## Chapter 33

## Matrix Perturbation Theory

Let $A$ and $B$ be $n \times n$ Hermitian matrices. Our aim is to derive information about the eigenvalues of matrices of the form $A+t B$, for real $t$. The set of matrices

$$
\{A+t B: t \in \mathbb{R}\}
$$

is called a matrix pencil. If $\operatorname{rk}(B)=k$, we say that $A+B$ is a rank- $k$ update of $X$.
We are interested in matrix pencils where $A$ and $B$ are $n \times n$ Hermitian and $t$ is real, we call these Hermitian pencils. It is known [?] that, for a Hermitian pencil, there is an integer $m$ and analytic functions $\theta_{1}(t), \ldots, \theta_{m}(t)$ such that $\theta_{i}(t)$ is an eigenvalue of $A+t B$ (for each $i$ ). There are corresponding orthogonal projections $F_{1}(t), \ldots, F_{m}(t)$; these are analytic functions of $t$ and $F_{r}(t)$ is the projection onto the $\theta_{r}(t)$-eigenspace of $A+t B$.

### 33.1 Basics

The eigenvalues of a matrix $A$ are continuous functions of the entries of $A$. If the entries of $A=A(t)$ are analytic functions of $t$, of are the eigenvalues $A$

For any matrices $A$ and $B$, there is an open neighbourhood of zero such that

$$
\operatorname{rk}(A+t B) \geq \operatorname{rk}(A) .
$$

The key is that if $A$ is invertible, then $I+t A^{-1} B$ is invertible for small $t$, and so

$$
A+t B=A\left(I+t A^{-1} B\right)
$$

is invertible.

### 33.2 Rank-1 Updates

Let $A$ be a Hermitian matrix with spectral decomposition $A=\sum_{r} \theta_{r} E_{r}$. The eigenvalue support of a vector $x$ is the set

$$
\left\{r: E_{r} x \neq 0\right\} .
$$

Note that, since $E_{r}$ is a projection, $E_{r} x=0$ if and only if $x^{*} E_{r} x=0$.
33.2.1 Theorem. Let $A$ be a Hermitian matrix and let $x$ be a vector in $\mathbb{C}^{n}$. Then
(a) The eigenvalues of $A+t x x^{T}$ interlace the eigenvalues of $A$.
(b) The function $\theta_{r}(t)$ is constant if and only if $\theta_{r}(0)$ is not in the eigenvalue support of $x$.

### 33.3 Commutants

Let $A$ be Hermitian with spectral decomposition $A=\sum_{r} \theta_{r} E_{r}$. Define a map $\Psi_{A}$ on Mat ${ }_{n \times n}(\mathbb{C})$ by

$$
\Psi(M):=\sum_{r} E_{r} M E_{r}
$$

33.3.1 Theorem. If $A$ is Hermitian, $\Psi$ is orthogonal projection on the commutant of $A$.

Proof. As $E_{r} M E_{r}$ commutes with $A$, it is immediate that the image of $\Psi$ lies in the commutant of $A$. If $M$ commutes with $A$, it commutes with each idempotent $E_{r}$ and accordingly

$$
M=I M I=\sum_{r, s} E_{r} M E_{s}
$$

If $r \neq s$, then $E_{r} M E_{s}=M E_{r} E_{s}=0$, and therefore the commutant of $A$ is the imnage of $\Psi$.

It is also clear that $\Psi^{2}=\Psi$, so $\Psi$ is idempotent. Now if $M, N \in \operatorname{Mat}_{n \times n}(\mathbb{C})$, then

$$
\begin{aligned}
\langle N, \Psi(M)\rangle=\operatorname{tr} N^{T} \Psi(M) & =\sum_{r} \operatorname{tr}\left(N^{T} E_{r} M E_{r}\right) \\
& =\sum_{r} \operatorname{tr}\left(E_{r} N^{T} E_{r} M\right) \\
& =\langle\Psi(N), M\rangle
\end{aligned}
$$

and so $\Psi$ is self-adjoint.
If $A$ is diagonal, then its Schur idempotents are diagonal 01-matrices. If the $i$-th eigenvalue of $A$ is $\theta_{i}$ and has mutiplicity $m_{i}$ (for $i=1, \ldots, k$ ), then the commutant of $A$ consists of the block-diagonal matrices with $k$ blocks, where the $i$-th block is $m_{i} \times m_{i}$. (Hence the dimension of the commutant is $\sum_{i} m_{i}^{2}$.) The orthogonal complement to the commutant consists of the matrices Schurorthogonal to the block-diagonal matrix

$$
J_{m_{1}} \oplus \cdots \oplus J_{m_{k}}
$$

If $H$ commutes with $A$, we can express the eigenvalues of $A+t B$ in terms of the eigenvalues of $A$ and $B$. To help with determining the eigenvalues of the pencil when $A$ and $B$ do not commute, we describe a more complicated way of getting at the eigenvalues in the commutative case.

