : x, y \in S, \lambda \in \mathbb{R}\}$ = intersection of all affine subspaces containing S
- Cone $K \subseteq \mathbb{E}$. $\forall x \in K, \forall \lambda > 0, \lambda x \in K$
- Positively-homogeneous function $f : \mathbb{E} \to [-\infty, +\infty]$. (1) $\forall x \in \mathbb{E}, \forall \lambda > 0, f(\lambda x) = \lambda f(x)$ (2) epi(f) is a cone
- Relatively open set $S \subseteq \mathbb{E}$. $\forall x \in S, \exists \delta > 0, (\{x\} + \delta B) \cap Af(S) \subseteq S$
- Relative interior of S. $ri(S) = \{x \in Af(S) : (\{x\} + \delta B) \cap Af(S) \subseteq S \text{ for some } \delta > 0\}$
- Domain of $f: \mathbb{E} \to [-\infty, +\infty]$. $dom(f) = \{x \in \mathbb{E} : f(x) < +\infty\}$
- **Proper function** $f: \mathbb{E} \to [-\infty, +\infty]$. $dom(f) \neq \emptyset$ and $f(x) > -\infty$ for all $x \in \mathbb{E}$
- Epigraph of $f : \mathbb{E} \to [-\infty, +\infty]$. $epi(f) = \{(x, r) \in \mathbb{E} \oplus \mathbb{R} : f(x) \le r\}$
- Sub-level set of $f: \mathbb{E} \to [-\infty, +\infty]$ at level $r \in \mathbb{R}$. $S_r(f) = \{x \in \mathbb{E} : f(x) \le r\}$
- Closure of $f : \mathbb{E} \to [-\infty, +\infty]$. $cl(f) : x \in \mathbb{E} \mapsto \liminf_{y \to x} f(y)$
- Infimum convolution of $f, g : \mathbb{E} \to (-\infty, +\infty]$. $f \odot g : x \in \mathbb{E} \mapsto \inf\{f(y) + g(x y)\}$
- Indicator function of $S \subseteq \mathbb{E}$. $\delta_S : x \in \mathbb{E} \mapsto 0$ if $x \in S$, $+\infty$ otherwise

2 Convex Sets and Functions

2.1 Convex Sets

Definition 2.1 The set $S \subset \mathbb{E}$ is a convex set if

$$\lambda x + (1 - \lambda)y \in S, \forall \lambda \in (0, 1), \forall x, y \in S.$$

Proposition 2.2 For a nonempty convex set C:

1. We have relint $C \neq \emptyset$ and the affine hulls aff C = aff relint (C). Moreover, for any $x \in$ relint C and $y \in cl C$, the line segment $[x, y) \subset$ relint C and thus relint C is convex. Furthermore,

cl C = cl relint C, relint C = relint cl C.

2. relint $C \subset C \subset cl C$.

Include definitions and basic results on: Basic (strong, strict) separation theorems; convex hull; convex combination, recession cones, Caratheodory Theorem.

2.2 Convex Functions

Definition 2.3 The epigraph of a function $f : \mathbb{R}^n \to (-\infty, +\infty]$ is defined as

 $\mathrm{epi}\,(f)=\{(x,r):f(x)\leq r\}.$

Definition 2.4 The function $f : \mathbb{R}^n \to (-\infty, +\infty]$ is a convex function if

$$f(\lambda x + (1 - \lambda)y) \le \lambda f(x) + (1 - \lambda)f(y), \forall x, y \in \mathbb{R}^{n}, \forall \lambda \in [0, 1].$$

Definition 2.5 The convex hull or convex envelope of a function $f : \mathbb{R}^n \to \mathbb{R}$ is defined as

 $\operatorname{conv}(f)(x) = \inf\{t : (x, t) \in \operatorname{conv} \operatorname{epi} f\}.$

Proposition 2.6 A convex function f is locally Lipschitz on the interior of its domain.

Include definitions and basic results on: composing convex functions, convex growth conditions, locally Lipschitz

2.3 Basics for Convex Functions and Convex Sets

- Convex set. $\forall x, y \in S, \forall \lambda \in (0, 1), \lambda x + (1 \lambda)y \in S$
- Convex function f: E → [-∞, +∞]. epi(f) is convex; note that f is a proper convex function if its domain is nonempty and it does not take on the value -∞.
- Sublinear function $f: \mathbb{E} \to [-\infty, +\infty]$. f is positively-homogeneous and convex
- Subadditive function $f: \mathbb{E} \to [-\infty, +\infty]$. $\forall x, y \in dom(f), f(x + y) \leq f(x) + f(y)$
- Convex hull of $S \subseteq \mathbb{E}$. $\operatorname{conv}(S) = \{\lambda x + (1 \lambda)y : x, y \in S, \lambda \in (0, 1)\}$
- Convex hull of $f : \mathbb{E} \to [-\infty, +\infty]$. $\operatorname{conv}(f) : x \mapsto \inf\{r : (x, r) \in \operatorname{conv}(epi(f))\}$
- Locally Lipschitz f at $x \in \text{dom}(f)$. $\exists K > 0, \exists \delta > 0, \forall y, z \in \{x\} + \delta B, |f(y) f(z)| \le K ||y z||$

3 Duality of Functions and Sets

3.1 Conjugate, Positively Homogeneous, Sublinear Functions

Definition 3.1 The Fenchel conjugate of $h : \mathbb{E} \to [-\infty, +\infty]$ is

$$h^*(\phi) := \sup_{x \in \mathbb{E}} \{ \langle \phi, x \rangle - h(x) \}.$$

 $\mbox{Proposition 3.2} \qquad 1. \ f \geq g \Rightarrow f^* \leq g^*$

3.2 Indicator Functions, Support Functions and Sets, Closures

Definition 3.3 The indicator function of a set $S \subset \mathbb{E}$ is

$$\delta_S(x) := \left\{ \begin{array}{ll} 0 & \textit{if } x \in S \\ \infty & \textit{otherwise} \end{array} \right.$$

Definition 3.4 The support function of a set $S \subset \mathbb{E}$ is

$$\sigma_S(\varphi) := \sup_{x \in S} \{ \langle \varphi, x \rangle \}.$$

Definition 3.5 A function f is positively homogeneous if

$$f(\lambda x) = \lambda f(x), \forall \lambda > 0, \forall x \in \mathbb{E}.$$

Remark 3.6 Equivalently, the function f is positively homogeneous if

 $f(\lambda x) \leq \lambda f(x), \forall \lambda > 0, \forall x \in \mathbb{E}.$

And, a support function is positively homogeneous.

Definition 3.7 A function is sublinear if it is subadditive and positively homogeneous, equivalently, if

$$f(\alpha x + \beta y) \le \alpha f(x) + \beta f(y), \forall \alpha > 0, \beta > 0, \forall x, y \in \mathbb{E}.$$

Definition 3.8 The set $S_f := \{ \phi : \langle \phi, x \rangle \leq f(x), \forall x \}$ is the set supported by f.

Proposition 3.9 Suppose that the function f is positively homogeneous. Then the conjugate function

$$f^* = \delta_{S_f}$$
.

3.2.1 Closures of Sets and Functions

Proposition 3.10 $\delta_S^{**} = \delta_S$ iff S is closed and convex.

Proposition 3.11 The second conjugate function $f^{**} = f$ iff f is a closed and convex function.

Definition 3.12 The closure of a function f is defined as

$$\operatorname{cl}\left(f\right)(x) = \inf\left\{\lim_{k \to \infty} f(x^k) : x^k \to x \text{ and } \lim_{k \to \infty} f(x^k) \text{ exists}\right\}$$

Proposition 3.13 The second conjugate functions:

$$\begin{array}{rcl} \delta^{**}_S &=& \delta_{\operatorname{cl}\left(\operatorname{conv}\left(S\right)\right)} \\ \sigma^{**}_S &=& \sigma_{\operatorname{cl}\left(\operatorname{conv}\left(S\right)\right)} \\ f^{**} &=& \operatorname{cl}\left(\operatorname{conv}\left(f\right)\right) \end{array}$$

Proposition 3.14 The second polar $S^{\circ\circ} = cl (conv (S \cup \{0\})).$

3.2.2 Convex Cones

Proposition 3.15 If K is a nonempty cone, then $K^{--} = cl(conv(K))$.

3.2.3 More on Support Functions

- **Theorem 3.16** 1. If $\emptyset \neq S \subset \mathbb{E}$ is a closed, convex set, then the support function σ_S is a proper, closed, sublinear function.
 - 2. Moreover, if f is a proper, closed and sublinear function, then

 $f = \sigma_{S_f},$

i.e. it is the support function of the set supported by f.

3. Thus $S \leftrightarrow \sigma_S$ is a bijection between {closed, convex sets} and {closed, sublinear functions}.

3.3 Gauge Functions, Polar of a Function, Norms and Dual Norms

Definition 3.17 The function defined by $\gamma_{S}(x) := \inf\{\lambda \ge 0 : x \in \lambda S\}$ is called the gauge of S.