Assume $A$ has spectral decomposition

$$
A=\sum_{r} \theta_{r} E_{r}
$$

If $B$ commutes with $A$, then each eigenspace of $A$ is $B$-invariant and therefore has an orthogonal basis formed from eigenvectors of $B$. Let $E$ be a spectral idempotent of $A$ and assume its rank is $m$ and that the corresponding eigenvalue is $\theta$. There is an $n \times m$ matrix $U$ such that $U^{*} U=I_{m}$ and $U U^{*}=E$; its column space is the eigenspace associated with $E$. The matrix that represents the restriction of $B$ to $\operatorname{col}(U)$ is $U^{*} B U$ and, if its eigenvalues are

$$
v_{1}, \ldots, v_{r}
$$

with respective multiplicities

$$
\mu_{1}, \ldots, \mu_{r},
$$

the eigenvalues of the restriction of $A+t B$ to $\operatorname{col}(U)$ are

$$
\theta+t v_{1}, \cdots, \theta+t v_{r}
$$

with multiplicities as above. We will establish very similar expressions in the case where $A$ and $B$ need not commute.

### 33.4 The General Case

We assume $A$ has spectral decomposition $A=\sum_{i} \theta_{i} E_{r}$, and that $\theta_{i}$ has multiplicity $m_{i}$. Assume $E_{r}=U_{r} U_{r}^{*}$, as before. Let $B_{0}$ be the orthogonal projection of $B$ onto the commutant of $A$ and set $B_{1}=B-B_{0}$. Then

$$
B_{0}=\sum_{i} E_{i} B E_{i} .
$$

and

$$
E_{i} B_{1} E_{i}=0
$$

for all $i$. There is a constant $\epsilon>0$ such that the eigenspaces of $A+t B_{0}$ are the same for all $t$ in the open interval $(0, \epsilon)$, and hence in this interval the projections onto the eigenspaces of $A+t B_{0}$ are independent of $t$. Hence if $F$ represents projection onto one of these eigenspaces, then $F B_{1} F=0$.

We now appeal to Theorem 7.9.1 of Lancaseer "Theory of Matrices", which tells us that if $\sum_{i} E_{i} B E_{i}=0$, then the linear terms in the series expansions of the eigenvalues of $A+t B$ are zero. Equivalently, the linear terms depend only on the eigenvalues of $\sum_{i} E_{i} B E_{i}$.

## The Inertia Bound for $L\left(K_{5}\right)$

For any graph $X$ the size of a coclique is bounded (above) by the minimum of the number of non-negative eigenvalues and the number of non-positive eigenvalues of any symmetric matrix $S$ such that $S_{i, j} \neq 0$ only if $i j \in E(X)$. This is the inertia bound, which is due to Dragos Cvetkovic. Following Elzinga, we prove that the inertia bound for $L\left(K_{5}\right)$ is tight.

We take the vertex set of $K_{5}$ to be $\{0,1,2,3,4\}$. There is a partition of the vertices of $L\left(K_{5}\right)$ into three cliques. The first clique consists of the vertices that contain 0 . The remaining six vertices split into the $K_{3}$ formed by the vertices that contain 1, and a second $K_{3}$ formed by the vertices that do not contain 1 . These three cliques form a spanning subgraph of $L\left(K_{5}\right)$ with 12 edges; let $C$ denote its adjacency matrix. Let $A$ be the adjacency matrix of $L\left(K_{5}\right)$.