Definition 3.18 The polar of a function g is

$$g^{\circ}(\phi) := \inf\{\lambda > 0 : \langle \phi, x \rangle \leq \lambda g(x), \forall x\}$$

Proposition 3.19 1. The support function of the polar set of S, $\sigma_{s^{\circ}}$, is majorized by the gauge function of S, γ_{S} .

- 2. $\gamma_S \ge 0$ and $\gamma(0) = 0$.
- 3. γ_S is positively homogeneous.
- 4. If S is convex, then γ_S is sublinear.
- 5. If S is closed and convex, then γ_S is closed and sublinear.
- 6.

$$\gamma_{S} = \gamma_{S}^{**} = \delta_{S^{\circ}}^{*} = \sigma_{S^{\circ}}.$$

- 7. A gauge function is a non-negative sublinear function which maps the origin to 0.
- 8. A norm is a gauge function. Conversely, the gauge function of a closed, convex set containing 0 is a norm.

Proposition 3.20 Given a norm $\|\cdot\|$, then the polar function $\|\cdot\|^{\circ}$, is also a norm, called the dual norm. Moreover,

$$S_{\|\cdot\|} = \{ \varphi : \|\varphi\|^{\circ} \le 1 \}, \qquad S_{\|\cdot\|^{\circ}} = \{ x : \|x\| \le 1 \} = S_{\|\cdot\|}^{\circ}.$$

3.4 Subdifferentials, Directional Derivatives, Set Constrained Optimization

3.4.1 Subdifferentials and Directional Derivatives

Theorem 3.21 Let f be a differentiable function on an open convex subset $S \subset \mathbb{E}$. Each of the following conditions is necessary and sufficient for f to be convex on S:

1.
$$f(x) - f(y) \ge \langle x - y, \nabla f(y) \rangle, \forall x, y \in S.$$

2.
$$\langle \nabla f(x) - \nabla f(y), x - y \rangle \ge 0, \forall x, y \in S.$$

3. $\nabla^2 f(x)$ is positive semidefinite for all $x \in S$ whenever f is twice differentiable on S.

To extend results as in Theorem 3.21 to the nondifferentiable case, we use the following.

Definition 3.22 The vector ϕ is called a subgradient of f at x if

$$f(y) - f(x) \ge \langle \phi, y - x \rangle, \forall y \in \mathcal{E}.$$

The subdifferential of f at x is

$$\partial f(x) = \{ \phi : f(y) - f(x) \ge \langle \phi, y - x \rangle, \forall y \in \mathcal{E}.$$

 $\partial f(\mathbf{x}) = \emptyset$, if $\mathbf{x} \notin \text{dom}(f)$.

Proposition 3.23 Suppose that f is convex. Then $\partial f(x)$ is a closed convex set. And, $x \in \operatorname{argmin}_{x} f(x)$ if and only if $0 \in \partial f(x)$.

Proposition 3.24 Suppose that $f : \mathbb{E} \to (-\infty, +\infty]$ is convex. Let

$$g(t) := \frac{f(x+td) - f(x)}{t}.$$

Then for all $x, d \in \mathbb{E}$, $x \in \text{dom}(f)$, the function g is monotonically nondecreasing for t > 0 (and for t < 0).

Definition 3.25 The directional derivative of f at x (in dom(f)) along d is

$$f'(x;d) := \lim_{t \downarrow 0} \frac{1}{t} f(x+td) - f(x)$$

if it exists.

Theorem 3.26 Suppose that f is convex. Then for all $x, d \in \mathbb{E}$, $x \in \text{dom}(f)$, the directional derivative

$$f'(x; d) = \lim_{t \downarrow 0} \frac{f(x + td) - f(x)}{t}$$

exists in $[-\infty, +\infty]$.

3.4.2 Properties of $f'(x; d), \partial f(x)$

Proposition 3.27 Let f be convex and $x \in \text{dom}(f)$. Then φ is a subgradient of f at x iff $f'(x; d) \ge \langle \varphi, d \rangle, \forall d \in \mathbb{E}$.

Proposition 3.28 Let f, g be proper convex functions.

- 1. $f'(x; \cdot)$ is positively homogeneous.
- 2. If f is convex, then $f'(x; \cdot)$ is convex; hence it is sublinear.
- 3. If f is convex, then $\forall x \in \text{dom}(f)$ we have

$$\partial f(\mathbf{x}) = S_{f'(\mathbf{x};\cdot)}.$$

4.

$$\partial(f+g)(x) \supset \partial f(x) + \partial g(x).$$

- 5. With f(x) finite:
 - (a) $\partial f(x) \neq \emptyset \Rightarrow f(x) = f^{**}(x)$.
 - (b) $f(x) = f^{**}(x) \Rightarrow \partial f(x) = \partial f^{**}(x)$.
 - (c) $y \in \partial f(x) \Rightarrow x \in \partial f(y)$.

Example 3.29 Let $X \in \mathbb{S}^n$, $f(X) := \lambda_{\max}(X)$ denote the largest eigenvalue of X, and let V be the corresponding eigenspace, i.e. the subspace of eigenvectors $V = \{v : Xv = \lambda_{\max}(X)v\}$. Then the directional derivative in the direction $D \in \mathbb{S}^n$ is

$$f'(X; D) = \max_{\|\nu\|=1, \nu \in V} \nu^{\mathsf{T}} D\nu = \sigma_{\partial f(X)}.$$

Therefore, f is differentiable if $\partial f(X)$ is a singleton, i.e. if the eigenvalue $\lambda_{\max}(X)$ is a singleton so the dimension of the eigenspace V is 1.

3.5 Basics for Duality of Functions and Sets

- Polar set of $S \subseteq \mathbb{E}$. $S^{\circ} = \bigcap_{x \in S} \{ \varphi \in \mathbb{E} : \langle \varphi, x \rangle \le 1 \}$
- Polar cone of $K \subseteq \mathbb{E}$. $K^- = \bigcap_{x \in K} \{ \varphi \in \mathbb{E} : \langle \varphi, x \rangle \le 0 \}$
- Fenchel conjugate of $f: \mathbb{E} \to [-\infty, +\infty]$. $f^*: \varphi \in \mathbb{E} \mapsto \sup_{x \in dom(f)} \{\langle \varphi, x \rangle f(x)\}$
- Support function of $S \subseteq \mathbb{E}$. $\sigma_S = \delta_S^* : \phi \mapsto \sup\{\langle \phi, x \rangle : x \in S\}$
- Set supported by $f : \mathbb{E} \to [-\infty, +\infty]$. $S_f = \{ \varphi \in \mathbb{E} : \forall x \in \mathbb{E}, \langle \varphi, x \rangle \leq f(x) \}$

4 Optimization

4.1 Set Constrained Optimization and Normal Cones

Proposition 4.1 Suppose that f is a differentiable convex function and S is an open convex set. Then $\bar{\mathbf{x}} \in \operatorname{argmin}_{\mathbf{x} \in S} f(\mathbf{x})$ iff $\nabla f(\bar{\mathbf{x}}) = 0$.

Definition 4.2 The normal cone to the convex set C in \mathbb{E} at $\bar{x} \in C$ is

 $\mathsf{N}_{\mathsf{C}}(\bar{\mathsf{x}}) := \{ \mathsf{d} \in \mathbb{E} : \langle \mathsf{d}, \mathsf{x} - \bar{\mathsf{x}} \rangle \le 0, \forall \mathsf{x} \in \mathsf{C} \}.$

Definition 4.3 The (convex) tangent cone to the convex set C in \mathbb{E} at $\bar{x} \in C$ is

$$T_C(\bar{x}) := cl \operatorname{cone} (C - \bar{x}).$$

Definition 4.4 The set of feasible directions to the convex set C in \mathbb{E} at $\bar{x} \in C$ is

$$\mathcal{D}_{\mathbf{C}}(\bar{\mathbf{x}}) := \operatorname{cone}\left(\mathbf{C} - \bar{\mathbf{x}}\right)$$

Proposition 4.5 Suppose that C is a convex set and $f: C \to \mathbb{R}$. If \bar{x} is a <u>local</u> minimum of f on C, then

$$f'(\bar{x}; x - \bar{x}) \ge 0, \forall x \in C.$$

$$(4.1)$$

If f is differentiable, this is equivalent to $\nabla f(\bar{x}) \in -N_C(\bar{x})$. If, in addition, f is convex on C, then the condition (4.1) is sufficient for \bar{x} to be a minimum of f on C, i.e. we get (if f is lsc on S) that

$$\bar{\mathbf{x}} \in \operatorname*{argmin}_{\mathbf{x} \in \mathbf{C}} f(\mathbf{x}) \text{ iff } \exists \boldsymbol{\varphi} \in (-N_{\mathbf{C}}(\bar{\mathbf{x}})) \cap \partial f(\bar{\mathbf{x}}).$$