Now compute the eigenvalues of the matrix

$$
C+t(A-C)
$$

In sage we can do this with the magic words

```
import scipy
from scipy import linalg
lk5 = graphs.CompleteGraph(5).line_graph()
A = lk5.am()
c0 = lk5.subgraph([vx for vx in lk5.vertices() if 0 in vx])
c1 = lk5.subgraph([vx for vx in lk5.vertices() if 0 not in vx and 1 in vx])
c2 = lk5.subgraph([vx for vx in lk5.vertices() if 0 not in vx and 1 not in vx])
clqs = c0.disjoint_union(c1.disjoint_union(c2))
C = clqs.am()
def evals(t):
return vector(linalg.eigh( C +t*(A-C), eigvals_only = True))
# sage: evals(-0.9)
# (-2.8, -2.8, -1.31661554144, -1.01151297144, -0.1, -0.1, -0.1, -0.1, 4.11661554144, 4.21151297144)
```

If $C+t(A-C))$ is not invertible, $-1 / t$ is an eigenvalue of $C^{-1}(A-C)$; we calculate these by
vector(linalg.eig( $\mathrm{C}^{\wedge}(-1) *(\mathrm{~A}-\mathrm{C})$, right=False))
$(1.61803398875,-0.5+0.866025403784 * I,-0.5-0.866025403784 * I,-0.61803398875,1.0,-2.0,-2.0,1.0,1.0,1.0)$
Here the real eigenvalues determine the values where the inertia of $C+t(A-C)$ changes. They are:

$$
t=-1,-0.618,0.5,1.618
$$

Now we find the eigenvalues of $C+t(A-C))$ for $t$ in $-1.5,-1.4, \ldots, 1.9,2.0$, and we see that if $t$ is one of $-0.9,-0.8,-0.7$ then $C+t *(A-C)$ has only two non-negative eigenvalues. Therefore the inertia bound is tight for $L\left(K_{5}\right)$. [Each row of the table is the value of $t$ followed by the 10 eigenvalues.]

| -1.5 | -4.0 | -4.0 | -3.18330013267 | -1.67423461417 | 0.5 | 0.5 | 0.5 | 0.5 | 5.18330013267 | 5.67423461417 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| -1.4 | -3.8 | -3.8 | -2.82045915678 | -1.61140997322 | 0.4 | 0.4 | 0.4 | 0.4 | 5.02045915678 | 5.41140997322 |
| -1.3 | -3.6 | -3.6 | -2.45786823163 | -1.54962684489 | 0.3 | 0.3 | 0.3 | 0.3 | 4.85786823163 | 5.14962684489 |
| -1.2 | -3.4 | -3.4 | -2.09558536927 | -1.48904374382 | 0.2 | 0.2 | 0.2 | 0.2 | 4.69558536927 | 4.88904374382 |
| -1.1 | -3.2 | -3.2 | -1.73368792320 | -1.42985148151 | 0.1 | 0.1 | 0.1 | 0.1 | 4.5336879232 | 4.62985148151 |
| -1.0 | -3.0 | -3.0 | -1.37228132327 | $-1.37228132327$ | 0.0 | 0.0 | 0.0 | 0.0 | 4.37228132327 | 4.37228132327 |
| -0.9 | $-2.8$ | -2.8 | -1.31661554144 | -1.01151297144 | -0.1 | -0.1 | -0.1 | -0.1 | 4.11661554144 | 4.21151297144 |
| -0.8 | -2.6 | -2.6 | -1.2632011236 | -0.651595203261 | -0.2 | -0.2 | -0.2 | -0.2 | 3.8632011236 | 4.05159520326 |
| -0.7 | -2.4 | -2.4 | -1.21246761636 | -0.3 | -0.3 | -0.3 | -0.3 | -0.292844953646 | 3.61246761636 | 3.89284495365 |
| -0.6 | -2.2 | -2.2 | -1.16495033058 | -0.4 | -0.4 | -0.4 | -0.4 | 0.0642440249314 | 3.36495033058 | 3.73575597507 |
| -0.5 | -2.0 | -2.0 | -1.12132034356 | -0.5 | -0.5 | -0.5 | -0.5 | 0.418861169916 | 3.12132034356 | 3.58113883008 |
| -0.4 | -1.8 | -1.8 | -1.08242276016 | -0.6 | -0.6 | -0.6 | -0.6 | 0.769586530435 | 2.88242276016 | 3.43041346957 |
| -0.3 | -1.6 | -1.6 | -1.04932420089 | -0.7 | -0.7 | -0.7 | -0.7 | 1.11372195088 | 2.64932420089 | 3.28627804912 |
| -0.2 | -1.4 | -1.4 | -1.02336879396 | -0.8 | -0.8 | -0.8 | -0.8 | 1.44559962547 | 2.42336879396 | 3.15440037453 |
| -0.1 | -0.1 | -1.2 | $-1.00623784042$ | -0.9 | -0.9 | -0.9 | -0.9 | 1.75192593016 | 2.20623784042 | 3.04807406984 |
| 0.0 | -1.0 | -1.0 | -1.0 | -1.0 | -1.0 | -1.0 | -1.0 | 2.0 | 2.0 | 3.0 |
| 0.1 | -1.1 | -1.1 | -1.1 | -1.1 | -1.00712472795 | -0.8 | -0.8 | 1.80712472795 | 2.13095842402 | 3.06904157598 |