4.2 Basics for Optimization

- Subdifferential of f at $x \in dom(f)$. $\partial f(x) = \{ \varphi \in \mathbb{E} : \forall y \in dom(f), \langle \varphi, y x \rangle \leq f(y) f(x) \}$
- Subgradient of f at $x \in dom(f)$. $\phi \in \partial f(x)$
- Directional derivative of f at $x \in \text{dom}(f)$ in direction $d \in \mathbb{E}$. $f'(x;d) = \lim_{t \downarrow 0} \frac{1}{t} [f(x + td) f(x)]$, if exists
- Differentiability of f at $x \in \text{dom}(f)$. $\exists \nabla f(x) \in \mathbb{E}, \forall d \in \mathbb{E}, f'(x; d) = \langle \nabla f(x), d \rangle; \nabla f(x) \text{ is called the gradient}$
- Normal cone to convex set S at $x \in S$. $N_S(x) = \bigcap_{y \in S} \{ \varphi \in \mathbb{E} : \langle \varphi, y x \rangle \le 0 \} = \partial \delta_S(x)$

5 Theorems

5.1 Convexity

• Relative interior.

 $\begin{array}{lll} S \ {\rm convex} & \Longrightarrow & \emptyset \neq {\tt ri}(S) = \{x \in S : \forall y \in S, \exists \delta > 0, x + \delta(x-y) \in S\} = \{x \in S : \bigcup_{t \geq 0} t(S - \{x\}) \ {\rm is \ a \ linear \ subspace}\} \end{array}$

• Convexity preserving operations. Suppose that $\{S_t : t \in T\}$ is a collection of convex sets, $\{f_t : t \in T\}$ is a collection of convex functions, and A is an affine map. Then the following are convex:

$$\begin{array}{lll} -: \bigcap_{t \in T} S_t & & - \bigoplus_{t \in T} S_t \; (T \; {\rm finite}) & & -: \sum_{t \in T} S_t \; (T \; {\rm finite}) \\ -: \; A(S_t) \; (t \in T) & & - A^{-1}(S_t) \; (t \in T) & & - {\rm ri}(S_t) \; (t \in T) & & - {\rm cl}(S_t) \; (t \in T) \\ -: \; \sup_{t \in T} f_t & & - \sum_{t \in T} f_t \; (T \; {\rm finite}) & & -: \bigodot_{t \in T} f_t \; (T \; {\rm finite}) & & - f_t \circ A \; (t \in T) \end{array}$$

- Monotonicity of gradient. Suppose f continuous over dom(f) and differentiable over int(dom(f)), dom(f) convex, and int(dom(f)) ≠ Ø.
 - $-: f convex \iff \forall x, y \in int(dom(f)), \langle \nabla f(x) \nabla f(y), x y \rangle \ge 0$
 - -: f strictly convex over $int(dom(f)) \iff \forall x, y \in int(dom(f)), \langle \nabla f(x) \nabla f(y), x y \rangle > 0$
- Interior representation of convexity. $-: S \subseteq \mathbb{E}$ is convex $\iff S = conv(S)$ $-: f: \mathbb{E} \rightarrow [-\infty, +\infty]$ is convex $\iff f = conv(f)$
- Basic separation. S is a closed, convex set and $x \notin S \implies \exists a \in \mathbb{E}, \exists b \in \mathbb{R}, \forall y \in S, \langle a, x \rangle > b \ge \langle a, y \rangle$. If S is a cone, we may take b = 0.
- Characterization of sublinearity. f is sublinear \iff f is positively-homogeneous and subadditive.

f is proper, closed and sublinear $\iff S_f \neq \emptyset$ and $f = \sigma_{S_f}$

• Continuity of convex functions. f is proper and convex, and $x \in int(dom(f)) \implies f$ is locally Lipschitz at x

5.2 Duality

- Exterior representation of convexity.
 - $\neg: S \subseteq \mathbb{E} \text{ is closed, convex and contains } 0 \iff S = (S^{\circ})^{\circ}$ $\neg: f: \mathbb{E} \rightarrow [-\infty, +\infty] \text{ is closed and convex } \iff f = (f^{*})^{*}$
- Fenchel-Young inequality. $\forall \phi, x \in \mathbb{E}, f(x) + f^*(\phi) \ge \langle \phi, x \rangle$, with equality iff $\phi \in \partial f(x)$
- Polar Calculus. Suppose S, T are nonempty sets, K a nonempty cone.
 - $-: (S^{\circ})^{\circ} = cl(conv(S \cup \{0\}))$

$$-: (K^{-})^{-} = cl(conv(K))$$

$$-: (S \cup T)^{\circ} = S^{\circ} \cap T^{\circ}$$

- $-: (S \cap T)^{\circ} \supseteq cl(conv(S^{\circ} \cup T^{\circ}))$, with equality when S, T are closed, convex and contain 0
- Conjugate calculus. Suppose f, g, f_1, \ldots, f_m are proper.