| 0.2 | -1.2 | -1.2 | -1.2 | -1.2 | $-1.03041346957$ | -0.6 | -0.6 | 1.63041346957 | 2.12554373535 | 3.27445626465 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 0.3 | -1.3 | -1.3 | -1.3 | -1.3 | -1.07279220614 | -0.4 | -0.4 | 1.47279220614 | 2.03842268941 | 3.56157731059 |
| 0.4 | -1.4 | -1.4 | -1.4 | -1.4 | -1.13693168769 | -0.2 | -0.2 | 1.33693168769 | 1.91511421982 | 3.88488578018 |
| 0.5 | -1.5 | -1.5 | -1.5 | -1.5 | -1.22474487139 | 0 | 0 | 1.22474487139 | 1.77525512861 | 4.22474487139 |
| 0.6 | -1.6 | -1.6 | -1.6 | -1.6 | -1.33693168769 | 0.2 | 0.2 | 1.13693168769 | 1.62690801373 | 4.57309198627 |
| 0.7 | -1.7 | -1.7 | -1.7 | -1.7 | -1.47279220614 | 0.4 | 0.4 | 1.07279220614 | 1.47373234984 | 4.92626765016 |
| 0.8 | -1.8 | -1.8 | -1.8 | -1.8 | -1.63041346957 | 0.6 | 0.6 | 1.03041346957 | 1.31757723984 | 5.28242276016 |
| 0.9 | -1.9 | -1.9 | -1.9 | -1.9 | -1.80712472795 | 0.8 | 0.8 | 1.00712472795 | 1.15946434976 | 5.64053565024 |
| 1.0 | -2.0 | -2.0 | -2.0 | -2.0 | -2.0 | 1.0 | 1.0 | 1.0 | 1.0 | 6.0 |
| 1.1 | -2.20623784042 | -2.1 | -2.1 | -2.1 | -2.1 | 0.839565251632 | 1.00623784042 | 1.2 | 1.2 | 6.36043474837 |
| 1.2 | -2.42336879396 | -2.2 | -2.2 | -2.2 | -2.2 | 0.678411014052 | 1.02336879396 | 1.4 | 1.4 | 6.72158898595 |
| 1.3 | -2.64932420089 | -2.3 | -2.3 | -2.3 | -2.3 | 0.516708968124 | 1.04932420089 | 1.6 | 1.6 | 7.08329103188 |
| 1.4 | -2.88242276016 | -2.4 | -2.4 | -2.4 | -2.4 | 0.354580419753 | 1.08242276016 | 1.8 | 1.8 | 7.44541958025 |
| 1.5 | -3.12132034356 | -2.5 | -2.5 | -2.5 | -2.5 | 0.192113447068 | 1.12132034356 | 2.0 | 2.0 | 7.80788655293 |
| 1.6 | -3.36495033058 | -2.6 | -2.6 | -2.6 | -2.6 | 0.0293735125905 | 1.16495033058 | 2.2 | 2.2 | 8.17062648741 |
| 1.7 | -3.61246761636 | -2.7 | -2.7 | -2.7 | -2.7 | -0.133589736004 | 1.21246761636 | 2.4 | 2.4 | 8.533589736 |
| 1.8 | -3.8632011236 | -2.8 | -2.8 | -2.8 | -2.8 | -0.296737973824 | 1.2632011236 | 2.6 | 2.6 | 8.89673797382 |
| 1.9 | -4.11661554144 | -2.9 | -2.9 | -2.9 | -2.9 | -0.460041152089 | 1.31661554144 | 2.8 | 2.8 | 9.26004115209 |
| 2.0 | -4.37228132327 | -3.0 | -3.0 | -3.0 | -3.0 | -0.62347538298 | 1.37228132327 | 3.0 | 3.0 | 9.62347538298 |