$$-: (f^*)^* = cl(conv(f))$$

- $-: \ f,g \ \mathrm{convex} \ \Longrightarrow \ (f \odot g)^* = f^* + g^*$
- $-: f, g \text{ convex} \implies (f+g)^* \leq f^* \odot g^*.$ Equality holds when $int(dom(f)) \cap dom(g) \neq \emptyset$

- -: f convex, and A a linear map \implies $(f \circ A)^*(\phi) \leq \inf\{f^*(\psi) : A^{\alpha dj}\psi = \phi\}$. Equality holds when $\exists y, Ay \in int(dom(f))$, in which case infimum is attained when finite
- $\begin{array}{l} -: f_1, \ldots, f_m \, {\rm convex} \, {\rm with} \, {\rm common} \, {\rm domain} \implies (\max_i f_i)^*(\varphi) \leq \inf\{\sum_{i=1}^m \lambda_i f_i^*(\varphi^i) : \sum_{i=1}^m \lambda_i(\varphi^i, 1) = (\varphi, 1), \lambda_i \geq 0\}. \end{array}$

Equality holds when $int(dom(f_i)) \neq \emptyset$, in which case the infimum is attained when finite

• Fenchel duality. Suppose f, g are proper and convex

 $-: \inf\{f(x) + g(x)\} \ge \sup\{-f^*(-\varphi) - g^*(\varphi)\}$

-: Equality holds when $int(dom(f)) \cap dom(g) \neq \emptyset$, in which case the supremum is attained when finite

• Convex conic duality. Suppose K is a convex cone, and A, D are linear maps

 $-: \inf_x \{ \langle c, x \rangle : b - Ax \in K, Dx = e \} \geq \sup_{\varphi, \eta} \{ \langle b, \varphi \rangle + \langle e, \eta \rangle : A^{adj} \varphi + D^{adj} \eta = c, \varphi \in K^- \}$

–: Equality holds when $\exists x, Dx = e, b - Ax \in int(K)$, in which case the supremum is attained if finite

- Lagrange duality. Suppose f, g_1, \ldots, g_m are proper, $L : (x, \lambda) \in \mathbb{E} \oplus \mathbb{R}^m \mapsto f(x) + \sum_{i=1}^m \lambda_i g_i(x)$, and $D = dom(f) \cap (\bigcap_{i=1}^m dom(g_i))$.
 - $-: \inf\{f(x): g_{\mathfrak{i}}(x) \leq 0, \mathfrak{i} = 1, \dots, m\} \geq \sup_{\lambda > 0} \inf_{x} L(x, \lambda)$

 $\neg: \exists x \in D, \lambda \ge 0, (g_i(x) \le 0, i = 1, \dots, m) \land (x \text{ minimizes } y \mapsto L(y, \lambda) \text{ over } D) \land (\lambda_i g_i(x) = 0, i = 1, \dots, m)$

 \implies equality holds with x and λ attaining the infimum and supremum respectively

 $\begin{array}{l} -: \ (f,g_1,\ldots,g_m \ {\rm convex}) \land (\exists y \in dom(f), \forall i \in \{1,\ldots,m\}g_i(y) < 0) \land (x \ {\rm attains \ the \ infimum}) \\ \implies \ {\rm equality \ holds \ and \ } \exists \lambda \ge 0, \ (x \ {\rm minimizes \ } y \ \mapsto \ L(y,\lambda) \ {\rm over \ } D) \land (\lambda_i g_i(x) = 0, i = 1,\ldots,m) \end{array}$

 \neg : (f, g₁,..., g_m closed and convex) ∧ (∃λ ≥ 0, x → L(x, λ) has bounded sub-level sets ⇒ equality holds and the infimum is attained if finite

5.3 Optimization

- Convex optimality conditions. Suppose f, g_1, \ldots, g_m are proper and convex, and S is nonempty and convex
 - -: x minimizes f $\iff 0 \in \partial f(x)$
 - $-: 0 \in \partial f(x) + N_S(x) \implies x \text{ minimizes } f \text{ over } S.$ The converse is true when $int(dom(f)) \cap S \neq \emptyset$

-: (KKT condition) Suppose $S = \{y : g_i(y) \le 0, i = 1, ..., m\}$, $x \in S$ and $f, g_1, ..., g_m$ are differentiable at x.

 $\exists \lambda \geq 0, (\nabla f(x) + \sum_{i=1}^{m} \lambda_i \nabla g(x) = 0) \land (\lambda_i g_i(x) = 0, i = 1, \dots, m) \implies x \text{ minimizes } f \text{ over } S.$ The converse is true when $\exists y \in dom(f), \forall i \in \{1, \dots, m\}, g_i(y) < 0$

• Subdifferential calculus. Suppose f, g, f_1, \ldots, f_m are proper and convex with f_1, \ldots, f_m sharing same domain, and A is a linear map.

 $-: \forall x \in dom(f) \cap dom(g), \partial(f + g)(x) ⊇ \partial f(x) + \partial g(x).$ Equality holds when $int(dom(f)) \cap dom(g) \neq \emptyset$

- \neg : $\forall x \in \text{dom}(f \circ A)), \partial(f \circ A)(x) \supseteq A^{adj}\partial f(Ax)$. Equality holds when $\exists y, Ay \in \text{int}(\text{dom}(f))$
- $\begin{array}{l} -: \ \forall x \in dom(f_i), \vartheta(\max_i f_i)(x) = \bigcup \{ \vartheta(\sum_{i \in I} \lambda_i f_i)(x) : \sum_{i \in I} \lambda_i = 1, \lambda_i \geq 0 \} \supseteq conv(\bigcup_{i \in I} \vartheta f_i(x)), \\ \mathrm{where} \ I = \{ i : f_i(x) = f(x) \}. \ \mathrm{Equality \ holds \ when \ int}(dom(f_i)) \neq \emptyset. \end{array}$
- Sublinearity of directional derivatives. Suppose f is proper and convex.

 $\label{eq:convex} -: \ x \in dom(f) \implies f'(x;\cdot): d \in \mathbb{E} \mapsto f'(x;d) \ \mathrm{is \ sublinear \ and} \ \partial f(x) = S_{f'(x;\cdot)} \ \mathrm{is \ closed \ and} \ \mathrm{convex}$

 $\label{eq:convex_and_bounded} -: x \in int(dom(f)) \implies \partial f(x) \mbox{ is closed, convex and bounded, and } f'(x; \cdot) = \max_{\varphi \in \partial f(x)} \langle \varphi, \cdot \rangle \mbox{ is closed.}$

 $-: x \in dom(f) \setminus int(dom(f)) \implies \partial f(x)$ is either empty or unbounded.

- Directional derivatives of max-function. f_1, \ldots, f_m are proper and convex, $x \in \bigcap_{i=1}^m int(dom(f_i))$ and $I = \{i : f_i(x) = f(x)\} \implies \forall d \in \mathbb{E}, f'(x; d) = \max_{i \in I} \{f'_i(x; d)\}$
- Unique subgradient. Suppose f is proper and convex and $x \in dom(f)$

-: f is differentiable at $x \iff \partial f(x)$ is a singleton

6 Nonsmooth (Nonconvex)

6.1 Definitions

- Dini directional derivative of locally Lipschitz f at x in direction d. $f^{-}(x;d) = \liminf_{t \downarrow 0} \frac{1}{t} [f(x + td) f(x)]$
- Michel-Penot directional derivative of locally Lipschitz f at x in direction d. $f^{\diamond}(x; d) = \sup_{u \in \mathbb{E}} \limsup_{t \downarrow 0} \frac{1}{t} [f(x + tu + td) - f(x + tu)]$
- Clarke directional derivative of locally Lipschitz f at x in direction d. $f^{\circ}(x; d) = \limsup_{u \to x, t \mid 0} \frac{1}{t} [f(y + td) - f(y)]$
- Dini subdifferential of locally Lipschitz f at x. $\partial_{-}f(x) = \{ \phi \in \mathbb{E} : \forall d \in \mathbb{E}, \langle \phi, d \rangle \leq f^{-}(x; d) \}$
- Michel-Penot subdifferential of locally Lipschitz f at x. $\partial_{\diamond}f(x) = \{ \varphi \in \mathbb{E} : \forall d \in \mathbb{E}, \langle \varphi, d \rangle \leq f^{\diamond}(x; d) \}$
- Clarke subdifferential of locally Lipschitz f at x. $\partial_{\circ}f(x) = \{\varphi \in \mathbb{E} : \forall d \in \mathbb{E}, \langle \varphi, d \rangle \le f^{\circ}(x; d)\}$
- Nonsmooth subgradients. members of nonsmooth subdifferentials
- Regularity of locally Lipschitz f at x. $\forall d \in \mathbb{E}, f'(x; d) = f^{\circ}(x; d)$
- Distance function of S. $d_S : x \in \mathbb{E} \mapsto \inf\{\|x y\| : y \in S\}$
- Clarke normal cone of S at $x \in S$. $N_S(x) = cl(\bigcup_{t>0} t\partial_o d_S(x))$
- Clarke tangent cone of S at $x \in S$. $T_S(x) = N_S(x)^- = \{d \in \mathbb{E} : d_S^\circ(x; d) = 0\}$

6.2 Theorems

- Bounded nonsmooth directional derivatives. f locally Lipschitz at x with Lipschitz constant K $\implies \forall d \in \mathbb{E}, f^{-}(x; d) < f^{\circ}(x; d) < f^{\circ}(x; d) < K \|d\|$
- Bounded nonsmooth subdifferentials. f locally Lipschitz at x with Lipschitz constant K $\implies \partial_-f(x) \subseteq \partial_\diamond f(x) \subseteq \partial_\diamond f(x) \subseteq KB$
- Sublinarity of nonsmooth directional derivatives. Suppose f locally Lipschitz at $x f^{\diamond}(x; \cdot) : d \in \mathbb{E} \mapsto f^{\diamond}(x; d)$ and $f^{\circ}(x; \cdot) : d \in \mathbb{E} \mapsto f^{\circ}(x; d)$ are sublinear and finite everywhere $-f^{\diamond}(x; \cdot) = \sigma_{\partial_{\diamond}f(x)}$ and $f^{\circ}(x; \cdot) = \sigma_{\partial_{\diamond}f(x)}$
- Characterization of regularity. Suppose f locally Lipschitz at x. f is regular at $x \iff \forall d \in \mathbb{E}, f^{-}(x; d) = f^{\circ}(x; d) = f^{\circ}(x; d)$
- Regularity of convex functions. f is proper and convex, and $x \in int(dom(f)) \implies f$ is regular at x.

- Nonsmooth subdifferential calculus. Suppose f_1, \ldots, f_m are locally Lipschitz at x. It holds $\partial_{\diamond}(\sum_{i=1}^{m} f_i)(x) \subseteq \sum_{i=1}^{m} \partial_{\diamond} f_i(x)$, $\partial_{\circ}(\sum_{i=1}^{m} f_i)(x) \subseteq \sum_{i=1}^{m} \partial_{\circ} f_i(x)$, $\partial_{\diamond}(\max_i f_i)(x) \subseteq \operatorname{conv}(\bigcup_{i \in I} \partial_{\diamond} f_i(x))$, and $\partial_{\circ}(\max_i f_i)(x) \subseteq \operatorname{conv}(\bigcup_{i \in I} \partial_{\circ} f_i(x))$, where $I = \{i : f_i(x) = f(x)\}$ Equalities hold throughout when f_1, \ldots, f_m are regular at x.
- Nonsmooth directional derivatives of max-function. f_1, \ldots, f_m locally Lipschitz at x and $I = \{i : f_i(x) = f(x)\} \implies \forall d \in \mathbb{E}, (f^{\diamond}(x; d) \le \max_{i \in I} \{f_i^{\diamond}(x; d)\}) \land (f^{\circ}(x; d) \le \max_{i \in I} \{f_i^{\diamond}(x; d)\})$
- Nonsmooth optimality conditions. Suppose f, g_1, \ldots, g_m locally Lipschitz at x, and S nonempty
 - $\ x \ \mathrm{minimizes} \ f \ \Longrightarrow \ 0 \in \partial_\diamond f(x) \subseteq \partial_\circ f(x)$
 - $-x \text{ minimizes } f \text{ over } S \implies 0 \in \partial_{\circ}f(x) + N_{S}(x) \implies \forall d \in T_{S}(x), f^{\circ}(x;d) \geq 0$
 - $\begin{array}{l} -x \ \mathrm{minimizes} \ f \ \mathrm{over} \ \{y: g_i(y) \leq 0, i=1,\ldots,m\} \\ \Longrightarrow \ \exists \lambda \geq 0, (\sum_{i=0}^m \lambda_i > 0) \land (\lambda_0 \partial_\circ f(x) + \sum_{i=1}^m \lambda_i \partial_\circ g(x) = 0) \land (\lambda_i g_i(x) = 0, i=1,\ldots,m). \\ \mathrm{We} \ \mathrm{can} \ \mathrm{take} \ \lambda_0 = 1 \ \mathrm{when} \ \exists d \in \mathbb{E}, (g_i(x) < 0) \lor (g_i^\circ(x;d) < 0) \end{array}$

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7 Bibliography

- 1. The main source of the content is from the course textbook on Convex Analysis [3] and the classic book by Rockafellar [6].
- 2. Another good source for information are the two books on Convex Analysis and Optimization: [2] and [5]; and the books on variational inequalities [1, 4].

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